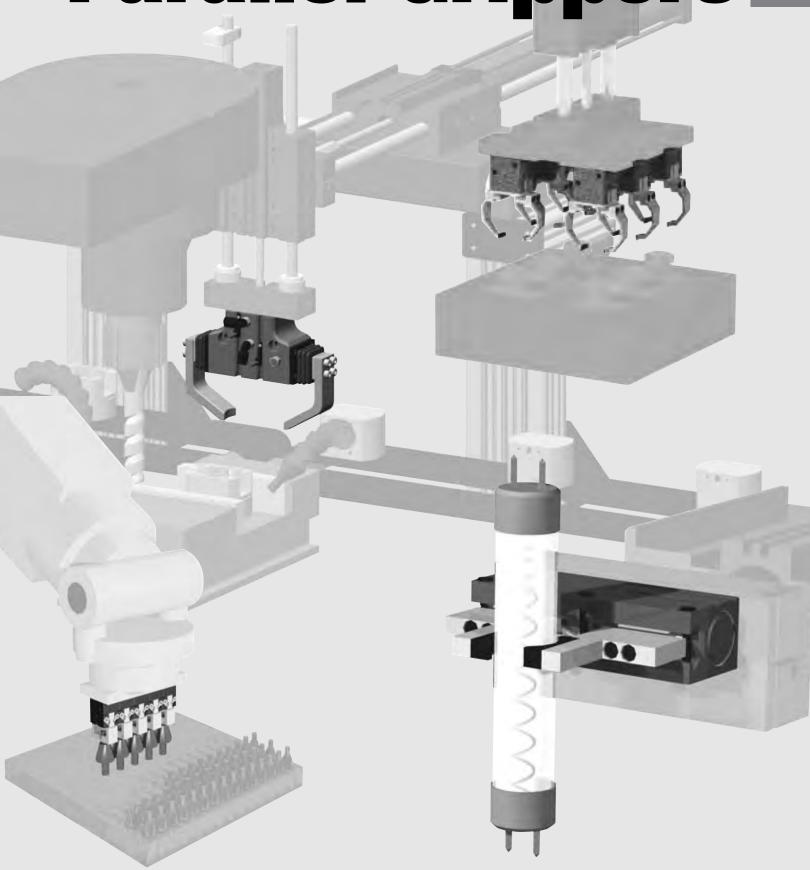
Parallel Grippers 1.1



Parallel Motion Gripper



(NEW

Preferred Market:
Global

RDH Series

Two Jaw Parallel Gripper

- Shielded design deflects chips and other particulate away from the internal components
- · Large surface area of the jaws allows for use of long fingers · All gripper sizes are available in 2 strokes sizes.

Preferred Market:

Global



See 1.20

2P Series Precision Two Jaw Parallel Gripper

- Precision operation
- Cylindrical design
- Optional springs for failsafe operation or for increased gripforces
- Side or rear airports
- Tandem piston for double grip force
- Optional Protective Boot for harsh environments
- All gripper sizes are available in 2 strokes sizes

See 1.40

Preferred Market: ■ EU ◆ SA

CP Series Compact Two Jaw Parallel Gripper

- · Rugged, compact design
- · Shielded design deflects chips and other particulate away from the internal components
- Optional springs for failsafe operation or for increased gripforces
- Side or rear airports
- Multi-sensor capable design
- All gripper sizes are available in 2 strokes sizes

See 1.58 Page 1.58

Preferred Market: ■ EU

DPP Series

DIRECTOONNECT

Precision Gripper

- Featuring our DIRECTCONNECT™ mounting pattern
- . "Dual-V" precision roller bearing design provides zero side play for excellent part position repeatability
- Optional double acting spring assist for increased force or failsafe operation
- · Low friction design allows for delicate part handling
- Synchronized and non-synchronized versions available

See 1.74

RPL/RPLC Series Low Profile/Clean Room Gripper

- Lightweight, CompactPatented Dual "V" Roller Bearing System
- · Excellent accuracy and repeatability
- · Synchronized and non-synchronized versions available
- Designed for use in Class 10 clean rooms as well as in harsh environments
- · Stainless Steel hardware and covers for durability
- Vacuum/Pressure port

Preferred Market:
Global

RPM/RPMC Series Micro/Clean Room Gripper

- Extremely small size—as small as 5/8" wide!
- Compact design allows for gripping small parts
- . Top air manifold eliminates the need for air fittings and allows grippers to be mounted in close array
- · Ultra low friction mechanism allows for consistent, repeatable gripping forces
- · Shielded with purge port

Preferred Market:

Global



See 1.106

DPG Series DIRECTEONNECT **Modular Gripper**

- Multiple DIRECTCONNECT™ mounting locations
- Multiple air port locations
- · Spring assisted design for failsafe operation or
- · Shielded design repels contaminates
- · Synchronized and non-synchronized versions

See 1.122

Preferred Market:

Global

DPDS & DPDL DIRECTCONNECT

Modular Gripper

- Multiple DIRECTCONNECT™ mounting locations
- Multiple air port locations
- Multiple strokes per size
- Front-to-back thru-body mounting
- Extended strokes (DPDL)
- Purge/scavenge ports for harsh environments
- Optional corrosion resistant hardware, high temperature seals, and sealed jaw boot (DPDL)

See 1.134

Preferred Market:

Global

DPL Series

DIRECT CONNECT



- · For use in confined spaces, combining long strokes with the high gripping force provided by two simultaneously acting pistons.
- Offers wide range of options and accessories (safety springs, in-line jaws, magneto resistive or inductive sensors).
- · Enclosed, shielded design repels chips and other particulate

Preferred Market:
Global





NEW

See 1.222

See 1.228

See 1.230

Products Overview

RP Series Miniature Double Wedge Gripper

- Compact size, high gripping force, and extended jaw design facilitates finger attachment for smaller parts.
 High grip force to weight ratio make these grippers very
- popular on small robots.
- . Miniature size allows banks of grippers to be mounted in close proximity for multiple part picking and placing.
- Internally sealed for use in hostile environments



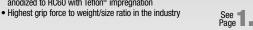
Preferred Market:

Global

RP Series Double Wedge Gripper

- Patented "Double Wedge Design" for extreme high
- · Internally sealed for use in hostile environments
- · Superior accuracy and repeatability
- · Made from 7075-T6 aircraft quality aluminum hardcoat anodized to RC60 with Teflon® impregnation

See 1.176



Preferred Market: Global

GC Series Precision Parallel Gripper

- Precision operation
- Spring assistGrippers are fitted with 2 sensor holders (sensor available separately)
- Side or rear airports
- Optional 3rd sensor for part sensing, Viton® seals for high temperature applications, and encoder available

Preferred Market:

Global



DPW Series

DIRECTOONNECT

Wide Body Gripper

· Excellent jaw support through the full body of

· Each gripper is offered in 2 different strokes

• Highly configurable gripper featuring multiple options

· Synchronized and non-synchronized versions available

• Features our DIRECTCONNECT

mounting pattern

and accessories

Preferred Market:

Global

the gripper

See 1.186

3P Series Precision Three Jaw Parallel Gripper

RPR Gladiator

Heavy Duty Parallel

Rigid design and full body support of

jaws allows for longer finger lengths

• High temperature design available

Industrial Grippers · For large and wide parts in machining

· Extremely high grip forces and moment loads

Preferred Market: ▲ NA ◆ SA

B-Series

and foundry applications

· Heavy duty, rugged designs

Preferred Market: ▲ NA ◆ SA

RTH Series

Gripper

of long fingers

Preferred Market:
Global

Three Jaw Centering

• Shielded design (DTH) deflects chips and other

particulate away from the internal components Large surface area of the jaws allows for use

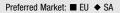
Gripper Gripper

• Wide body, long stroke design Designed for maching and foundry applications

- Precision operation
- Cylindrical design
- · Optional springs for failsafe operation or for increased gripforces
- · Side or rear airports
- Tandem piston for double grip force
- · Optional Protective Boot for harsh environments
- · All gripper sizes are available in 2 strokes sizes

See 1.252

NEW



RPW Series Large Format Wide

- **Body Gripper** · Excellent jaw support through the
- full body of the gripper High gripping forces utilizing two opposing pistons
- · Synchronized and non-synchronized versions available
- · Superior accuracy and repeatability
- · Sealed design for harsh environments



See 1.214

See 1.196

PPC Series Through Hole Gripper

- Unique through hole design
- 3 jaw concentric parallel gripper
 Shielded design protects internal components
- for increased life in harsh environments Optional safety springs, extended strokes, sensors, and high temperature seals

Preferred Market:
Global



See 1.268





5 0.00 in [6.3 1.2.7mm] 0 0.75 in, [12.7 + 19.1mm] 0 0.75 in, [19.1 - 25.4mm] 0 1.25 in, [25.4 - 31.8mm] 0 1.15 in, [25.4 - 31.8mm] 0 1.15 in, [28.1 + 45.5mm] 0 1.25 in, [28.1 + 45.5mm] 0 2.25 in, [28.1 + 45.5mm] 0 2.25 in, [68.5 - 69.8mm] 5 2.50 in, [64.5 - 69.8mm] 0 - 2.75 in, [68.5 - 69.8mm] 0 + 76.2mm+] 1 - 10 lbs. [0.45 - 45N] 10 - 25 lbs. [45 - 111N] 25 - 50 lbs. [111 - 223N] 5 50 - 100 lbs. [223 - 445N] 100 - 500 lbs. [445 - 2225N] 500 - 3000 lbs. [2225 - 1335 Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist 5 - 100 psi [0.3 - 7 bar] 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3 - 7 bar] 50 - 100 psi [3.5 - 7 bar] - 305mm] 1152 - 203mm) 1. [203 - 254mm] 1. [204 - 305mm] 1. [205 - 356mm] 2. [305 - 356mm] 3. [406 - 457mm] 9. [406 - 457mm] 9. [457 - 508mm] Inductive Sensors Magneto Resistive Sensors Clean Room Environment Normal Environment 24VDC Electric Actuation Harsh/Dirty Environment 0.05 - 0.1 sec. 0.1 - 0.5 sec. 0.5 - 0.75 sec. 10 - 12 in. [12 - 14 in. [14 - 16 in. [16 - 18 in.] 18 - 20 in. | 20 in. + [50 Two Jaws Three Jaws 1.25 -1.50 -1.75 -2.00 -2.25 -2.25 -2.75 -3.00+ Maximum Finger Length @ 60 PSI [4 bar] Actuation Time Stroke Range DPE ELECTRIC GRIPPER DPE-200-25 • • • RPE ELECTRIC GRIPPE RPE-101 RDH/DDH RDH-1 RDH-1-L RDH-2 RDH-2-L RDH-3 RDH-3-L RDH-4 RDH-4-L RDH-5 RDH-5-L RDH-6 RDH-6-L = RDH-7 + RDH-7-L RDH-8 ÷ 1.3 sec RDH-8-L + 2P PRECIS 6002P 6002P-C 8002P 8002P-C 11002P 11002P-C 14002P 14002P-C 16502P 16502P-C 16502PGR CP SQU CP-1 CP-1-C CP-2 CP-2-C CP-3 CP-3-C CP-4 CP-4-C CP-5-C CP-6 CP-6-C DPP-10M-06 DPP-10M-12 DPP-14M-15 DPP-14M-25 DPP-20M-25 DPP-20M-38 LOW PROFILE DESI RPL-1 RPL-2 RPL-3 RPL-4 LOW P E CLEAN RPLC-1 RPLC-2 RPLC-3 RPLC-4 MICRO D RPM-1 RPM-2 RPM-3 RPMC-1 RPMC-2 RPMC-3 Continued on next page

Destaco-Robohand Parallel Gripper Product Selector

.25 in. [0 - 6.3mm] 5 - 0.50 in. [6.3 - 1.2.7mm] 70 - 0.75 in. [12.7 - 19.1mm] 75 - 1.00 in. [19.1 - 25.4mm] 6.00 - 1.25 in. [25.4 - 31.8mm] 1.25 - 1.50 in. [31.8 - 38.1mm] 1.25 - 1.50 in. [38.1 - 44.5m] 1.75 - 2.00 in. [44.5 - 50.8r] 2.26 - 2.20 in. [57.1 - 63.25] 2.26 - 2.27 in. [63.5 - 69] 2.75 - 3.00 in. [69.8 - 7] 3.00 + [76.2mm+] Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist Non-Synchronous Option 1-10 lbs. [0.45 - 45N] 10-25 lbs. [45 - 111N] 25-50 lbs. [111 - 223N] 50-100 lbs. [223 - 445N] 100-500 lbs. [445 - 2225f 500-3000 lbs. [2225 - 133 [0.3 - 7 bar] si [1.5 - 7 bar] si [3 - 7 bar] si [3.5 - 7 bar] si [5 - 7 bar] 3 in, 152-203mm] 10 in, [203-254mm] 10 in, [203-254mm] 1-12 in, [254-305mm] 2-14 in, [305-365mm] 4-16 in, [305-406m] 16-18 in, [405-457f] 18-20 in, [457-508] 305mm] 356mm] Inductive Sensors Magneto Resistive Sensors Room Environment Normal Environment Harsh/Dirty Environment Failsafe Operation 5 - 0.1 sec. - 0.5 sec. - 0.75 sec. psi psi psi psi 5 - 100 p 20 - 100 40 - 100 50 - 100 70 - 15 Clean R Normal 0.05 - 0.1 - 0.5 - 0.5 - 0.5 - 0.5 8 - 1 10 -112 -114 -16 -18 -20 in Maximum Finger Length @ 60 PSI [4 bar] Stroke Range DPG-10-1 DPG-10-2 DPG-10-3 DPG-10-4 DIRECTO DPDS-047 DPDS-056 DPDS-088 DPDS-125 DPDL-047 DPDL-056 DPDL-088 DPDL-125 ECT LONG STROKE DESIGN DIRECTCO DPL-2520 DPL-2535 DPL-3230 DPL-3250 DPL-4040 DPL-4070 **DOUBLE W** RP-5 RP-10 RP-11 RP-12 RP-15 RP-17 RP-18 RP-19 PRECISI DGC-25 DGC-45 DGC-65 GC-85 GC-105 DIRECTCO DPW-250M-1 DPW-250M-2 DPW-375M-1 DPW-375M-2 DPW-500M-1 DPW-500M-2 LARGE FORMAT WIDE BODY DE RPW-625-1 RPW-625-2 RPW-750 GLADIATOR GRIPPER RPR-57-200 BPW-2000 BRP-20 BRP-21 BRP-21-D BPG-160 RTH/DTH S RTH/DTH-1 RTH/DTH-1-L RTH/DTH-2 RTH/DTH-2-L RTH/DTH-3 RTH/DTH-3-L RTH/DTH-4 RTH/DTH-4-L RTH/DTH-5 RTH/DTH-5-L RTH/DTH-6 RTH/DTH-6-L Ξ RTH/DTH-7 RTH/DTH-7-L RTH/DTH-8 RTH/DTH-8-L Continued on next page

Destaco-Robohand Parallel Gripper Product Selector

Destaco-Robohand Parallel Gripper Product Selector 1 - 10 lbs. [0.45 - 45N] 10 - 25 lbs. [45 - 111M] 25 - 50 lbs. [111 - 223N] 50 - 100 lbs. [223 - 445N] 100 - 500 lbs. [445 - 2225N] 500 - 3000 lbs. [2225 - 13350N] (6.3 - 12.7mm) (12.7 - 19.1mm) (112.7 - 19.1mm) (119.1 - 25.4mm) (25.4 - 31.8mm) (31.8 - 38.1mm) (38.1 - 44.5mm) (44.5 - 50.8mm) (53.6 - 67.1mm) (53.5 - 69.8mm) (63.5 - 69.8mm) (69.8 - 76.2mm) Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist Non-Synchronous Option 5 - 100 psi [0.3 - 7 bar] 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3 - 7 bar] 50 - 100 psi [3.5 - 7 bar] 70 - 150 psi [5 - 7 bar] Clean Room Environment Normal Environment Harsh/Dirty Environment Magneto Resistive Sensors 0 - 0.25 in. [0 - 6.3mm] 0.25 - 0.50 in. [6.3 - 12.7 0.50 - 0.75 in. [12.7 - 19. 0.75 - 1.00 in. [19.1 - 25. [0 - 50.8mm] [50.8 - 102mm] [102 - 152mm] [152 - 203mm] 0.75 - 1.00 in, [17] 1.00 - 1.25 in, [25] 1.00 - 1.25 in, [31] 1.50 - 1.75 in, [38] 1.75 - 2.00 in, [44], 2.05 - 2.25 in, [50.4] 2.50 - 2.25 in, [67], 2.50 - 2.75 in, [68], 2.75 - 3.00 in, [69.8] 3.00+ [76.2mm+] 16 - 18 in. [406 - 48 18 - 20 in. [457 - 50 20 in.+ [508mm+] Failsafe Operation Inductive Sensors 0.05 - 0.1 sec. 0.1 - 0.5 sec. 0.5 - 0.75 sec. Two Jaws Three Jaws Maximum Finger Length @ 60 PSI [4 bar] Stroke Range 3P PRECISION DESIGN 6003P 6003P-C 8003P 8003P-C 11003P 11003P-C 14003P 14003P-C 16503P 16503P-C PPC THROUGH HOLE DESIGN PPC-12 . . . PPC-12-C PPC-25 PPC-25-C PPC-34 PPC-34-C

DPE Parallel Gripper-Electric Gripper Series

Electrically Actuated

24 VDC, 4-wire input: power, ground, open & closed signals. 100% duty cycle for high throughput.

• "Light Switch" Simplicity

Plug and play. No programming, tuning or adjusting required. As easy as a pneumatic gripper to control and operate.

Energy Efficient

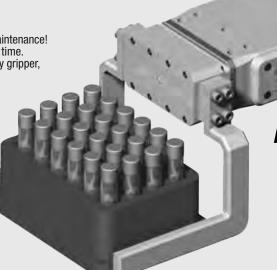
Only 3W required. Can be driven directly by most PLC's without a separate power supply. Can be battery driven for remote applications.

• High Cycle Life

20+ million cycles with zero maintenance! High reliability eliminates down time. Lowest cost of ownership of any gripper, pneumatic or electric.

• Built-in Electronics

All electronics are sealed within the gripper. No external control board needed. 4-pin/wire control cable sold separately.





• Long Stroke, Fast Actuation

25mm stroke for picking multiple sized parts. Full actuation in 0.25 second. Pick up to 150 parts per minute (with reduced stroke).

• Failsafe operation

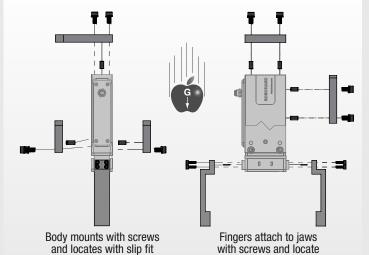
In case of a power loss, the jaws will not separate but grip force will be diminished. Finger design should include features other than just friction to retain part for critical applications.

Patent Pending.

Mounting Information:

dowel pins for accuracy

Gripper can be mounted and operated in any orientation



Technical Specifications:

Product Specifications

Voltage Power Max. 40 W
Operating Temperature 5°/50° C (40°/120°F)
Protection Class IP54
Clean Room With Scavenge Port* 100
Clontact Tech Support.

Maintenance Specifications

Field Repairable Yes

Application Restrictions

- Timing, power and load beyond specifications
- Suitable for external gripping only

with dowel pins

Product Features

Multiple Position Sensing

Slot mounted magneto-resistive sensing. Sense up to 4 gripping positions. Internal magnetic targets and external sensor mounting slots come standard. Sensors & quick disconnect cables sold separately.

DirectConnect Mounting

Mounts directly to other automation products without adaptor plates. Versatile mounting on top, side front and back of body.

One-Piece Body

One-piece, lightweight aircraft quality aluminum body ensures product accuracy.

Sealed Design

IP 54 rating for tough application environments.

Hardcoat Anodize

The body and jaws are hardcoat anodized to 60Rc with Teflon impregnation.

Slip Fit Dowel Pin Holes

Located in body and jaws for precision mounting.

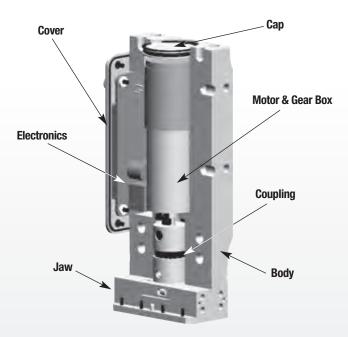
Superior Jaw Support

Ridged design and full body support of the jaws allows for long finger lengths.

Rack & Pinion Drive

Precision drive components for smooth actuation. Zero backlash while gripping ensures excellent repeatability and accuracy.

Operating Principle



- Apply +24 VDC from the PLC to the gripper "Close" wire.
- The motor rotates a planetary gear reduction box that is connected to the drive pinion by a coupling
- The pinion drives the integral jaw racks causing the jaws to close synchronously
- Power is maintained to the closed signal to continue gripping force throughout the grip cycle.
- To open, remove signal to "Close" wire and apply +24 VDC from the PLC to the gripper "Open" wire
- · Design is suitable for internal or external gripping

Patent Pending

Style-DPE

Size -200-25



Stroke: Grip Force: Weight:

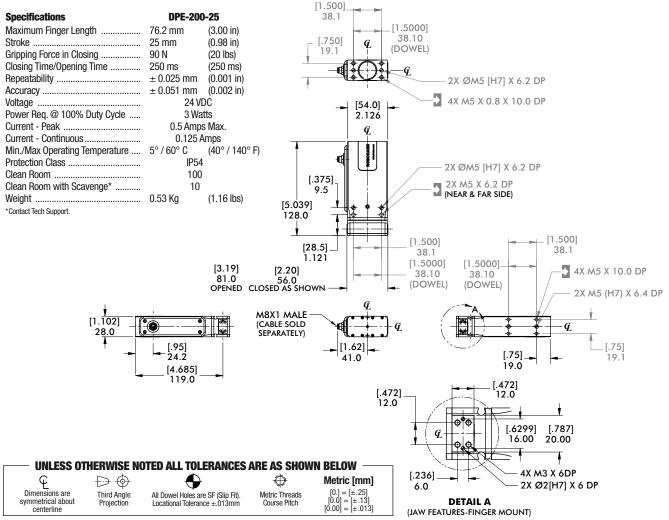
25 mm 0.98 in 90 N 20 lbs 0.53 Kg 1.16 lbs



DIRECTCONNECT

PARALLEL GRIPPER DPE-200-25 E-GRIPPER SERIES





Loading Information How to Order: (Order Accessories separately from Basic Model) WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE FORCE VS LENGTH N lbs. 44 10 **BASIC MODEL** FINGER LENGTHS **5** 35 **DPE-200-25** FINGER FORCE -16 18 **ACCESSORIES*** 9 2 4-wire Power and Signal Cable, 5m long CABL-046 NPN Magneto Resistive Sensor (with Qk. Disc.)*† **OHSN-017** 1 or 2 PNP Magneto Resistive Sensor (with Qk. Disc.)*† **OHSP-017** 1 or 2 CABL-013 51 64 Quick Disconnect 5 Meter Cable Length*† 1 or 2 EFFECTIVE FINGER LENGTH - L *Sensor and cables sold separately. †Power cable plus 1 or 2 sensor cables. SENSOR MAGNET SUPPLIED INSIDE WITH THE JAWS INSTALL SENSOR HEAD INTO THE SLOT, ADJUST IT'S LOCATION, AND LOCK ITS POSITION WITH THE PROVIDED LOCK SCREW. My Loading Capacity[†] Static Maximum Tensile T 75 lbs [10 N] Maximum Compressive C 75 lbs [10 N] Maximum Moment Mx 120 lbf-in [14 Nm] Maximum Moment My 150 lbf-in [17 Nm] **CUSTOMER SUPPLED FINGER** Maximum Moment Mz 120 lbf-in [14 Nm] †Capacities are per set of jaws and are not simultaneous



PARALLEL GRIPPER DPE-200-25 **E-GRIPPER SERIES**

Installation and Operation:

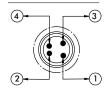
- 1. Mount fingers (customer supplied) to gripper jaws using dowel pins and threaded fasteners. See dimensional drawing for hole sizes. Use Loctite® 242 threadlocker or equivalent.
- 2. Mount gripper using dowel pins and threaded fasteners. Gripper can be mounted and operated in any orientation. See dimensional drawing for mounting hole pattern and sizes. Use Loctite® 242 threadlocker or equivalent.
- 3. To operate the DPE gripper, follow the instructions below:

 Apply +24VDC to pin 1 (brown) and Ground to pin 3 (blue) to turn on the gripper. To open the fingers, apply +24VDC to pin 2 (white). To close the fingers, remove +24VDC from pin 2, and apply +24VDC to pin 4 (black). +24VDC signal must remain present on the open / close line to maintain the force output. The gripper will do nothing if a +24VDC signal is present on the open and close lines at the same time.

WARNING:

- Operating gripper outside of power voltages and can cause damage and void warranty
- Disconnect power from gripper before performing maintenance or making adjustments.

ELECTRICAL INTERFACE



PIN OUT (LOOKING INTO HEADER CONNECTOR ON GRIPPER)

(+ 24 VDC)

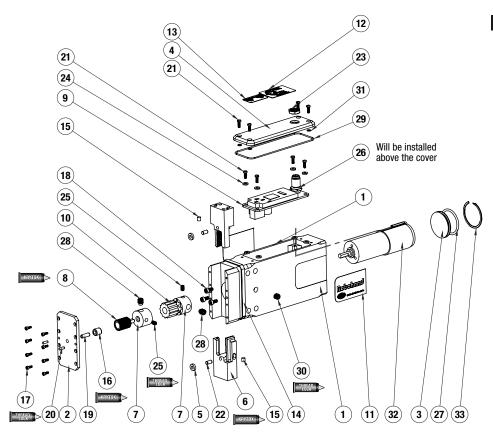
2 WHITE 3 BLUE (OPEN GRIPPER) +24 VDC = ACTIVE (GROUND) (CLOSE GRIPPER) +24 VDC = ACTIVE 4 BLACK

CABLE # CABL-046

DPE Series Exploded View







Assembly Procedure

- 1) Clean all make details free of dirt, oil and other contaminants.
- 2) Insert # 32 motor into the # 1 body, line up the motor holes and assemble motor to the body by using # 18 screws. Make sure that the motor wires are carefully routed to the top for it's connection to the motor control board.
- 3) Assemble # 25 set screws one of the # 7 coupling hubs, but not all the way in. Assemble the coupling to the motor shaft, with flat on the motor shaft facing one of the set screws and adjust the inside face of the coupling, flat with end face of the motor shaft. Tighten the set screw on the motor shaft thru the acccess hole at set screw # 30 location.
- 4) Assemble the # 10 coupling insert into the # 7 hub, as asssembled to the motor shaft, as above.
- 5) Assemble # 8 drive pinion with it's shaft all the way into the second # 7 coupling hub and tighten the set screws. Assemble # 16 bearing and # 19 dowel pin into the drive pinion. Now install this assembly hub / insert assembly installed earlier to the motor shaft.
- 7) Assemble # 15 magnets into # 6 jaws, using lok-tite as recommended.
- 8) Lubricate the pinion, the bearing, the jaws and inside surfaces of jaw-ways with lubricant as recommended.
- 9) Install the jaws into the body, meshed with the pinion and symmetrically positioned w.r.t the pinion.

- 10) Install # 5 stop and # 22 dowel pins into the jaws.
- 11) Assemble # 2 cover to the body, with dowel pins # 19 and # 29 aligned to the corrosponding holes in the cover. Install fasteners # 17 to secure the cover to the body.
- 12) Install / connect the motor cable connector the motor control board. Use # 21 & # 24 fasteners and install the motor control board to the body. Note: Remove the hex nut supplied with the connector on the motor control board. This hex nut will be re-installed after # 4 cover is installed.
- 13) Install # 4 cover to the body with # 29 gasket and # 21 screws as shown.
- 14) Installed the previously removed hex nut back to the connector. Caution: Only snug tighten this hex nut.
- 15) Install # 3 cap with 0 ring and snap ring, as shown.
- 16) Install tags and labels as shown.

Item	Qty	Name	
01	1	Body	
02	1	Bottom Plate	
03		Cap	
04		Cover	
05	2	Bumper	
06	2	Jaw	
07	2	Coupling Pin	
08	1	Drive Pin	
09	.	Motor Control Board	
10	1	Coupling Insert	
11	2	Tag-Destaco-Robohand	
12	1	Tag-Electric Pin Out	
13	1	Tag-Production	
14	.	Tag-VBL Collar	
15	2	Magnet	
16	1	Bearing	
17	8	SHCS, M1.6*5mm, Alloy	
18	3	SHCS, M2.5*5mm, Alloy	
19	1	Dowel Pin: 1/8 Dia X 3/8	
20	2	Dowel Pin: 2mm	
20	_	dia*6mm lg	
21	8	Screw, Fillister HD,	
	Ū	M2x6mm	
22	2	Dowel Pin: 3mm	
	-	dia*6mm lg.	
23	0	Jam Nut-Ref Only (Part Of	
20	Ü	Motor Control Board)	
24	8	Washer	
25	2	Set Screw	
26	0	0-Ring - Ref Only (Comes	
		With Connector)	
27	1	0-Ring	
28	2	Set Screw	
29	1	0-Ring	
30	1	Set Screw	
31	4	0-Ring, Buna, 70d,	
0.	•	0.026 CS, .097id	
32	1	Gear Motor	
33	1	Ret. Ring	
	-		

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.



RECTONNE







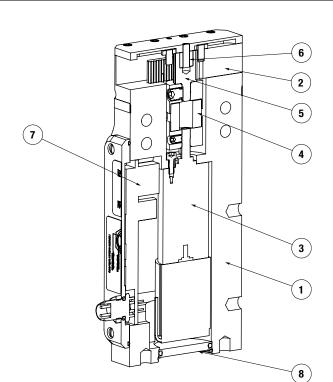








DPE Series Assembled View



Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Motor/Gear ASM
04	1	Coupling Asm
05	1	Pinion
06	1	Bearing
07	1	Motor Control Board
84	1	End Cap

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.















RPE Parallel Gripper-Electric Gripper Series

• Failsafe Operation:

Spring closed feature allows for full grip force during power off conditions.

• Electrically Actuated:

Requires simple 24VDC pulsed signal. No programmable or expensive controller required.

• Sensing:

Adjustable inductive proximity sensors available.

• Low System Impact:

Easily integrated into current engineering and manufacturing processes.

• Miniature size:

Compact design allows for gripping small parts in small spaces.

Patent Pending. The RPE is CE marked.



Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.

• Delicate part handling:

Low friction mechanism allows for repeatable gripping forces for holding delicate parts. Grip force is constant throughout stroke.

• Clean room suitable:

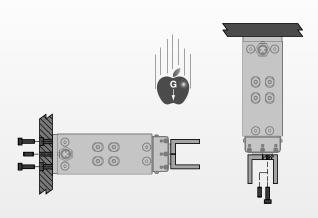
A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with Krytox™ grease.

Harsh environments:

All moving components are located within the corrosion resistant cover.

Mounting Information:

Gripper can be mounted and operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy Fingers attach to jaws with screws and locate with dowel pins

Technical Specifications:

Product Specifications

Voltage 24 VDC
Power Max. 40 W
Operating Temperature 5° / 50° C (40° / 120°F)
Protection Class IP54
Clean Room 100
Clean Room with Scavenge Port* 10

*Contact Tech Support.

Maintenance Specifications

Field Repairable Yes

Application Restrictions

- Timing, power and load beyond specifications
- Suitable for external gripping only

Product Features

Quality Components

Body made from aluminum alloy with Teflon™ impregnated hardcoat anodize. Jaws, housing, and end cap nickel plated for use in medical parts handling applications.

Spring Close

Spring closed feature for failsafe operation

Energy Efficient

Power is only required for 50 msec to open and close the gripper, no power is required to keep the part gripped or

Adjustable Preloaded **Bearings** Adjustable preload

screw allows for adjustment of preload on roller bearings. Bearings are preloaded for maximum support and zero side play.

Sensor Option

Reads position of jaw (sold separatelysee "How to order" Section for more info)

> **Hardened Plated Jaws** For wear resistance and longer life

Roller Bearings

Patented Dual-"V" roller bearings provide low friction rolling motion and maximum rigidity for fingers

to keep the gripper fully opened.

Stainless Steel Cover

Stationary and non-contacting

cover eliminates the possibility

of particle generation **Clean Room**

Krytox™ clean-room grade lubricant standard.

FDA approved lubricants available. Vacuum

scavenge ports are available

Slip Fit

Dowel

Pin Holes

Located in body

and jaws

Style-RPE

Size -100M

Stroke: Grip Force: Weight:

4 mm (0.16 in) 5 N (1.1 lbs) 226 g (0.50 lbs)

See **1.16**

Style-RPE

Size -101M

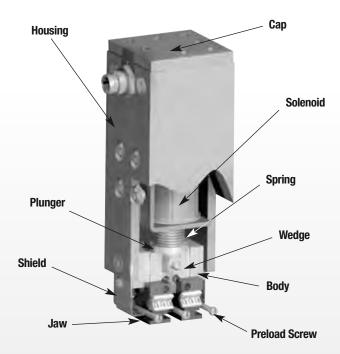


Style: Stroke: Grip Force: Weight:

RPE-101M 4 mm (0.16 in) 5 N (1.1 lbs) 226 g (0.50 lbs)

See 1.16

Operating Principle

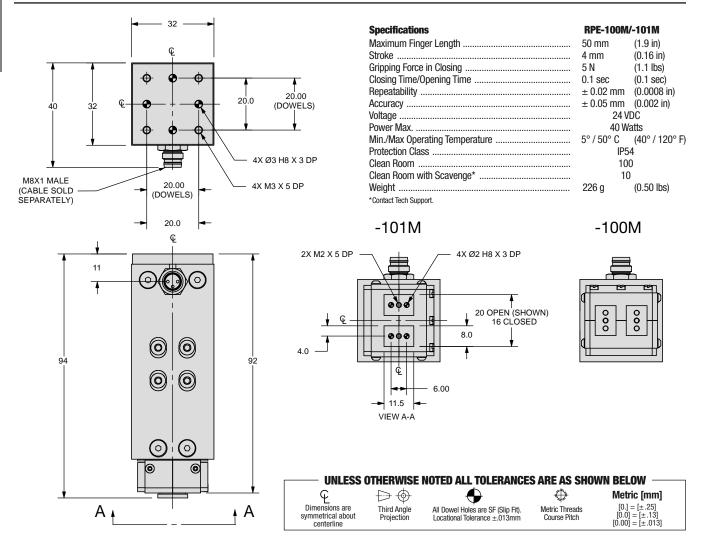


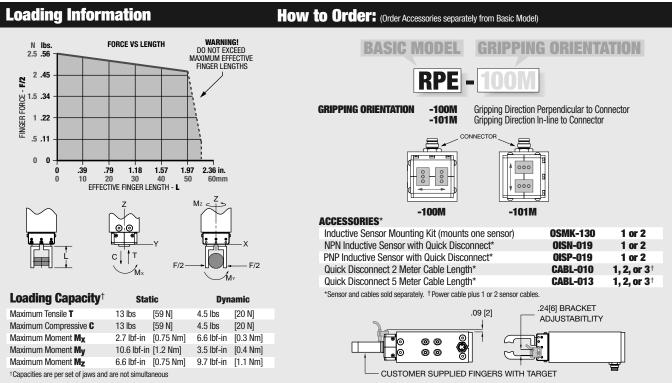
- A short power pulse releases the latching solenoid's plunger, allowing the spring to drive the wedge mechanism.
- The spring driven wedge drives the jaws towards one another to grip the part. No power is required to maintain grip force.
- To open the gripper, a short power pulse to the solenoid retracts the plunger to the latched position, which opens the jaws. No power is required to maintain the open position.
- · Suitable for external gripping only.

U.S. Patent # 5,529,359. Other Patents Pending.

PARALLEL GRIPPER RPE-100M/-101M E-GRIPPER SERIES







PARALLEL GRIPPER RPE-100M/-101M E-GRIPPER SERIES

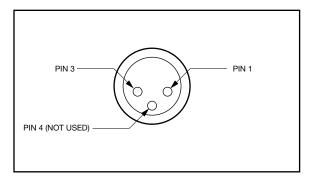
Installation and Operation:

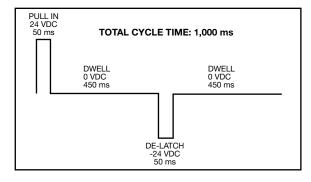
- Mount fingers (customer supplied) to gripper jaws using dowel pins and threaded fasteners. See dimensional drawing for hole sizes. Use Loctite[®] 242 threadlocker or equivalent.
- Mount gripper using dowel pins and threaded fasteners. Gripper can be mounted and operated in any orientation. See dimensional drawing for mounting hole pattern and sizes. Use Loctite® 242 threadlocker or equivalent.
- 3. The following instructions apply to standard operation and require a 24VDC power supply:

 To open gripper, connect positive lead of power supply to Pin 1 of the connector and negative lead to Pin 3 of the connector. See below for pin orientation. Pulse for 50msec maximum as shown in Timing Diagram. After 50 msec pulse, allow 450msec minimum dwell time. To close gripper, connect positive lead of power supply to Pin 3 of connector and negative lead to Pin 1 of connector. Pulse for 50msec maximum as shown in Timing Diagram. After 50msec pulse, allow 450msec minimum dwell time.

WARNING:

- Operating gripper outside of power voltages and pulse times will cause damage and void warranty
- Do not insert any foreign objects (tools, body parts, etc) between gripper fingers when power is applied.
- Disconnect power from gripper before performing maintenance or making adjustments.
- Do not apply power to gripper for more than 100msec maximum. Observe 10% duty cycle at all times.

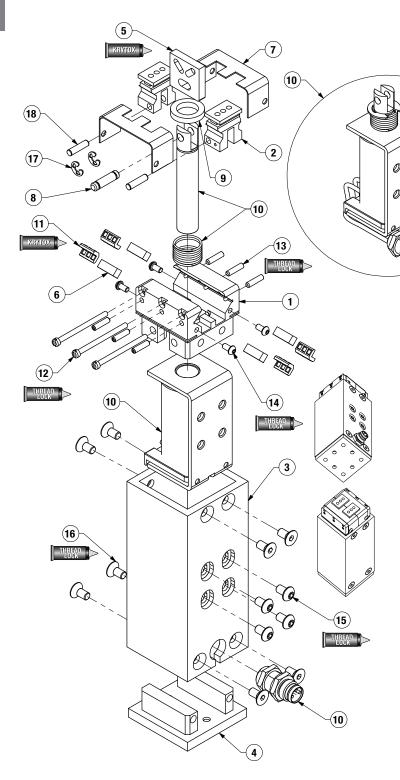




PIN ORIENTATION

TIMING DIAGRAM

NOTE: The RPE is CE marked.



Item	Qty	Name
04		Dado
01	1	Body
02	2	Jaw
03	1	Housing
04	1	Cap
05	1	Wedge
06	4	Way
07	2	Shield
80	1	Clevis Pin
09	1	Spacer
10	1	Solenoid
11	4	Kit, Roller Bearing
		and Cage
12	3	Preload Screw
13	6	Set Screw-Way Locating
14	4	BHCS-Shield
		Mounting Screw
15	4	BHCS Solenoid
		Mounting Screw
16	8	FHCS-Housing
		Mounting Screw
17	2	Retaining Ring
18	2	Dowel Pin

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate #1 body, #5 wedge, and #11 bearings using Krytox™ grease.
- 2) Insert #2 jaws and #5 wedge into body. 3) Insert #6 way and #11 bearings into each end of the body.
- 4) Adjust preload by adjusting #12 preload screws. (See below for procedure)
- 5) Install #10 solenoid plunger with #8 clevis pin and #17 retaining rings.
- 6) Fasten #10 solenoid to housing. Do not tighten yet, allowing the solenoid to freely move within slots.
- Slide #9 spacer and #10 solenoid spring onto plunger.
- 8) Fasten #1 body into #3 housing. Completely fasten the two screws that are located on the same side as the #10 solenoid 3-pin connector then fasten the two remaining screws on the opposite side.
- 9) Fully open jaws and tighten #15 screws securely.
- 10) Install #7 shields to gripper.
- 11) Fasten #10 3-pin connector.
- 12) Fasten #4 cap into housing. Completely fasten the two screws that are located on the same side as the #10 solenoid 3-pin connector then fasten the two remaining screws on the opposite side.

Preload Adjustment Procedure

- Install preload screws (12) with Loctite® 7649 primer and Loctite® 242 thread locker on threads.
- Tighten until there is no side play in the jaws.
- Cycle gripper (w/finger assembly)
- 4) Recheck for play in jaws & tighten or loosen as needed.













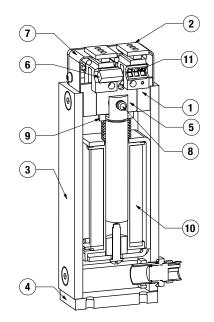




For more information call us at: 1.888.DESTACO or 248.836.6700 Fax: 248.836.6901 Visit us on the Internet at: www.destaco.com

RPE Series Assembled View

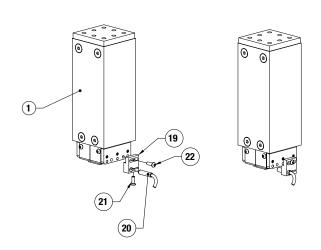




Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Housing
04	1	Cap
05	1	Wedge
06	4	Way
07	2	Shield
80	1	Clevis Pin
09	1	Spacer
10	1	Solenoid
11	4	Kit, Roller Bearing
		and Cage
		*

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

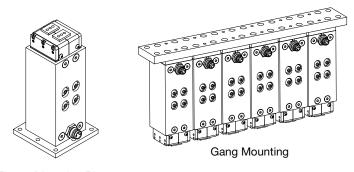


Installation*

- 1) Install sensors as shown.
- 2) Adjust for desired end of stroke detection.
- * Fingers should be designed to act as target for inductive sensor. Sensing range is 0.031 [0.8]. The center line of the sensor diameter is located 0.094 [2.4] off of jaw mounting surface.

Fingers supplied by customer.

Flange Mounting Plate, Gang Mounting and more...



Drawings shown are for concept only. Contact DE-STA-CO Tech Support with project requirements.

Flange Mounting Plate















For more information call us at: 1.888.DESTACO or 248.836.6700 Fax: 248.836.6901 Visit us on the Internet at: www.destaco.com

Parallel Grippers-2-Jaw Parallel Series

Machine applications:

The 2 symmetric jaws and excellent repeatability allow for precise handling of various parts.

Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism.

Compact, robust and powerful gripper:

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Different strokes:

All gripper sizes are available in 2 strokes sizes.

For long fingers applications:

The large surface area of the jaws, coupled with the encapsulated bottom case design allows for long fingers applications.

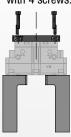
Multi-purpose gripper:

A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, magneto resistive or inductive sensors) allow these grippers to be used in a wide number of applications.

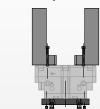
Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located using 2 dowel pins and assembled from the top with 4 screws.







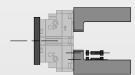
Gripper can also be assembled

from the bottom with 4 through

body screws.

Gripper is protected from debris when operated upside down.

Gripper can be operated utilizing top manifold air ports



Fingers are located on jaws with 2 dowel sleeves (provided) and assembled with 2 screws.

Technical Specifications:

Pneumatic Specifications

Pressure Operating Range

without Springs

Cylinder Type

30-100 psi

Imperial

2-7 bar **Double Acting**

Metric

or Double Acting Spring Assist or Single Acting Spring Return **Internally Lubricated Buna-N**

Dynamic Seals Valve Required to Operate:

Double Acting

Single Acting (-C or -O Option)

4-way, 2-position 3-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

Buna-N Seals (Standard) -30°~180° F -35°~80° C Viton® Seals (Optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life

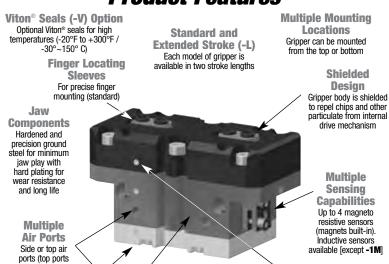
Normal Application w/ Preventative Maintenance Field Repairable

5 million cycles 10+ million cycles* Yes Yes

Seal Repair Kits Available *Addition of lubrication will greatly increase service life

See Maintenance Section

Product Features



Optional Spring Assist Optional spring assist retains the component should the air supply fail, to assist the gripper for internal (-0) or external (-0) gripping, or

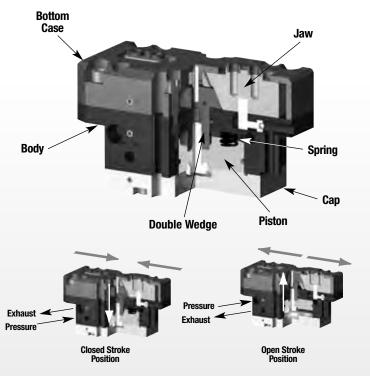
in single acting or spring assist mode

require O-ring)

Standard Purge/ Scavenge Port

Used with a vacuum for clean room environments or positive pressure for harsh environments

Operating Principle



- A double acting piston is connected to a double sided wedge.
- The double wedge slides into a slot in each of the jaws converting the vertical motion of the wedge into a horizontal motion of the jaws.
- Each jaw moves within the bottom case, the closed design increases the rigidity and permits the use of longer fingers. The large surface area of the guiding system allows for higher moments loads.
- This gripper is suitable for internal or external gripping using single or double acting mode.

Style -RDH Parallel Gripper Size RDH-1M-L RDH-1M Total Stroke: 0.16 in. 4 mm 0.31 in. 8 mm 156 lbs 693 N 102 lbs 452 N Grip Force: 0.4 lbs 0.19 Kg Weiaht: 0.4 lbs 0.19 Kg **Style -RDH Parallel Gripper** Size -2M RDH-2M RDH-2M-L Total Stroke: 0.23 in. 6 mm 0.47 in. 12 mm Grip Force: 226 lbs 1006 N 149 lbs 661 N 0.9 lbs 0.39 Kg 0.9 lbs 0.39 Kg Weight: **Style -RDH Parallel Gripper** Size -3M RDH-3M RDH-3M-L Total Stroke: 0.31 in. 8 mm 0.62 in. 16 mm **Grip Force:** 379 lbs 1683 N 246 lbs 1094 N 1.8 lbs 0.82 Kg Weiaht: 1.8 lbs 0.82 Kg **Style -RDH Parallel Gripper**

-4M Size RDH-4M RDH-4M-L Total Stroke: 0.39 in. 10 mm 0.78 in. 20 mm

帽		Grip Force: Weight:	628 lbs 3.1 lbs		408 lbs 3.1 lbs	1814 N 1.43 Kg
4					See Page	.28
	Style	-RDH Pa	aralle	l Grip	per	
	Size	-5M	RDH	-5M	RDH-	5M-L
	-Atte	Total Stroke:				
ed (Till	malle	Grip Force:	1037 lbs	4609 N	675 lbs	2999 N
411	1000	Weight:	6.1 lbs	2.75 Kg	6.1 lbs	2.75 Kg
-					See 1	.30
					. ago _	
	Style	-RDH Pa	aralle	l Grip	per	
	Size	-6M	DUN	-6M	DNU_	6M-L
		Total Stroke:				
		Grip Force:			1.25 III.	
The second	CARMIC	arip roice.	1344 105	0040 11	1203 108	3023 IV

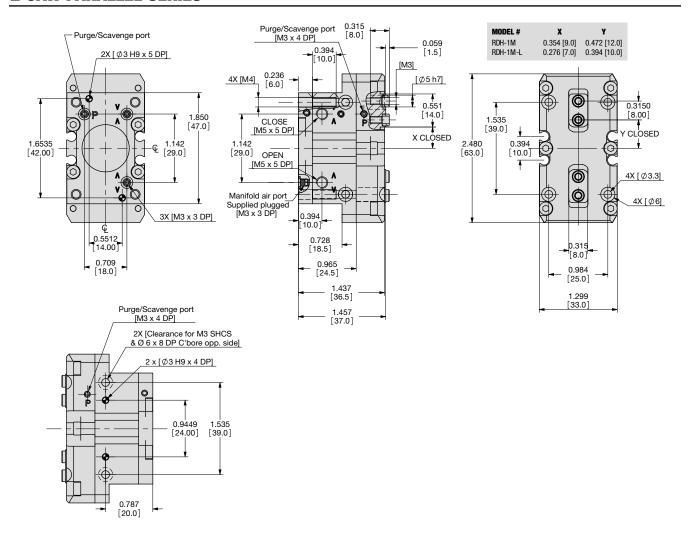
Size	-6M	RDH	-6M	RDH-	6M-L
- Allen	Total Stroke:	0.62 in.	16 mm	1.25 in.	32 mm
ALC: UNITED IN	Grip Force:	1944 lbs	8640 N	1265 lbs	5623 N
	Weight:	12.7 lbs	5.77 Kg	12.7 lbs	5.77 Kg
A STATE OF THE PARTY OF THE PAR				See Page	.32

				3-		
Style	-RDH Pa	aralle	el Grip	pe	r	
Size	-7M	RDH	I-7M	RI	DH-	7M-L
and the last	Total Stroke:	0.98 in.	25 mm	1.95	in.	50 mm
No. of Lot	Grip Force:	2822 lbs	12542 N	1830	lbs	8135 N
	Weight:	24.8 lbs	11.25 Kg	24.8	lbs	11.25 K
				See	4	2/

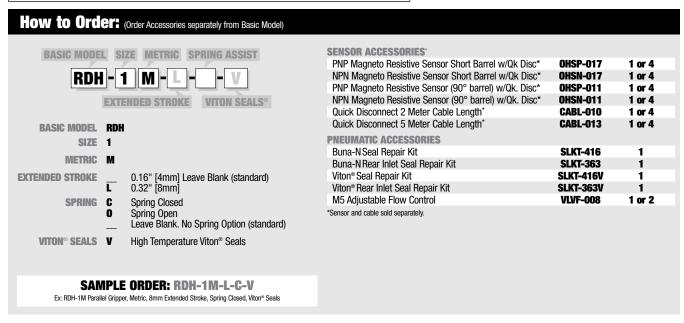
-	r				Page	1107
	Style	-RDH Pa	aralle	l Grip	per	
	Size	-8M	RDH	I-8M	RD	H-8M-L
		Total Stroke:	1.37 in.	35 mm	2.73 ir	n. 70 mm
đ	EECh.	Grip Force:	6300 lbs	28002 N	4076 lb	os 18115 N
	SHIPS.	Weight:	71.1 lbs	32.3 Kg	71.1 lb	s 32.3 Kg
Ì	N/A				See Page	1.36

PARALLEL GRIPPER RDH-1M **2-JAW PARALLEL SERIES**





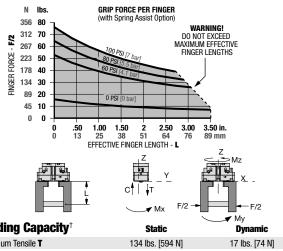
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW					
UNLESS UTHERWISE NUTED ALL TULERANCES ARE AS SHOWN BELOW					
Ç	$\rightarrow \odot$	⊕	\bigoplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$



(DESTACO)

PARALLEL GRIPPER RDH-1M 2-JAW PARALLEL SERIES

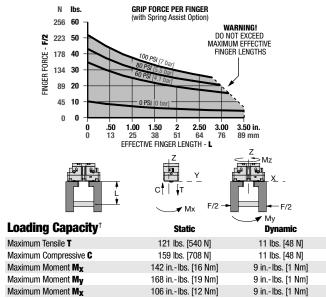
RDH-1M Loading Information



Loading Capacity ¹	Static	Dynamic
Maximum Tensile T	134 lbs. [594 N]	17 lbs. [74 N]
Maximum Compressive C	175 lbs. [779 N]	17 lbs. [74 N]
Maximum Moment M _X	159 inlbs. [18 Nm]	18 inlbs. [2 Nm]
Maximum Moment My	204 inlbs. [23 Nm]	18 inlbs. [2 Nm]
Maximum Moment M _X	124 inlbs. [14 Nm]	18 inlbs. [2 Nm]
*Connection are not act of inum and are not a	imultanaoua	

[†]Capacities are per set of jaws and are not simultaneous

RDH-1M-L Loading Information



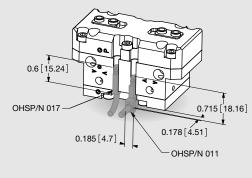
†Capacities are per set of jaws and are not simultaneous

PLUMBING FITTING

Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	125 lbs.	555 N
Without Spring Assist -L	81 lbs.	361 N
With Spring Assist	156 lbs.	693 N
With Spring Assist -L	102 lbs.	452 N
Total Stroke:		
Standard	0.16 in.	4 mm
Extended -L	0.32 in.	8 mm
Weight (RDH)	0.4/0.5 lbs.	0.19/0.21 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

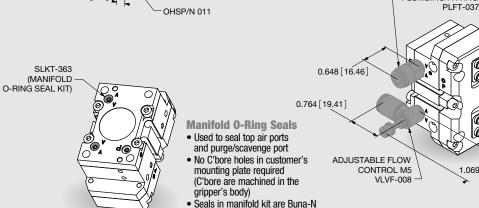
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	0.9 in ² .	5.8 cm ²
Displacement	0.31 in ³ .	5 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.06 sec.	/0.06 sec.
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



(Viton® seal kit SLKT-363V)

Plumbing Fittings

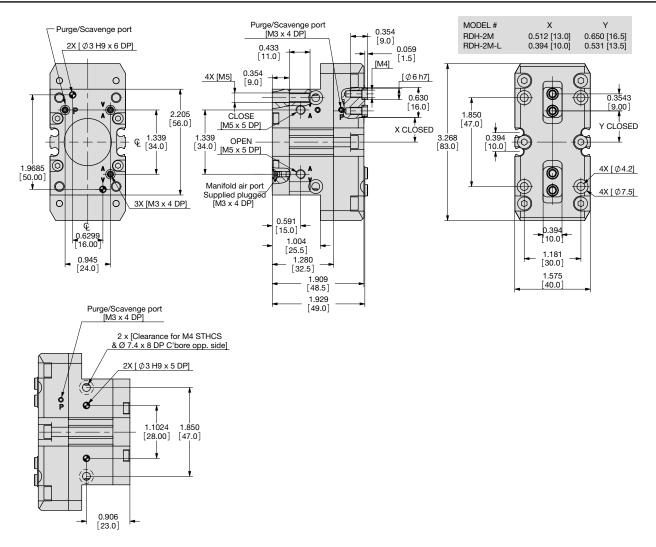
- Adjustable flow controls:
 - Have thumb screw adjust with locking nut for adjusting actuation time
 - Available for 6mm 0D tubing
- Plumbing fittings:

1.069 [27.15]

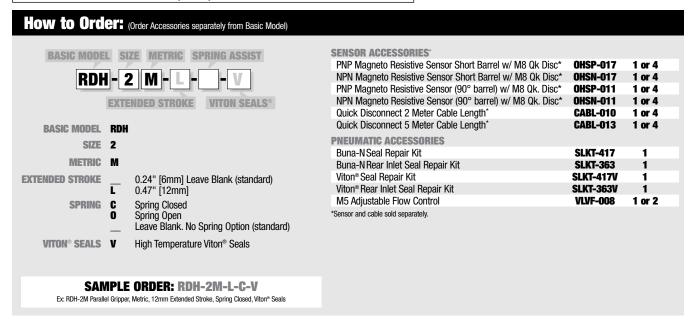
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RDH-2M 2-JAW PARALLEL SERIES



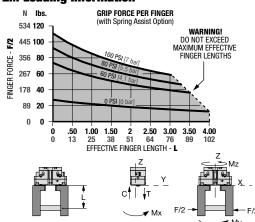


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Ç	$\rightarrow \odot$	⊕	\bigoplus	Imperial in.	Metric [mm]	
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$	



PARALLEL GRIPPER RDH-2M 2-JAW PARALLEL SERIES

RDH-2M Loading Information



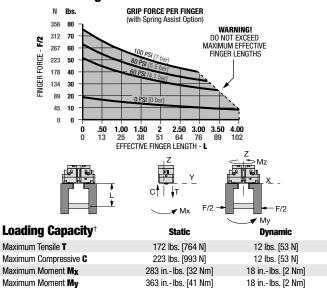
Loading Capacity	Static	Dynamic
Maximum Tensile T	191 lbs. [849 N]	18 lbs. [81 N]
Maximum Compressive C	248 lbs. [1103 N]	18 lbs. [81 N]
Maximum Moment M _X	319 inlbs. [36 Nm]	27 inlbs. [3 Nm]
Maximum Moment My	451 inlbs. [51 Nm]	35 inlbs. [4 Nm]
Maximum Moment M _X	283 inlbs. [32 Nm]	35 inlbs. [4 Nm]

 $^{\scriptscriptstyle \dagger}\text{Capacities}$ are per set of jaws and are not simultaneous

RDH-2M-L Loading Information

Maximum Moment Mx

†Capacities are per set of jaws and are not simultaneous



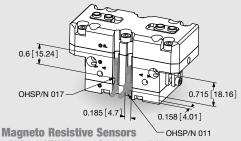
Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	170 lbs.	754 N
Without Spring Assist -L	111 lbs.	494 N
With Spring Assist	226 lbs.	1006 N
With Spring Assist -L	149 lbs.	661 N
Total Stroke:		
Standard	0.24 in.	6 mm
Extended -L	0.47 in.	12 mm
Weight (RDH)	0.86/0.93 lbs.	0.39/0.42 Kg
Pressure Range without Spring		2-7 Bar
Pressure Range with Spring		4.5-7 Bar

Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	1.24 in ² .	8 cm ²
Displacement		10.3 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.07 sec./0.07 sec.	
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2-p	osition
Valve required to actuate double acting	. 4-way, 2-position	

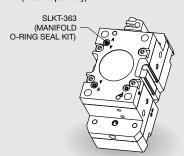
230 in.-lbs. [26 Nm]

18 in.-lbs. [2 Nm]

Accessory Mounting Technical Data

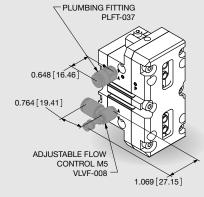


- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold O-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-363V)

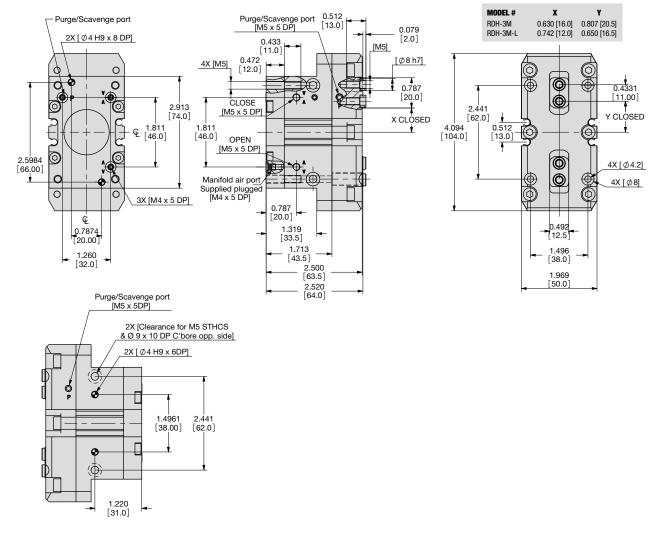


Plumbing Fittings

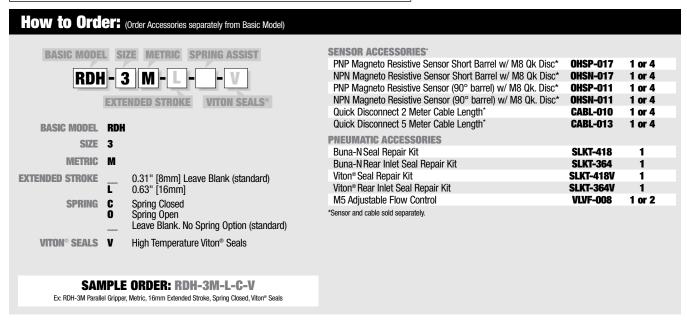
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RDH-3M **2-JAW PARALLEL SERIES**



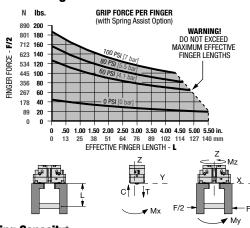


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW							
UNLESS DIHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW							
Ç	$\Rightarrow \Leftrightarrow$	⊕	\oplus	Imperial in.	Metric [mm]		
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$		



PARALLEL GRIPPER RDH-3M 2-JAW PARALLEL SERIES

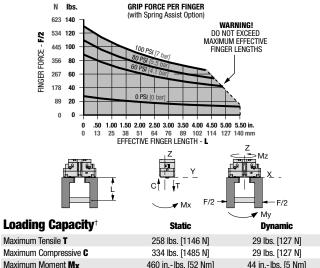
RDH-3M Loading Information



Loading Capacity [™]	Static	Dynamic
Maximum Tensile T	289 lbs. [1284 N]	44 lbs. [196 N]
Maximum Compressive C	374 lbs. [1665 N]	44 lbs. [196 N]
Maximum Moment M _X	513 inlbs. [58 Nm]	62 inlbs. [7 Nm]
Maximum Moment My	735 inlbs. [83 Nm]	97 inlbs. [11 Nm]
Maximum Moment M _X	478 inlbs. [54 Nm]	97 inlbs. [11 Nm]

†Capacities are per set of jaws and are not simultaneous

RDH-3M-L Loading Information



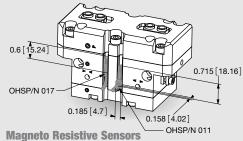
Maximum Tensile T	258 lbs. [1146 N]	29 lbs. [127 N]
Maximum Compressive C	334 lbs. [1485 N]	29 lbs. [127 N]
Maximum Moment M _X	460 inlbs. [52 Nm]	44 inlbs. [5 Nm]
Maximum Moment My	584 inlbs. [66 Nm]	53 inlbs. [6 Nm]
Maximum Moment M _X	381 inlbs. [43 Nm]	53 inlbs. [6 Nm]
10 111 1 1		

†Capacities are per set of jaws and are not simultaneous

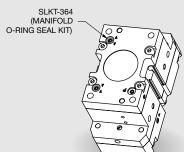
Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	296 lbs.	1317 N
Without Spring Assist -L	192 lbs.	854 N
With Spring Assist	379 lbs.	1683 N
With Spring Assist -L	246 lbs.	1094 N
Total Stroke:		
Standard	0.31 in.	8 mm
Extended -L	0.63 in.	16 mm
Weight (RDH)	1.81/1.94 lbs.	0.82/0.88 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	2.14 in ² .	13.8 cm ²
Displacement	1.43 in ³ .	23.4 cm ³
Temperature Range		
Actuation (open/close)		/0.08 sec.
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data

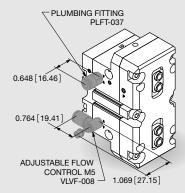


- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold O-Ring Seals

- · Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-364V)

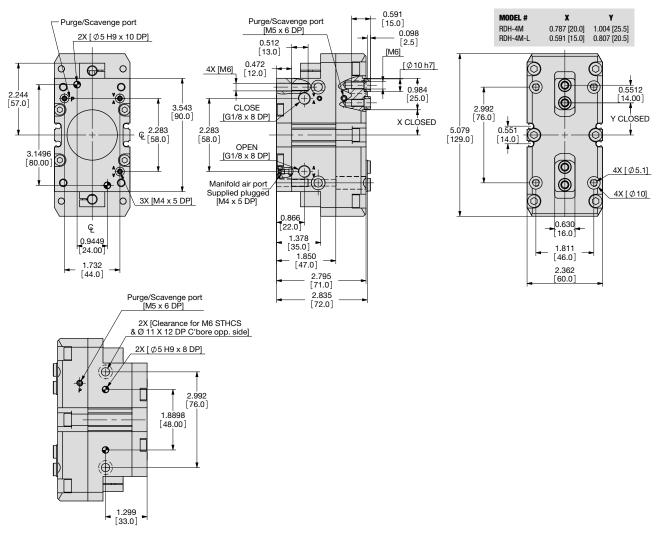


Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RDH-4M 2-JAW PARALLEL SERIES



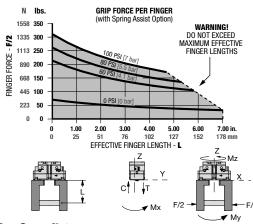


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW						
ONLESS GIBERMISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW						
Ç	$\rightarrow \odot$	⊕	\bigoplus	Imperial in.	Metric [mm]	
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$	

HOW TO Order: (Order Accessories separately from Basic Model) BASIC MODEL SIZE METRIC SPRING ASSIST RDH - 4 M - L - V EXTENDED STROKE VITON SEALS* BASIC MODEL RDH SIZE 4 METRIC M EXTENDED STROKE 0.39" [10mm] Leave Blank (standard) L 0.79" [20mm] SPRING C Spring Closed 0 Spring Open Leave Blank, No Spring Option (standard)	SENSOR ACCESSORIES* 8mm PNP Inductive Sensor w/ M8 Quick Disconnect* 8mm NPN Inductive Sensor w/ M8 Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* Quick Disconnect 2 Meter Cable Length* Quick Disconnect 5 Meter Cable Length* PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit G 1/8" Adjustable Flow Control	OISP-011 OISN-011 OHSP-017 OHSN-017 OHSN-011 OHSN-011 CABL-010 CABL-013 SLKT-419 SLKT-364 SLKT-364V VLVF-005	1 or 2 1 or 2 1 or 4 1 or 4 1 or 4 1 or 4 1 or 4
VITON® SEALS V High Temperature Viton® Seals	*Sensor and cable sold separately.		
SAMPLE ORDER: RDH-4M-L-C-V Ex: RDH-4M Parallel Gripper, Metric, 20mm Extended Stroke, Spring Closed, Viton® Seals			

PARALLEL GRIPPER RDH-4M 2-JAW PARALLEL SERIES

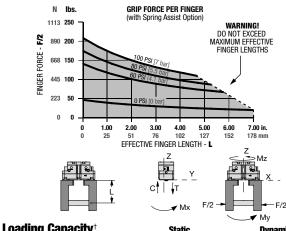
RDH-4M Loading Information



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m]
m]

†Capacities are per set of jaws and are not simultaneous

RDH-4M-L Loading Information



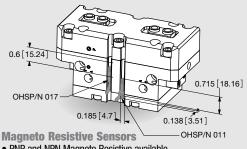
Loading Japacity	Static	Dynamic
Maximum Tensile T	313 lbs. [1394 N]	38 lbs. [168 N]
Maximum Compressive C	415 lbs. [1845 N]	38 lbs. [168 N]
Maximum Moment M _X	602 inlbs. [68 Nm]	53 inlbs. [6 Nm]
Maximum Moment My	743 inlbs. [84 Nm]	71 inlbs. [8 Nm]
Maximum Moment M _X	496 inlbs. [56 Nm]	71 inlbs. [8 Nm]

†Capacities are per set of jaws and are not simultaneous

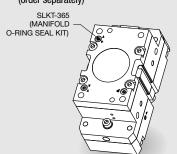
Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	490 lbs.	2177 N
Without Spring Assist -L	318 lbs.	1414 N
With Spring Assist	628 lbs.	2789 N
With Spring Assist -L	408 lbs.	1814 N
Total Stroke:		
Standard	0.39 in.	10 mm
Extended -L	0.79 in.	20 mm
Weight (RDH)	3.15/3.33 lbs.	1.43/1.51 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	3.52 in ² .	22.7 cm ²
Displacement	2.90 in ³ .	47.5 cm ³
Temperature Range	-30°~180° F	
Actuation (open/close)		/0.08 sec.
Accuracy	±0.0024 in.	±0.06 mm
Repeatability	±0.0012 in.	±0.03 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data

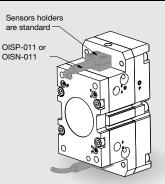


- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



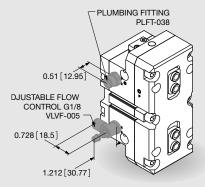
Manifold 0-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-364V)



Inductive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- · Simple adjustment of the target with screw driver
- Available with 2M Quick Disconnect mating cable (order separately)

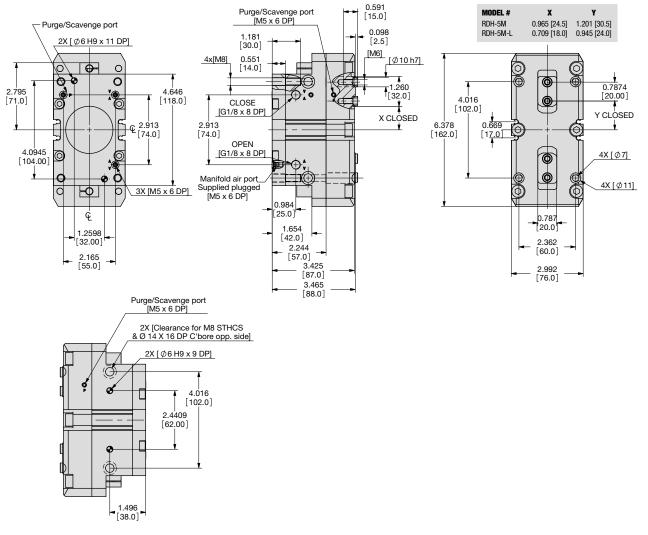


Plumbing Fittings

- Adjustable flow controls:
 - Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RDH-5M 2-JAW PARALLEL SERIES



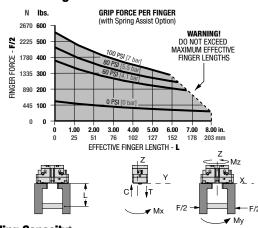


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Ç	$\rightarrow \odot$	⊕	\bigoplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

BASIC MODEL SIZE METRIC EXTENDED STROKE SPRING	RDH 5 M 0.51" [13mm] Leave Blank (standard) 1.02" [26mm] C Spring Closed O Spring Open Leave Blank. No Spring Option (standard)	SENSOR ACCESSORIES' 8mm PNP Inductive Sensor w/ M8 Quick Disconnect* 8mm NPN Inductive Sensor w/ M8 Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* Quick Disconnect 2 Meter Cable Length* Quick Disconnect 5 Meter Cable Length* PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit G 1/8" Adjustable Flow Control *Sensor and cable sold separately.	OISP-011 OISN-011 OHSP-017 OHSP-011 OHSP-011 CABL-010 CABL-013 SLKT-420 SLKT-365 SLKT-420V SLKT-365V VLVF-005	1 or 2 1 or 2 1 or 4 1 or 4 1 or 4 1 or 4 1 or 4 1 or 4
	W High Temperature Viton® Seals IPLE ORDER: RDH-5M-L-C-V I Gripper, Metric, 26mm Extended Stroke, Spring Closed, Viton® Seals			

PARALLEL GRIPPER RDH-5M 2-JAW PARALLEL SERIES

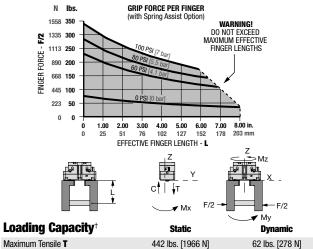
RDH-5M Loading Information



Loading Capacity	Static	Dynamic
Maximum Tensile T	493 lbs. [2192 N]	96 lbs. [428 N]
Maximum Compressive C	657 lbs. [2923 N]	96 lbs. [428 N]
Maximum Moment M _X	929 inIbs. [105 Nm]	142 inlbs. [16 Nm]
Maximum Moment My	1310 inlbs. [148 Nm]	195 inlbs. [22 Nm]
Maximum Moment M _X	859 inlbs. [97 Nm]	195 inlbs. [22 Nm]

†Capacities are per set of jaws and are not simultaneous

RDH-5M-L Loading Information



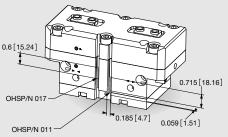
Maximum Tensile T	442 lbs. [1966 N]	62 lbs. [278 N]
Maximum Compressive C	589 lbs. [2621 N]	62 lbs. [278 N]
Maximum Moment M _X	832 inlbs. [94 Nm]	89 inlbs. [10 Nm]
Maximum Moment My	1053 inlbs. [119 Nm]	115 inlbs. [13 Nm]
Maximum Moment M _X	690 inlbs. [78 Nm]	115 inlbs. [13 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	808 lbs.	3593 N
Without Spring Assist -L	525 lbs.	2333 N
With Spring Assist	1037 lbs.	4609 N
With Spring Assist -L	675 lbs.	2999 N
Total Stroke:		
Standard	0.51 in.	13 mm
Extended -L	1.02 in.	26 mm
Weight (RDH)	6.06/6.57 lbs.	2.75/2.98 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	60-100 psi	4-7 Bar

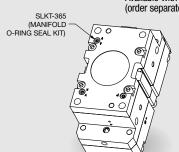
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	5.81 in ² .	37.5 cm ²
Displacement	6.22 in ³ .	102 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)		/0.14 sec.
Accuracy	±0.0024 in.	±0.06 mm
Repeatability	±0.0012 in.	±0.03 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



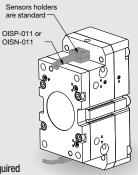
Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- . Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold O-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)



PLUMBING FITTING

0.51[12.95]

1.212 [30.77]

ADJUSTABLE FLOW

CONTROL G1/8

VLVF-005

PLFT-038

Inductive Sensors

6

- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- · Simple adjustment of the target with screw driver
- Available with 2M Quick Disconnect mating cable (order separately)

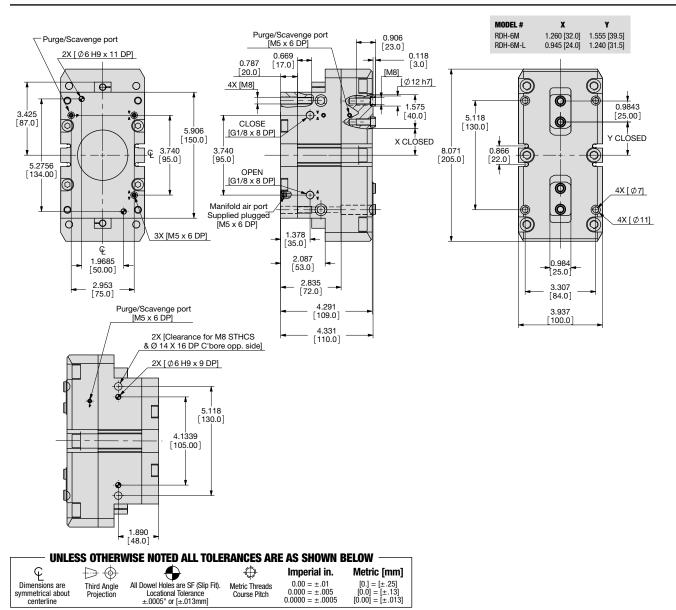
Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
 - For side air port location
 - Top air port are plugged as standard

centerline

PARALLEL GRIPPER RDH-6M 2-JAW PARALLEL SERIES



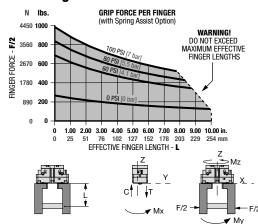


BASIC MODEL SIZE METRIC EXTENDED STROKE SPRING	C Spring Closed Spring Option (standard) Leave Blank. No Spring Option (standard) High Temperature Viton® Seals	SENSOR ACCESSORIES* 8mm PNP Inductive Sensor w/ M8 Quick Disconnect* 8mm NPN Inductive Sensor w/ M8 Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* Quick Disconnect 2 Meter Cable Length* Quick Disconnect 5 Meter Cable Length* PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit G 1/8" Adjustable Flow Control *Sensor and cable sold separately.	OISP-011 OISN-011 OHSP-017 OHSN-017 OHSP-011 OHSN-011 CABL-010 CABL-013 SLKT-421 SLKT-365 SLKT-421V SLKT-365V VLVF-005	1 or 2 1 or 2 1 or 4 1 or 4 1 or 4 1 or 4 1 or 4 1 or 4
	IPLE ORDER: RDH-6M-L-C-V Il Gripper, Metric, 32mm Extended Stroke, Spring Closed, Viton® Seals			

Course Pitch



RDH-6M Loading Information

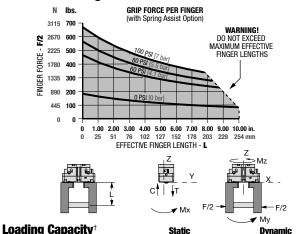


Loading Capacity	Static	Dynamic
Maximum Tensile T	779 lbs. [3463 N]	186 lbs. [827 N]
Maximum Compressive C	1045 lbs. [4649 N]	186 lbs. [827 N]
Maximum Moment M _X	1204 inlbs. [136 Nm]	248 inlbs. [28 Nm]
Maximum Moment My	1744 inlbs. [197 Nm]	363 inlbs. [41 Nm]
Maximum Moment M _X	1151 inlbs. [130 Nm]	363 inlbs. [41 Nm]
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†Capacities are per set of jaws and are not simultaneous

Looding Consoity

RDH-6M-L Loading Information



PARALLEL GRIPPER RDH-6M 2-JAW PARALLEL SERIES

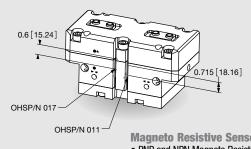
Louding Supusity	Julio	Dynamic
Maximum Tensile T	694 lbs. [3089 N]	121 lbs. [537 N]
Maximum Compressive C	932 lbs. [4146 N]	121 lbs. [537 N]
Maximum Moment M _X	1071 inlbs. [121 Nm]	159 inlbs. [18 Nm]
Maximum Moment My	1390 inlbs. [157 Nm]	212 inlbs. [24 Nm]
Maximum Moment M _X	912 inlbs. [103 Nm]	212 inlbs. [24 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications			
Total Rated Grip Force, F @ 100 psi [7 bar]:			
Without Spring Assist	1406 lbs.	6250 N	
Without Spring Assist -L	914 lbs.	4062 N	
With Spring Assist	1944 lbs.	8640 N	
With Spring Assist -L	1265 lbs.	5623 N	
Total Stroke:			
Standard	0.63 in.	16 mm	
Extended -L	1.26 in.	32 mm	
Weight	12.72 lbs.	5.77 Kg	
Pressure Range without Spring	30-100 psi	2-7 Bar	

Specifications (cont.) Max. Vacuum for Scavenge Port..... 20 mm Hg 8 in. Ha 30 psi Max. Pressure for Purge Port..... 2.1 Bar Cylinder Surface..... 10.08 in². 65 cm² 216 cm³ Temperature Range -30°~180° F -35°~80° C Actuation (open/close) 0.20 sec./0.20 sec. ±0.08 mm Accuracy ±0.0031 in. ±0.04 mm Repeatability ±0.0016 in. Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting 4-way, 2-position

Accessory Mounting Technical Data

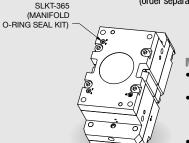


Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required

4.5-7 Bar

- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold O-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- · Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)



PLUMBING FITTING

ADJUSTABLE FLOW

CONTROL G1/8

VLVF-005

0.728 [18.5]

PLFT-038

0.51 [12.95]

1.212 [30.77]

Inductive Sensors

Ю

6

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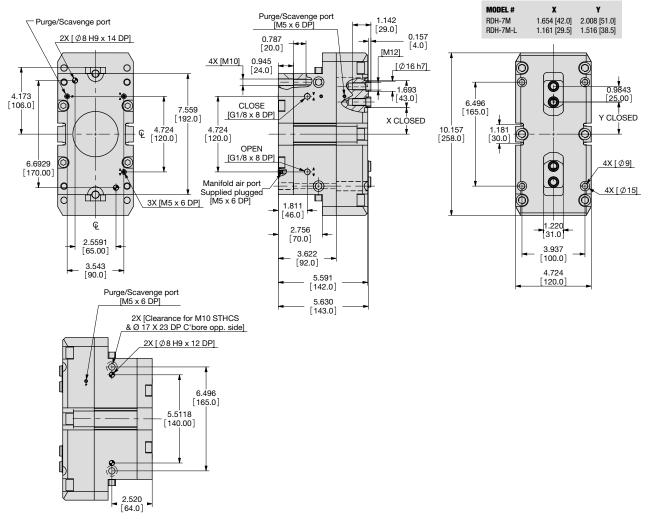
- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- · Simple adjustment of the target with screw driver
- Available with 2M Quick Disconnect mating cable (order separately)

Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- Plumbing fittings:
 - For side air port location
 - Top air port are plugged as standard

PARALLEL GRIPPER RDH-7M **2-JAW PARALLEL SERIES**



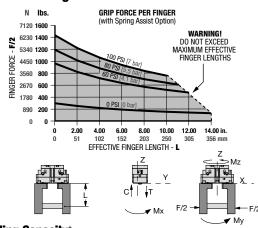


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UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW					
Ç	$\rightarrow \odot$	⊕	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

RDH BASIC MODEL	C Spring Closed Spring Closed Spring Closed Spring Closed Spring Closed Spring Open Leave Blank. No Spring Option (standard) High Temperature Viton® Seals	SENSOR ACCESSORIES* 12mm NPN Inductive Sensor w/ M12 Quick Disconnect* 12mm NPN Inductive Sensor w/ M12 Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* OHSN NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* M8 Quick Disconnect 2 Meter Cable Length* M8 Quick Disconnect 5 Meter Cable Length* M12 Quick Disconnect 2 Meter Cable Length* M12 Quick Disconnect 5 Meter Cable Length* CABL M12 Quick Disconnect 5 Meter Cable Length* CABL N12 Quick Disconnect 5 Meter Cable Length* SENTEROMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit Viton® Rear Inlet Seal Repair Kit SLKT- SENTEROMATIC SUMPLES SENT	-017 1 or 2 2-017 1 or 4 1-017 1 or 4 1-011 1 or 4 1-011 1 or 4 1-010 1 or 4 1-013 1 or 4 1-014 1 or 2 1-018 1 to 2 1-018 1 to 2 1-018 1 to 2
	IPLE ORDER: RDH-7M-L-C-V Gripper, Metric, 50mm Extended Stroke, Spring Closed, Viton* Seals		

PARALLEL GRIPPER RDH-7M 2-JAW PARALLEL SERIES

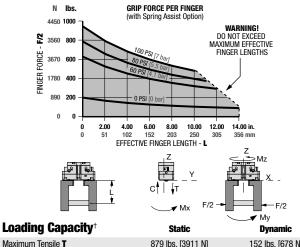
RDH-7M Loading Information



Loading Capacity [™]	Static	Dynamic
Maximum Tensile T	1013 lbs. [4505 N]	236 lbs. [1048 N]
Maximum Compressive C	1335 lbs. [5938 N]	236 lbs. [1048 N]
Maximum Moment M _X	1478 inlbs. [167 Nm]	319 inlbs. [36 Nm]
Maximum Moment My	2106 inlbs. [238 Nm]	451 inlbs. [51 Nm]
Maximum Moment M _X	1425 inlbs. [161 Nm]	451 inlbs. [51 Nm]

†Capacities are per set of jaws and are not simultaneous

RDH-7M-L Loading Information



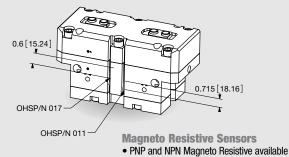
-causing capacity	outio	Dynamio .
Maximum Tensile T	879 lbs. [3911 N]	152 lbs. [678 N]
Maximum Compressive C	1159 lbs. [5155 N]	152 lbs. [678 N]
Maximum Moment M _X	1283 inlbs. [145 Nm]	204 inlbs. [23 Nm]
Maximum Moment My	1584 inlbs. [179 Nm]	257 inlbs. [29 Nm]
Maximum Moment M _X	1080 inlbs. [122 Nm]	257 inlbs. [29 Nm]

†Capacities are per set of jaws and are not simultaneous

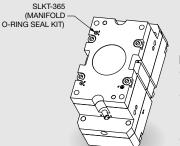
Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	2228 lbs.	9901 N
Without Spring Assist -L	1441 lbs.	6404 N
With Spring Assist	2822 lbs.	12542 N
With Spring Assist -L	1830 lbs.	8135 N
Total Stroke:		
Standard	0.98 in.	25 mm
Extended -L	1.97 in.	50 mm
Weight	24.8 lbs.	11.25 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar

Specifications (cont.) Max. Vacuum for Scavenge Port..... 8 in. Ha 20 mm Hg 30 psi Max. Pressure for Purge Port..... 2.1 Bar Cylinder Surface..... 16.12 in². 104 cm² Displacement..... 32.95 in³. 540 cm³ Temperature Range -30°~180° F -35°~80° C Actuation (open/close) 0.55 sec./0.55 sec. ±0.1 mm ±0.05 mm Repeatability ±0.002 in. Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting 4-way, 2-position

Accessory Mounting Technical Data

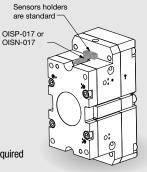


- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold 0-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)



PLUMBING FITTING

ADJUSTABLE FLOW

CONTROL G1/8

VLVF-005

0.728[18.5]

1.212 [30.77]

PLFT-038

0.51 [12.95

Inductive Sensors

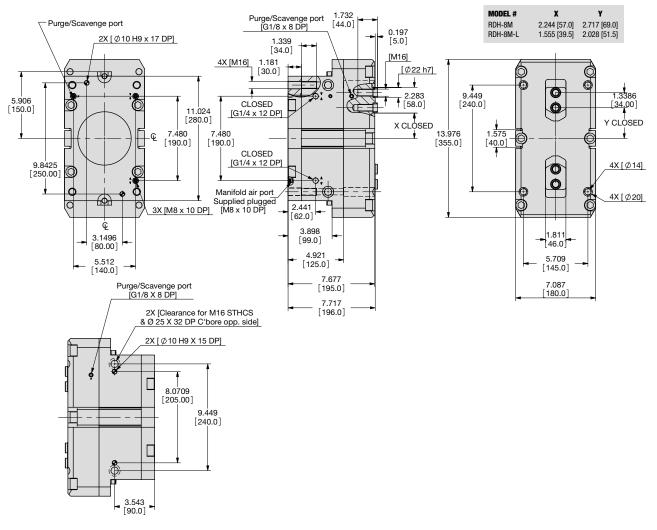
- PNP and NPN Magneto Resistive available
- Sensors holders and targets are standard mounted
- · Simple adjustment of the target with screw driver
- Available with 2M Quick Disconnect mating cable (order separately)

Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- · Plumbing fittings:
 - For side air port location
 - Top air port are plugged as standard

PARALLEL GRIPPER RDH-8M 2-JAW PARALLEL SERIES



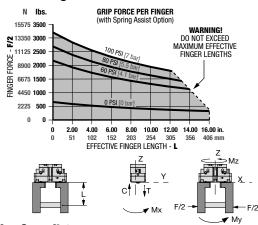


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW					
UNLESS UTHERWISE NOTED ALL TULERANCES ARE AS SHOWN BELOW					
Ç	$\rightarrow \odot$	⊕	\bigoplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

RDH BASIC MODEL	C Spring Closed Spring Option (standard) Well are Blank (standard) High Temperature Viton® Seals	PNP Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/ M8 Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/ M8 Qk. Disc* OHSP M8 Quick Disconnect 2 Meter Cable Length* M12 Quick Disconnect 5 Meter Cable Length* CABL M12 Quick Disconnect 2 Meter Cable Length* CABL M12 Quick Disconnect 5 Meter Cable Length* CABL PNEUMATIC ACCESSORIES Buna-NSeal Repair Kit Buna-NRear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit SLKT-	-017 1 or 2 -017 1 or 4 -017 1 or 4 -011 1 or 4 -011 1 or 4 -010 1 or 4 -013 1 or 4 -014 1 or 2 -018 1 to 2 -423 1 -423V 1
	IPLE ORDER: RDH-8M-L-C-V I Gripper, Metric, 70mm Extended Stroke, Spring Closed, Viton® Seals		

PARALLEL GRIPPER RDH-8M 2-JAW PARALLEL SERIES

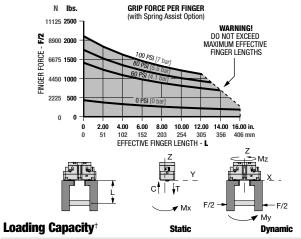
RDH-8M Loading Information



Loading Capacity	Static	Dynamic
Maximum Tensile T	1543 lbs. [6863 N]	392 lbs. [1743 N]
Maximum Compressive C	2006 lbs. [8921 N]	392 lbs. [1743 N]
Maximum Moment M _X	3354 inlbs. [379 Nm]	743 inlbs. [84 Nm]
Maximum Moment My	4257 inlbs. [481 Nm]	947 inlbs. [107 Nm]
Maximum Moment M _X	2664 inlbs. [301 Nm]	947 inlbs. [107 Nm]

†Capacities are per set of jaws and are not simultaneous

RDH-8M-L Loading Information



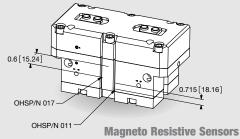
Maximum Tensile T	1328 lbs. [5906 N]	253 lbs. [1125 N]
Maximum Compressive C	1726 lbs. [7678 N]	253 lbs. [1125 N]
Maximum Moment M _X	2885 inlbs. [326 Nm]	478 inlbs. [54 Nm]
Maximum Moment My	3160 inlbs. [357 Nm]	522 inlbs. [59 Nm]
Maximum Moment M _X	1974 inlbs. [223 Nm]	522 inlbs. [59 Nm]

†Capacities are per set of jaws and are not simultaneous

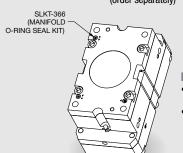
Specifications			
Total Rated Grip Force, F @ 100 psi [7 bar]:			
Without Spring Assist	4941 lbs.	21958 N	
Without Spring Assist -L	3190 lbs.	14178 N	
With Spring Assist	6300 lbs.	28002 N	
With Spring Assist -L	4076 lbs.	18115 N	
Total Stroke:			
Standard	1.38 in.	35 mm	
Extended -L	2.76 in.	70 mm	
Weight	71.1 lbs.	32.3 Kg	
Pressure Range without Spring	30-100 psi	2-7 Bar	
Pressure Range with Spring	50-100 psi	3.5-7 Bar	

Specifications (cont.) Max. Vacuum for Scavenge Port..... 8 in. Ha 20 mm Ha 30 psi Max. Pressure for Purge Port..... 2.1 Bar 35.81 in². 231 cm² Cylinder Surface..... Displacement..... 103.1 in³. 1689 cm3 Temperature Range-30°~180° F -35°~80° C Actuation (open/close) 1.3 sec./1.3 sec. ±0.1 mm Accuracy ±0.0039 in. ±0.05 mm Repeatability ±0.002 in. Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting 4-way, 2-position

Accessory Mounting Technical Data

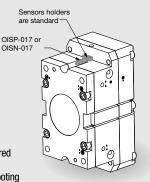


- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



Manifold O-Ring Seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-366V)



PLUMBING FITTING PLFT-039

ADJUSTABLE FLOW

CONTROL G1/4

VLVF-010

1.067 [27.09]

[12.45

1.15 [29.21]

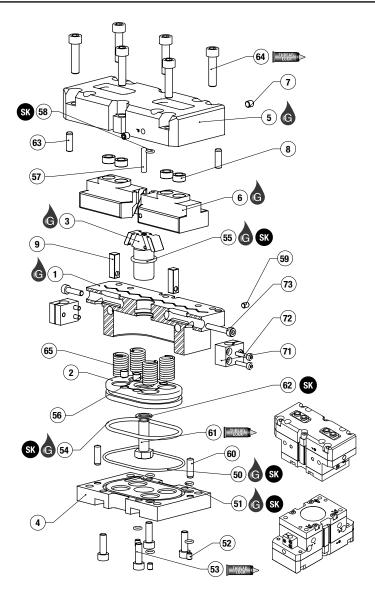
Inductive Sensors

0

- PNP and NPN Magneto Resistive available
- Sensors holders and targets are standard mounted
- · Simple adjustment of the target with screw driver
- Available with 2M Quick Disconnect mating cable (order separately)

Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- · Plumbing fittings:
 - For side air port location
 - Top air port are plugged as standard



Iten	ı Qty	Name
01	1	Body
02	1	Piston
03	1	Double wedge
04	1	Cap
05	1	Bottom Case
06	2	Jaws
07		Bottom Case, SS Screw
80	4	Locating sleeve
09	2	Sensing nut
50	1	Cap, 0-ring
<u>51</u>	3	Cap, 0-ring
52	3	Cap, SS screw
53	4	Cap, SHC screw
54	1	Piston, O-ring
55	11	Body, O-ring
56	4	Piston, Magnet
<u>57</u>	1	Piston, Pin
58	11	Bottom case, 0-ring
59	1	Body, SS screw
<u>60</u>	2	Cap, Pin
61	11	Double wedge, HH screw
62	1	Double wedge, Seal
<u>63</u>	2	Bottom case, Pin
64	6	Bottom case, SHC Screw
65	4 or 8	Spring
<u>71 </u>	2	Sensor holder
72	4	Sensor holder, SHC screw
73	2	Sensing nut, SHC screw

NOTE: Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.



Assembly Procedure

- 1) Lubricate and install seal #55 into the body #1
- 2) Install #59 screw with thread locker into the body #1
- 3) Sub assemble the sensing nuts #9 into the jaws #6
- 4) Sub assemble the jaws #6 on either side of the double wedge #3 with lubrication
- 5) Insert the jaws and double wedge sub assembly into the body
- 6) Install seal #58 into the bottom case #5
- 7) Insert the screws #7 into the bottom case #5
- 8) Install bottom case #5 with pressed-in pins #63 onto the body and fasten with #64 screws with thread locker
- 9) Lubricate and install seal #54 into the piston #2
- 10) Mount magnets #56 to piston #2 with thread locker

- 11) For –C option, insert the springs #65 into the body #1 counterbore holes
- 12) Insert the piston #2 with pressed-in pin #57 onto the double wedge#3 and fasten with screw #61 with thread locker and washer #62. Face mount the piston counterbore holes to the body counterbore holes for —C option. Opposite mount for —O option.
- 13) For -0 option, insert the springs #65 into the piston #2 counterbore holes
- 14) Install the screws #52 with thread locker onto the cap #4
- 15) Install seals #50 and #51 into the cap #4
- 16) Insert the cap #4 into the body #1 and locate it using cap dowel pins #60
- 17) Fasten the cap #4 with #53 screws with thread locker
- 18) Install the sensor holders #71 onto the body and fasten with screws #72

- 19) Insert screws #73 into the sensing nuts #9 from the body holes
- 20) Insert locating sleeves #8 into the jaws







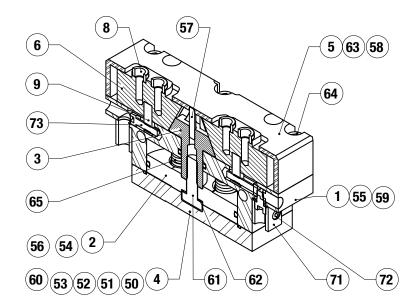








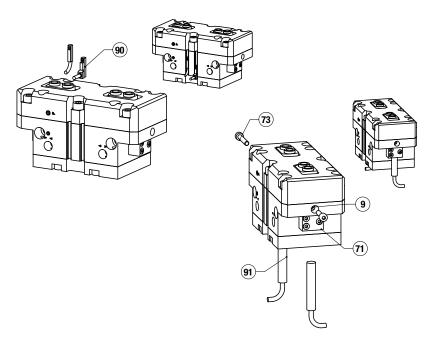




lten	n Qty	Name
I	quy	Nullio
01	1	Body
02	1	Piston
03	1	Double wedge
04	1	Cap
05	1	Bottom Case
06	2	Jaws
07	2	Bottom Case, SS Screw
08	4	Locating sleeve
09	2	Sensing nut
50	1	Cap, 0-ring
51	2	Cap, 0-ring
52	3	Cap, SS screw
53	4	Cap, SHC screw
54	1	Piston, O-ring
55	1	Body, O-ring
56	4	Piston, Magnet
57	1	Piston, Pin
58	1	Bottom case, 0-ring
59	1	Body, SS screw
60	2	Cap, Pin
61	1	Double wedge, HH screw
62	1	Double wedge, Seal
63	2	Bottom case, Pin
64	6	Bottom case, SHC Screw
65	4 or 8	Spring
71	2	Sensor holder
72	4	Sensor holder, SHC screw
73	2	Sensing nut, SHC screw

NOTE: Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Magneto Resistive Sensor #90

- 1) Insert sensor #90 from either end of the profile slot
- 2) Adjust the sensor #90 into the profile slot, depending on the position to sense
- 3) Set the sensor with the integrated screw

Inductive Sensor #91

- 1) Insert sensor #91 into the sensor holder #71
- 2) Tighten the sensor using the SHC screw onto the sensor holder #71
- 3) Insert the SHC screw #73 into the sensing nut #9. The SHC screws are the targets to be adjusted in front of the sensor. The SHC screws #73 are supplied with 2 different lengths: depending on the position to sense, use the shortest for open position, or the longest for close position. The sensing nut #9 has a thread insert that prevents the target from loosening (this may make the target harder to tighten into the nut).











ased





2P Parallel Gripper-2-Jaw Precision Series

Precision Gripper

Two centering jaws and very good repeatability [0.02mm] allow loading and unloading accurate cylindrical parts.

Harsh Environments

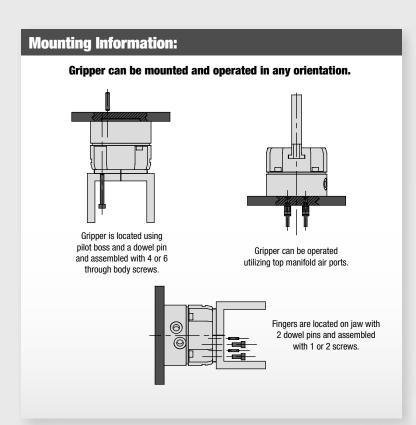
Shielded design (**-E**) repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.

Compact and Powerful

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, hydraulic power, safety springs for internal or external gripping, inductive sensors, tandem cylinder, Viton® seals, and protective boot) allow these grippers to be used in a number of applications.



Technical Specifications: Pneumatic Specifications Imperial Metric Pressure Operating Range 30-100 psi 2-7 bar Double or double acting Cylinder Type spring-assisted or single acting with spring **Dynamic Seals** Buna-N Valve Required to Operate: **Double Acting** 4-way, 2-position Single acting (Option RE or RI) 3-way, 2-position **Air Quality Requirements** Filtration **40 Micron or Better** Lubrification **Not Necessary* Temperature Operating Range** Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C **Application Restrictions Expected Life** Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes *Addition of lubrication will greatly increase service life

Product Features

Quality Components

Body made from aluminum alloy with Teflon™ impregnated hardcoat anodize. Other essential parts of the gripper are made of hardened and precision ground steel

Standard and **Extended Stroke (-C)** Each model of gripper is available in two stroke lengths

Versatile Finger Mounting 2 finger mounting surfaces on each jaw

Viton® Seals Optional Viton® seals for high temperatures



Protective Gripper BootOptional Gripper Boot (-E) to protect the mechanism of the clamp are liquid and large external impurities.

Sensor Target Option (**-T**) to control the jaw position at the rear of the clamp

Sensor Unit

Option (-K) to benefit from integrated detection

Pneumatic Power Side or top ports (sealing face / face)

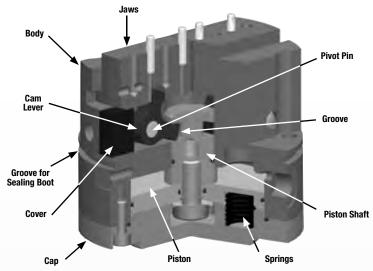
Hydraulic Power
Option (-H) up to 20 bar max,
(-H80) up to 80 bar max.

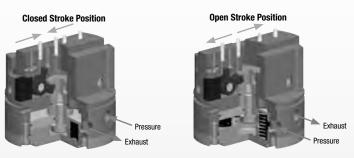
Optional Spring Assist
Optional spring assist retains the component should the air supply fail, to assist the gripper for internal (-RE) or external (-RI) gripping, or in single acting mode

Tandem Cylinder

Option (-M) doubles the grip force

Operating Principle





- A large double-acting piston is connected to the piston shaft at its end with a driving groove.
- Levers pivot in the body about an axis of articulation. Their two heads agree precisely on one side in the groove of the small piston, the other in a groove cut in each jaw holder.
- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

Style: 2P Precision Parallel Gripper



	OUUZP	0002F-6
Total Stroke:	10 mm	16 mm
Force at 6bar:1	694 N	432 N
Force w/o air:2	176 N	109 N
Weight:	0.51 kg	0.51 kg

See Page 1.42 & 1.43

Style: 2P Precision Parallel Gripper



	8002P	8002P-0
Total Stroke:	13 mm	20 mm
Force at 6bar:1	1946 N	1256 N
Force w/o air:2	635 N	410 N
Weight:	0.84 kg	0.84 kg

See Page 1.44 & 1.45

Style: 2P Precision Parallel Gripper



	11002P	11002P-
Total Stroke:	20 mm	30 mm
Force at 6bar:1	3043 N	2030 N
Force w/o air:2	965 N	644 N
Weight:	2.04 kg	2.04 kg

See Page 1.46 & 1.47

Style: 2P Precision Parallel Gripper



	14002P	14002P-C
Total Stroke:	26 mm	40 mm
Force at 6bar:1	6232 N	4031 N
Force w/o air:2	2305 N	1490 N
Weight:	4.20 kg	4.20 kg

See Page 1.48 & 1.49

Style: 2P Precision Parallel Gripper



	16502P	16502P-C
Total Stroke:	30 mm	50 mm
Force at 6bar:1	11475 N	6878 N
Force w/o air:2	3825 N	2292 N
Weight:	8.74 kg	8.74 kg
	=0.0	4 84
See Page	.50 &	1.51

Style: 2P Precision Parallel Gripper



	16502PGR
Total Stroke:	30 mm
Force at 6bar:1	11475 N
Force w/o air:2	3825 N
Weight:	11.5 kg

See Page 1.52

OPTIONS & ACCESSORIES

See Pages 1.53-1.56

- 1. Force with spring and air at 6bar
- 2. Force with spring without air

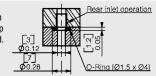
PARALLEL GRIPPER 6002P PRECISION 2P GRIPPER SERIES

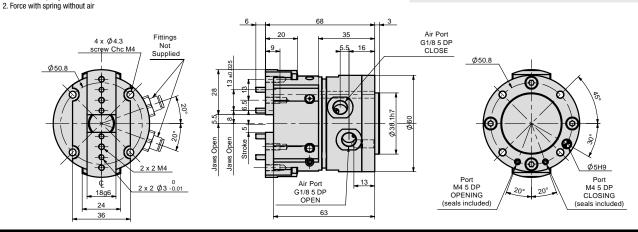


Specifications	6002P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	694 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	176 N
Total Stoke	10 mm
Weight	0.51 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	3 -7 bar
Ø Cylinder Bore	40 mm
Displacement	12 cm3
Actuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). \bigoplus Imperial in. Metric [mm] 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005 $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ Dimensions are Third Angle Projection Metric Threads Course Pitch $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ symmetrical about Locational Tolerance centerline ±.0005" or [±.013mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

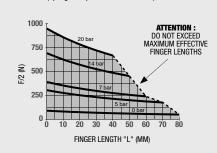


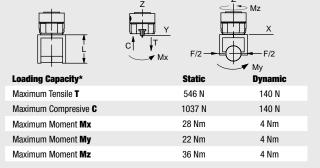


Loading Information:

1. Force with spring and air at 6bar

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

POW	ER TYPE				
P	Pneumatic				
Н	Hydraulic (page 1.53)				
(One of	f two options is mandatory P or H)				
SPRII	NGS				
RE RI	RE External Gripping RI Internal Gripping				
SENSOR UNIT					
• K	T1 • KT2 • KX1 • KX2				
PROT	PROTECTIVE BOOT				
• E	• E3				
_					

Options	and	Acc	essorie	Si
Se	e Pa	ige 1	.53	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER62P	1
Fireproof KEVLAR Protective Boot, Red	E 3	E3R62P	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-011-C	1 or 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 or 4
Cable (2 meters) with M8 screw right gold		CABL-010	1 or 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-156	1
Viton® Seal Repair Kit		SLKT-156V	1
Hydraulic Seal Repair Kit		SLKT-330	1



PARALLEL GRIPPER 6002P-C **PRECISION 2P GRIPPER SERIES**

Specifications Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 Grip Force (F0+R)², 0 bars, Springs Mid-Way, L=0 Total Stoke Weight Pressure Range

Pressure Range with Springs Ø Cylinder Bore Displacement Actuation (open / close)

Repeatability 1. Force with spring and air at 6bar

6002P-C 432 N 109 N 16 mm 0.51 kg 2 -7 bar 3 -7 bar

40 mm

12 cm3

0.07s / 0.07 s

± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are Third Angle Projection symmetrical about centerline

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

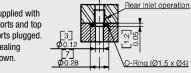
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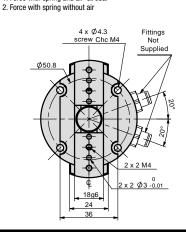
Metric Threads Course Pitch

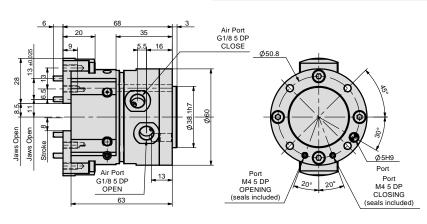
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Metric [mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

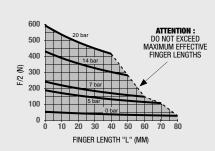


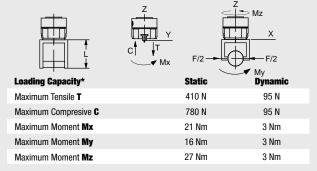




Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)

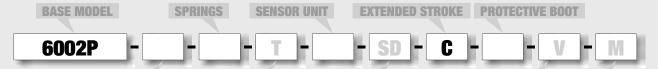




^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

E CEMCND	MICHINIT	VITON®	CEVIC
	IVIUUIVI	WIII UIN	S) E/A/LS

PUW	R TYPE		
P	Pneumatic		
Н	Hydraulic (pa	,	
	f two options is n	nandatory P (or H)
SPRII	NGS		
RE RI	External Grip Internal Grip		
SENS	OR UNIT		
• K	T1 • KT2	• KX1	• KX2
	ECTIVE BOOT		
PROT	ECLIVE DUUL		

Options	and Acces	ssories:
Se	Page 1.	53

PROTECTIVE ROOT ADDECCARIES	M-J-I 0-J-	01#	01-71-14
PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER62P	1
Fireproof KEVLAR Protective Boot, Red	E3	E3R62P	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-011-C	1 or 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 or 4
Cable (2 meters) with M8 screw right gold		CABL-010	1 or 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-156	1
Viton® Seal Repair Kit		SLKT-156V	1
Hydraulic Seal Repair Kit		SLKT-330	1

PARALLEL GRIPPER 8002P PRECISION 2P GRIPPER SERIES

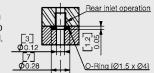


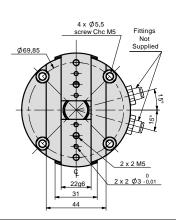
Specifications	8002P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	1946 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	635 N
Total Stoke	13 mm
Weight	0.84 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	60 mm
Displacement	35 cm3
Actuation (open / close)	0.08 s / 0.08 s
Repeatability	± 0.02 mm

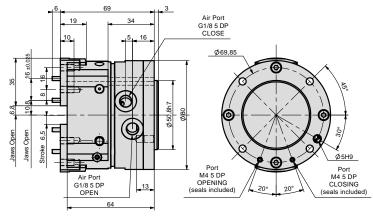
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). \bigoplus Imperial in. Metric [mm] $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ Dimensions are Third Angle Projection Metric Threads Course Pitch symmetrical about $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Locational Tolerance

±.0005" or [±.013mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



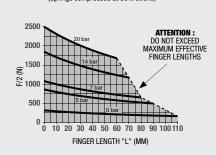


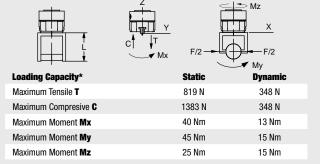


Loading Information:

1. Force with spring and air at 6bar 2. Force with spring without air

> Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

centerline

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

PUWE	R TYPE			
P	Pneum	atic		
Н	Hydrau	ılic (pa	ige 1.53)	
(One of	two optio	ns is m	andatory P	or H)
SPRIN	IGS			
RE RI	Externa Interna			
SENS	OR UNIT	Г		
• K1	M •	KT2	• KX1	• KX2
PROT	ECTIVE	BOOT		
		E3		

Options	and	Acc	esso	ries:
Se	e Pa	ge 1	.53	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER82P	1
Fireproof KEVLAR Protective Boot, Red SENSOR ACCESSORIES	E 3	E3R82P	1
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-011-C	1 or 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 or 4
Cable (2 meters) with M8 screw right gold PNEUMATIC ACCESSORIES		CABL-010	1 or 4
Standard Seal Repair Kit		S80	1
Viton® Seal Repair Kit		S80V	1
Hydraulic Seal Repair Kit		S80H	1

1,45



Repeatability

1. Force with spring and air at 6bar

PARALLEL GRIPPER 8002P-C PRECISION 2P GRIPPER SERIES



2002P-C 1256 N 410 N 20 mm 0.84 kg 2 -7 bar 4 -7 har 60 mm 35 cm3

± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are Third Angle Projection symmetrical about

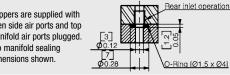
centerline

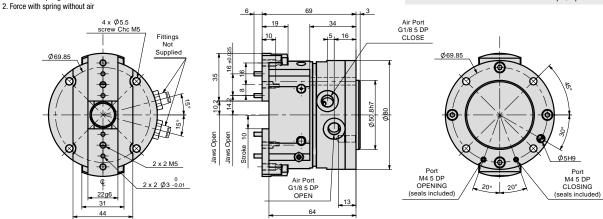
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm]

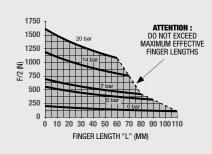
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

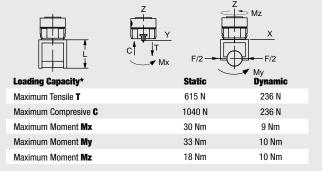






Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)

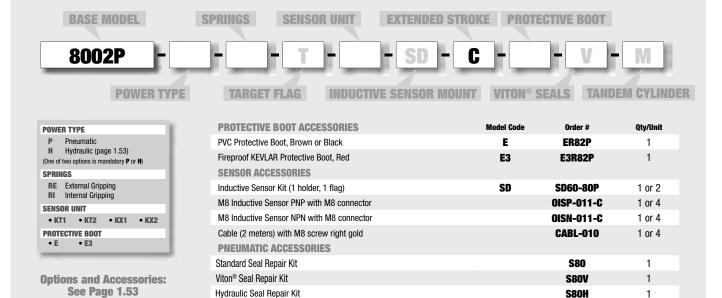




* The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



PARALLEL GRIPPER 11002P PRECISION 2P GRIPPER SERIES



3043 N Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 965 N Total Stoke 20 mm Weight 2.04 kg Pressure Range 2 -7 bar Pressure Range with Springs 4 -7 bar Ø Cylinder Bore 76 mm 87 cm3 Displacement Actuation (open / close) $0.10 \, s / \, 0.10 \, s$ Repeatability \pm 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Imperial in. Metric [mm]

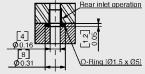
All Dowel Holes are SF (Slip Fit). Third Angle Projection

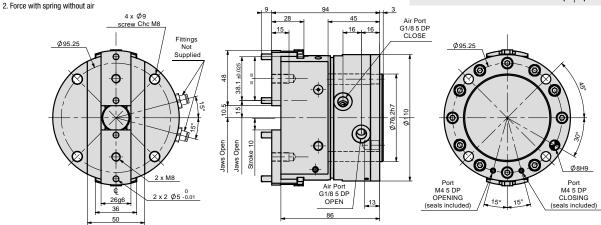
Locational Tolerance ±.0005" or [±.013mm] Metric Threads Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

 $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.





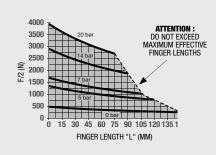
Dimensions are

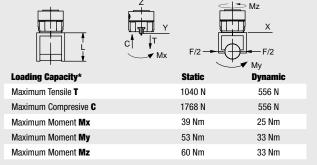
symmetrical about

Loading Information:

1. Force with spring and air at 6bar

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

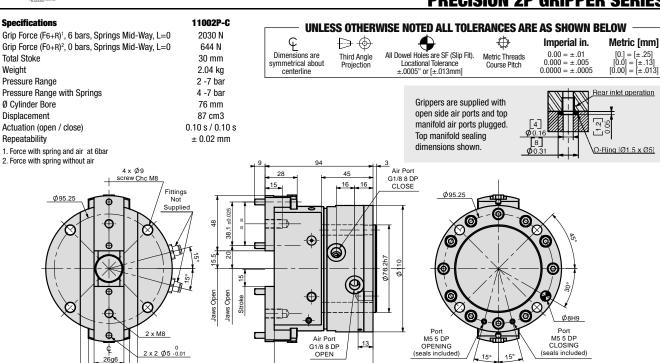
POWI	ER TYPE				
P	Pneumati	С			
Н	Hydraulic	(page 1.53)			
(One of	f two options i	s mandatory P	or H)		
SPRI	NGS				
RE External Gripping RI Internal Gripping					
SENSOR UNIT					
• KT1 • KT2 • KX1 • KX2					
PROTECTIVE BOOT					
• E	• E3				

Options	and	Acc	essories:	
Se	e Pa	ge 1	.53	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER112P	1
Fireproof KEVLAR Protective Boot, Red SENSOR ACCESSORIES	E 3	E3R112P	1
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD110P	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-011-C	1 or 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 or 4
Cable (2 meters) with M8 screw right gold PNEUMATIC ACCESSORIES		CABL-010	1 or 4
Standard Seal Repair Kit		S110	1
Viton® Seal Repair Kit		S110V	1
Hydraulic Seal Repair Kit		\$110H	1



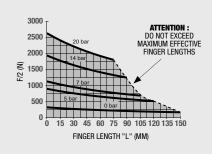
PARALLEL GRIPPER 11002P-C PRECISION 2P GRIPPER SERIES

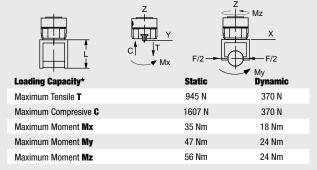






36

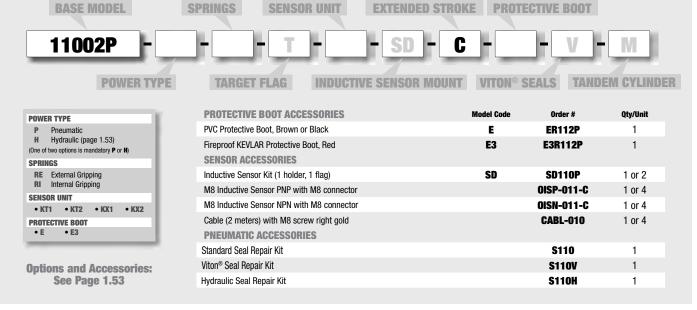




 $[\]ensuremath{^\star}$ The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



PARALLEL GRIPPER 14002P PRECISION 2P GRIPPER SERIES



Specifications	14002P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	6232 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	2305 N
Total Stoke	26 mm
Weight	4.20 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	105 mm
Displacement	220 cm3
Actuation (open / close)	0.16 s / 0.16 s
Repeatability	± 0.02 mm

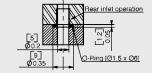
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW \bigoplus

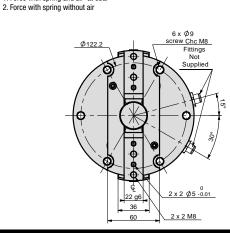
All Dowel Holes are SF (Slip Fit). Third Angle Projection

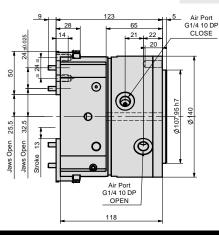
Locational Tolerance ±.0005" or [±.013mm] Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



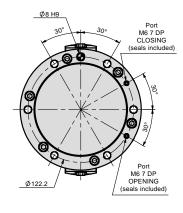




Dimensions are

symmetrical about

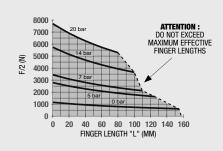
centerline

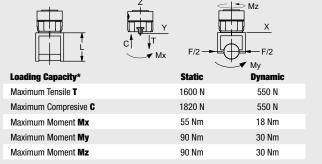


Loading Information:

1. Force with spring and air at 6bar

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

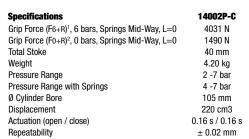
POWE	POWER TYPE				
P	Pneumatic				
Н	Hydraulic (page 1.53)				
(One of	two options is mandatory P or H)				
SPRIN	IGS				
RE RI	RE External Gripping RI Internal Gripping				
SENSOR UNIT					
• KT1 • KT2 • KX1 • KX2					
PROTECTIVE BOOT					
• E	• E3				
_					

Options	and	Acc	esso	ries:
Se	e Pa	ge 1	.53	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-311	1
Fireproof KEVLAR Protective Boot, Red SENSOR ACCESSORIES	E 3	KP-313	1
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-114	1 or 2
M8 Inductive Sensor PNP with M12 connector		OISP-017-C	1 or 4
M8 Inductive Sensor NPN with M12 connector		OISN-017-C	1 or 4
Cable (2 meters) with M12 screw right gold PNEUMATIC ACCESSORIES		CABL-014	1 or 4
Standard Seal Repair Kit		SLKT-333	1
Viton® Seal Repair Kit		SLKT-333V	1
Hydraulic Seal Repair Kit		SLKT-334	1



PARALLEL GRIPPER 14002P-C PRECISION 2P GRIPPER SERIES



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are Third Angle Projection symmetrical about

centerline

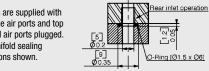
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

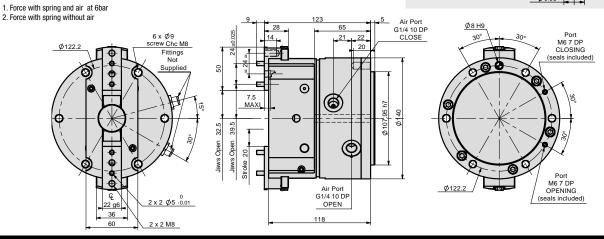
Metric Threads Course Pitch

0

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm]

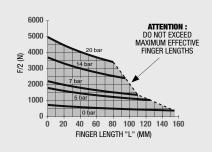
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

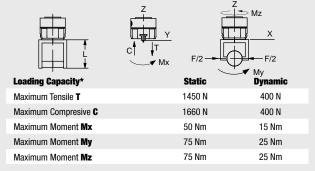




Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



Options and Accessories: See Page 1.53

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-311	1
Fireproof KEVLAR Protective Boot, Red	E3	KP-313	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-114	1 or 2
M8 Inductive Sensor PNP with M12 connector		OISP-017-C	1 or 4
M8 Inductive Sensor NPN with M12 connector		OISN-017-C	1 or 4
Cable (2 meters) with M12 screw right gold		CABL-014	1 or 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-333	1
Viton® Seal Repair Kit		SLKT-333V	1
Hydraulic Seal Repair Kit		SLKT-334	1

PARALLEL GRIPPER 16502P PRECISION 2P GRIPPER SERIES



Specifications	16502P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	11475 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	3825 N
Total Stoke	30 mm
Weight	8.74 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	120 mm
Displacement	494 cm3
Actuation (open / close)	0.29 s / 0.29
Repeatability	± 0.02 mm

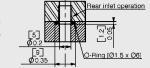
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW 0 Imperial in. Metric [mm]

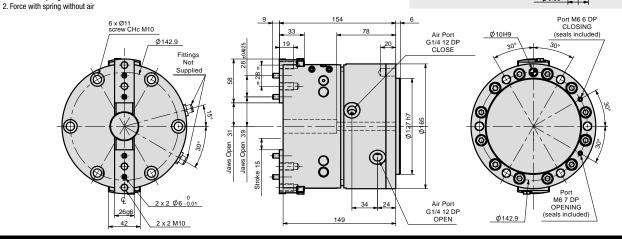
All Dowel Holes are SF (Slip Fit). Third Angle Projection

Locational Tolerance ±.0005" or [±.013mm] Metric Threads Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.





Dimensions are

symmetrical about

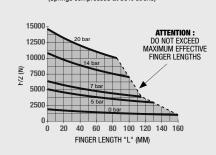
centerline

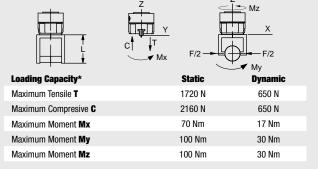
s

Loading Information:

1. Force with spring and air at 6bar

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE TARGET FLAG INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

POWI	POWER TYPE				
P	Pneumatic				
Н	Hydraulic (page 1.53)				
(One o	f two options is mandatory P or H)				
SPRI	NGS				
RE External Gripping RI Internal Gripping					
SENSOR UNIT					
• KT1 • KT2 • KX1 • KX2					
PROTECTIVE BOOT					
• E • E3					
_					

Options	and	Acc	esso	ries:
Se	e Pa	ge 1	1.53	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-314	1
Fireproof KEVLAR Protective Boot, Red	E3	KP-316	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-115	1 or 2
M8 Inductive Sensor PNP with M12 connector		OISP-017-C	1 or 4
M8 Inductive Sensor NPN with M12 connector		OISN-017-C	1 or 4
Cable (2 meters) with M12 screw right gold		CABL-014	1 or 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-335	1
Viton® Seal Repair Kit		SLKT-335V	1
Hydraulic Seal Repair Kit		SLKT-336	1



PARALLEL GRIPPER 16502P-C PRECISION 2P GRIPPER SERIES

Specifications	16502P-C
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	6878 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	2292 N
Total Stoke	50 mm
Weight	8.74 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	120 mm
Displacement	494 cm3
Actuation (open / close)	0.29 s / 0.29 s
Repeatability	± 0.02 mm
1. Force with spring and air at 6bar	

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW | Imperial in. | Metr

Dimensions are
symmetrical about
Third Angle
Projection
D

Third Angle Projection

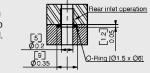
All Dowel Holes are SF (Slip Fit).

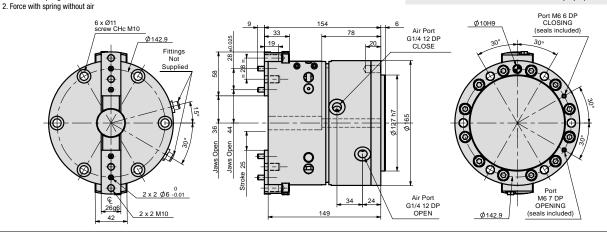
Locational Tolerance ±.0005" or [±.013mm]

Slip Fit). Metric Threads te Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

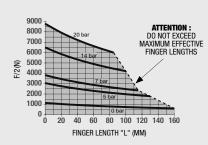


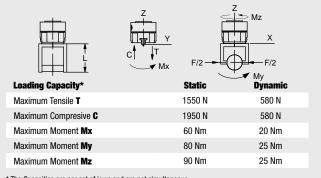


centerline

Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





* The Capacities are per set of jaws and are not simultaneous.

Standard Seal Repair Kit

Hydraulic Seal Repair Kit

Viton® Seal Repair Kit

How To Order:

Options and Accessories:

See Page 1.53

See Pages 53-56 for incompatible accessory combinations

SLKT-335

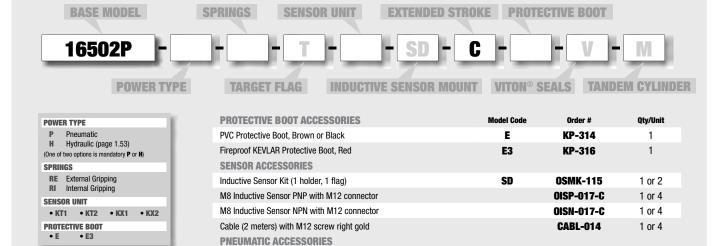
SLKT-335V

SLKT-336

1

1

1



PARALLEL GRIPPER 16502PGR PRECISION 2P GRIPPER SERIES



Specifications	16502P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	11475 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	3825 N
Total Stoke	30 mm
Weight	8.74 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	120 mm
Displacement	494 cm3
Actuation (open / close)	0.29 s / 0.29
Repeatability	± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW \bigoplus Imperial in. Metric [mm]

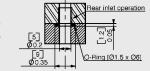
All Dowel Holes are SF (Slip Fit). Third Angle Projection

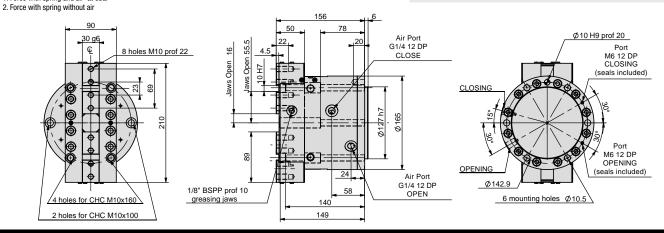
Locational Tolerance ±.0005" or [±.013mm] Metric Threads Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

 $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.





Dimensions are

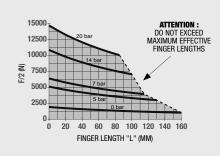
symmetrical about

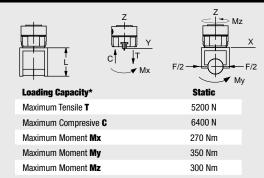
s

Loading Information:

1. Force with spring and air at 6bar

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





* The Capacities are per set of laws and are not simultaneous.

Model Code

How to Order:

See Pages 53-56 for incompatible accessory combinations



POWER TYPE

TARGET FLAG

ACCESSOIRES ENVELOPPE DE PROTECTION

PROTECTIVE BOOT

TANDEM CYLINDER

Qty/Unit

1

1

POWE	R TYPE						
P	Pneuma	tic					
Н	Hydrauli	c (paç	je 1.53)				
(One of t	wo options	is ma	ndatory P	or H)			
SPRIN	GS						
RE External Gripping RI Internal Gripping							
SENSO	R UNIT						
• KT	1 • K	T2	• KX1	• KX2			
PROTECTIVE BOOT							
	• E:						

Fireproof KEVLAR Protective Boot, Red	E 3	KENVE2-21384
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit		SLKT-335
Viton® Seal Repair Kit		SLKT-335V
Hydraulic Seal Repair Kit		SLKT-336

Options and Accessories: See Page 1.53

SUPPLY: (P) Pneumatic (H) (H80) Hydraulic

As standard, the clamp is supplied with air to a pressure of 7 bar. The clamp is fitted with Viton 0-ring seals for high temperatures.

On request (contact us) the gripper can be supplied with hydraulic fluid. The clamp is fitted with seals Viton Quad-Ring.

- Choice (H) allows a hydraulic power to a pressure of 20 bar max. In this case the overall dimensions do not change. For better security the gripper must be fixed on their support before being fired. CAUTION: Hydraulic cycle times are longer.
- Choice (**H80**) allows a hydraulic power to a pressure of 80 bar max. In this case the total height of the gripper is increased (contact us).

The hydraulic power is incompatible with the option tandem (M).

Option (RE) or (RI): Spring Assist

The internal springs of the gripper ensures failsafe operation by retaining the component during pressure loss, to increase the gripforce, or allows the usage of the gripper in single acting operation.

Option (**RE**) for external gripping. Option (**RI**) for internal gripping.

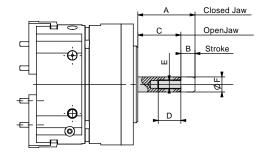
The (RE) is incompatible with the option (RI).

Option (T): Sensor Rod

Option (T) is a steel rod which comes out on the rear side of the gripper. The rod is fixed with the piston and has the same stroke movement. The open end of the rod allows for mounting a cam which allows to control the position of the jaws by using inductive sensors, micro switches, etc

WARNING: when screwing on cam rod, make sure the sensor rod does not rotate to prevent twisting of the springs of options (RE) or (RI).

Option (T) is incompatible with option (K).



Model	A	В	C	D	E	F
6002P & 6002P-C	35	5	30	15	M6	10
8002P & 8002P-C	35	6.5	28.5	15	M6	10
11002P & 11002P-C	35	10	25	15	M6	15
14002P & 14002P-C	55	13	42	20	M8	15
16502P & 16502P-C	53	23	30	20	M8	15

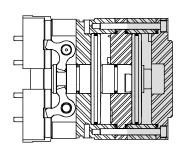
Option (M): Tandem Cylinder

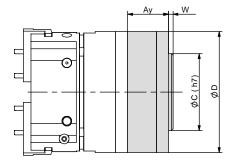
The (M) is a cylinder light-alloy that fits behind the bottom plate. This actuator's integral action allows to double the gripforce by using the same pressure.

The combination of tandem option tandem (M) and Option (RE) or (RI) can double the clamping forces of the spring assist option. For cycle times of the tandem option, apply a factor of 3 to the actuation time.

The (M) is incompatible with the option (H).

Model	Ау	ØC	ØD	W	Weight (kg)
6002P & 6002P-C	28.5	38.1	60	3	0.200
8002P & 8002P-C	27	50.8	80	3	0.300
11002P & 11002P-C	34	76.2	110	3	0.750
14002P & 14002P-C	49	107.95	140	5	2.100
16502P & 16502P-C	65	127	165	6	3.600

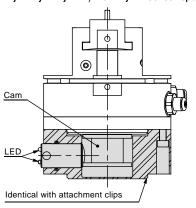


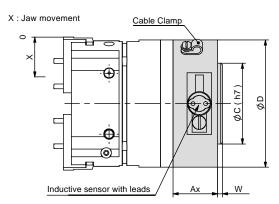


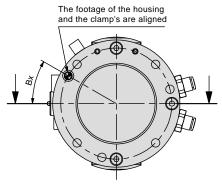


Option (KT1), (KX1), (KT2), (KX2): Sensor Unit

The (**K**) is a lightweight alloy housing that fits on the back of the gripper. An integrated shaft follows the movement of the piston to provide information to the sensor attached to the side of the unit. It can control two positions of the grippers jaws. 2 types of inductive sensors (**KT, KX**) and 2 detection zones (**1, 2**) are possible to allow for the combination of 2 to 4 possible positions (**KT1, KX1, KT2, KX2**). For **KT, KX** sensor specifications.







Model #	Ax	Вх	ØC	ØD	w	Weight (kg)	No. of Sensing Postions (please specify when ordering)	Information area from the open grip position (green LED) X (mm)	Area information relative to the closed grip position (yellow LED) X (mm)
6002P	23	30°	38.1	60	3	0.180	1	0 or 1 $^{+0,5}_{-0}$	4 ⁺⁰ or 5
OUUZP	23	30	30.1	00	3	0.100	2	0 or 2 $^{+0,5}_{-0}$	3 ⁺⁰ or 5
6002P-C	23	30°	38.1	60	3	0.180	1	0 or 1.6 $^{+0.8}_{-0}$	7 ⁺⁰ or 8
00021 -0	23	30	30.1	00	3	0.100	2	0 or 3.2 $^{+0.8}_{-0}$	4.8 ⁺⁰ or 8
8002P	28	30°	50.8	80	3	0.400	1	0 or 1 $^{+0,5}_{-0}$	5.5 ⁺⁰ _{-0,5} or 6,5
00021	20	30	30.0	00	3	0.400	2	0 or 2 $^{+0,5}_{-0}$	4.5 ⁺⁰ _{-0,5} or 6,5
8002P-C	28	30°	50.8	80	3	0.400	1	0 or 1.5 +0,8	8.5 ⁺⁰ or 10
000ZF-0	20	30	30.0	00	3	0.400	2	0 or 3.1 +0,8	6.9 ⁺⁰ or 10
11002P	36	30°	76.2	110	3	0.900	1	0 or 1 $^{+0,5}_{-0}$	9 ⁺⁰ _{-0,5} or 10
110021	30	30	70.2	110	3	0.900	2	0 or 3 $^{+0,5}_{-0}$	7 ⁺⁰ _{-0,5} or 10
11002P-C	36	30°	76.2	110	3	0.900	1	0 or 1.5 $^{+0,8}_{-0}$	13.5 ⁺⁰ or 15
110021-0	30	30	70.2	110	,	0.300	2	0 or 4.5 +0,8	10.5 ⁺⁰ _{-0,8} or 15
14002P	45.5	165°	107.95	140	5	1.670	1	0 or 2 $^{+0,5}_{-0}$	11 ⁺⁰ or 13
140021	40.0	103	107.33	140	3	1.070	2	0 or 4 $^{+0,5}_{-0}$	9 ⁺⁰ _{-0,5} or 13
14002P-C	45.5	165°	107.95	140	5	1.670	1	0 or 3 $^{+0.8}_{-0}$	17 ⁺⁰ _{-0,8} or 20
140021-0	40.0	103	107.33	140	3	1.070	2	0 or 6.2 +0,8	13.8 ⁺⁰ or 20
16502P	65.5	165°	127	165	6	2.670	1	0 or 2 $^{+0,5}_{-0}$	13 ⁺⁰ or 15
103021	05.5	103	121	100	U	2.070	2	0 or 4 $^{+0,5}_{-0}$	11 ⁺⁰ _{-0,5} or 15
16502P-C	65.5	165°	127	165	6	2.670	1	0 or 3.3 $^{+0,8}_{-0}$	21.7 ⁺⁰ _{-0,8} or 25
10302F=G	05.5	100	127	100	U	2.070	2	0 or 7 $^{+0.8}_{-0}$	18 ⁺⁰ or 25



Option (V): Viton® Seals

Gripper with Viton® seals allows for use in high temperature environments [-30 ° C or 150 ° C].

Accessory (E): Protective Boot

The accessory (**E**) is a protective boot that fits over the gripper. It protects the mechanism and thus improves the life of the gripper in hostile environments. The accessory (**E**) causes a different location of the fingers on the jaws as compared to the standard installation. Before attaching the boot, perform the following steps:

- 1. Mount gripper to machine.
- 2. Slip boot over gripper and secure in place.
- 3. Attached fingers to jaws using finger adapter.

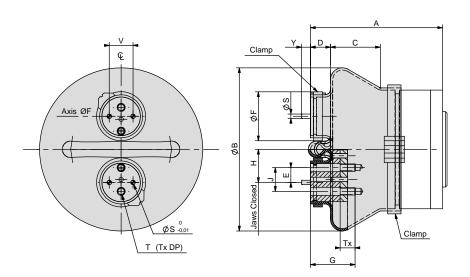
Depending on the environment 2 types of envelopes are available:

- (E) Envelope of black or brown PVC for environmental grinding with emery presence.
- (E3) red envelope containing KEVLAR fireproof silicone environment for hot chips and weld spatter.

The accessory (E) is incompatible with the accessory (SD)

Model Code	Order #	Model	A	В	C	D	E	F	G	Н	J	K	S	T	TX	V	Y
E	ER62P	6002P &	88	98	35	13.5	8	29	29	17.5	13		3	M4	9	13	6
E3	E3R62P	6002P-C	00	30	33	13.3	U	23	23	17.5	13	_	3	IVI	3	13	0
E	ER82P	8002P &	89	110	34	13.5	10	33	30	22.3	16		3	M5	10	16	6
E3	E3R82P	8002P-C	09	110	34	13.3	10	JJ	30	22.3	10	_	3	IVIO	10	10	0
E	ER112P	11002P &							ç.	e drawi	na						
E 3	E3R112P	11002P-C							36	e urawi	iiy						
E	KP-311	14002P &	140	185	50	18	12	55	34	19.5	24	18	5	M8	14		8
E3	KP-313	14002P-C	P-C 143	100	50	10	12	55	34	19.5	24	10	5	IVIO	14	1	0
E	KP-314	16502P &	170	220	70	16	14	67	37	24	28	23	6	M10	19		8
E 3	KP-316	16502P-C	172	220	70	10	14	07	3/	19	28	23	O	IVITU	19	ı	ď

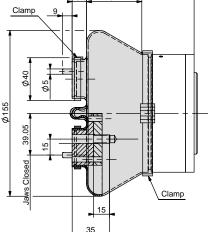
6002P 8002P



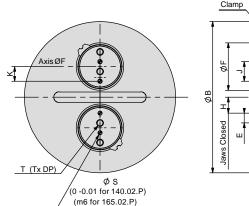


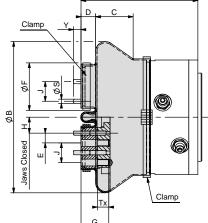
11002P

Axis Ø40



14002P 16502P





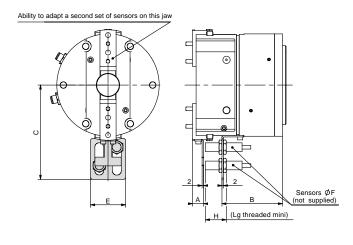
Accessory (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (SD) includes: 1 sensor bracket, 1 flag and screws. Sensors are not provided.

NOTES:

To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (**SD**).



Order #	Model	A	В	C	E	F	Н
SD60-80P	6002P & 6002P-C	20	35	67	32	8	35
SD60-80P	8002P & 8002P-C	19	34	77	32	8	35
SD110P	11002P & 11002P-C	19.5	45	97	32	8	35
OSMK-114	14002P & 14002P-C	15	83	129	48	12	28.5
OSMK-115	16502P & 16502P-C	29	96	147	48	12	33

PREGISDESIGN NOTES

4.1 PRECISION 2P

Parallel Gripper-CP Square Jaw Series

Compact and Powerful

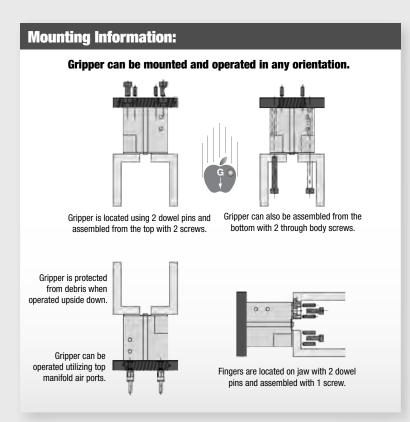
This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, inductive sensors and Viton® seals) allow these grippers to be used in a number of applications.

Harsh Environments

Shielded design repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.



Technical Specifications: Pneumatic Specifications

Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate:

Double Acting 4-way, 2-position
Single acting (Option RE or RI) 3-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better
Air Lubrication Not Necessary*

Temperature Operating Range

Buna-N Seals (standard) -35°~80° C
Viton® Seals (optional) -30°~150° C

Application Restrictions

Expected Life
Normal Application
w/ Preventative Maintenance
Field Repairable
Seal Repair Kits Available

3 million cycles 6 million cycles* Yes Yes

3-10 bar

Double Acting

Buna-N

*Addition of lubrication will greatly increase service life

Product Features

Multiple Air Ports Side or top air ports (top ports require 0-ring)

Angular Finger Jaws Option (-Q) Quality Components
Body made from aluminum alloy with
Teflon™ impregnated hardcoat anodize. Other essential parts of the gripper are made of hardened and precision ground steel

Inductive Sensors

Accessory (SD) for control jaw position. Support for two sensors. adjustable screen and spacer.

Viton® Seals Optional Viton® seals (-V) for high temperatures

Optional

Spring Assist
Optional spring assist retains
the component should the air supply fail, to assist the gripper for internal (-RE) or external (-RI) gripping, or in single acting mode

Sheilded Design

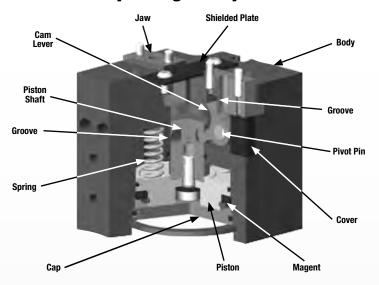
Gripper body is shielded to repel chips and other particulate from internal drive mechanism

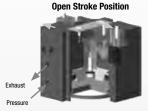
Optional: the front (push) or backward (pulling).

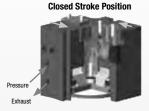
Standard and Extended Stroke (-C) Each model of gripper is available in two stroke lengths

Magnetic Sensing Gripper is pre-equipped with 2 magnets for sensors, adjustable in grooves (for sensing the position of the jaw).

OperatingPrinc iple







- A double-acting piston is connected to the piston shaft at its end with a driving groove. The piston is pre-fitted with a ring magnet for sensor detection.
- Levers pivot in the body about an axis of articulation. Their two heads agree precisely on one side in the groove of the small piston, the other in a groove cut in each jaw holder.
- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

Style: CP Parallel Gripper



Model	CP-1	CP-1-C
Total Stroke:	4 mm	6 mm
Force at 6bar:1	88 N	60 N
Force w/o air:2	15 N	10 N
Weight:	0.09 kg	0.09 kg

See Pages 1.60 & 1.61

Style: CP Parallel Gripper



Model	CP-2	CP-2-C
Total Stroke:	6 mm	9 mm
Force at 6bar:1	238 N	161 N
Force w/o air:2	43 N	29 N
Weight:	0.21 kg	0.20 kg

See Pages 1.62 &1.63

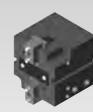
Style: CP Parallel Gripper



Model	CP-3	CP-3-C
Total Stroke:	10 mm	16 mm
Force at 6bar:1	677 N	407 N
Force w/o air:2	161 N	97 N
Weight:	0.45 kg	0.47 kg

See Pages 1.64 &1.65

Style: CP Parallel Gripper



Model	CP-4	CP-4-C
Total Stroke:	13 mm	20 mm
Force at 6bar:1	1016 N	665 N
Force w/o air:2	222 N	145 N
Weight:	0.73 kg	0.75 kg

See Pages 1.66 & 1.67

Style: CP Parallel Gripper



Model	CP-5	CP-5-C
Total Stroke:	18 mm	27 mm
Force F _{6+R} :	1591 N	1081 N
Force F _{0+R} :	322 N	219 N
Weight:	1.25 kg	1.27 kg

See Pages 1.68 &1.69

Style: CP Parallel Gripper



Model	CP-6	CP-6-C
Total Stroke:	24 mm	32 mm
Force at 6bar:1	2749 N	2092 N
Force w/o air:2	711 N	541 N
Weight:	2.50 kg	2.56 kg

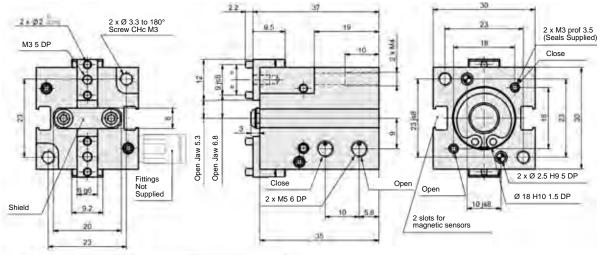
See Pages 1.70 &1.71

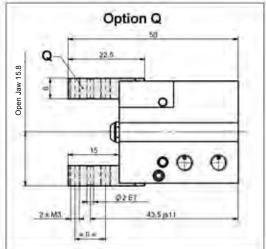
OPTIONS & ACCESSOIRES

See Page **1.72**

- 1. Force with spring and air at 6bar
- 2. Force with spring without air



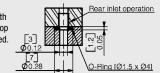




Specifications CP-1 Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 88 N Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 15 N **Total Stoke** 4 mm Weight 0.09 kg 2-10 bar Pressure Range Pressure Range with Springs 2.5-10 bar Ø Cylinder Bore 16 mm Displacement 0.7 cm Acuation (open / close) 0.06 s / 0.06 s ± 0.025 Repeatability 1. Force with spring and air at 6bar

Grippers are supplied with open side air ports and top manifold air ports plugged Top manifold sealing dimensions shown.

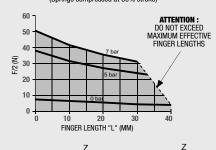
2. Force with spring without air



Loading Information

How to Order: (Order Accessories separately from Basic Model)

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)



	Z C T Mx	F/2 •	Z Mz X F/2
oading Capacity*		Static	Dynamic
Maximum Tensile T		110 N	10 N
Maximum Compresive C		190 N	10 N

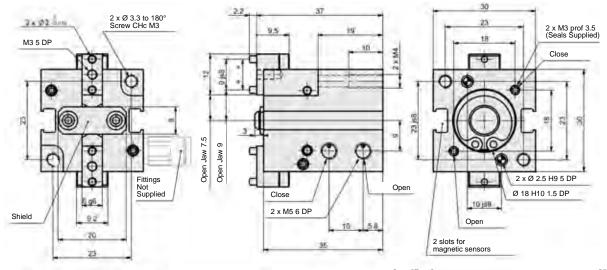
Maximum Moment Mx 1 Nm 0.2 Nm 2 Nm Maximum Moment My 0.4 Nm Maximum Moment Mz 2 Nm 0.4 Nm * The Capacities are per set of jaws and are not simultaneous.

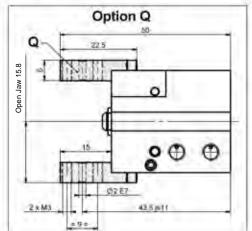


SENSOR ACCESSORIES ORDER # OTY/UNIT PNP Sensor with 0.3m Output Cable with 90° with M8 connector D1 1 or 2 PNP Sensor with 0.3m Output Cable with M8 connector **D4** 1 or 2 Quick Disconnect 2 Meter Cable Length CABL-010 1 or 2 **PNEUMATIC ACCESSORIES** Standard Seal Repair Kit SCP1 1 SCP1V Viton® Seal Repair Kit Repair Kit (screws, springs, standard seals) KSCP1 1 Repair Kit (screws, springs, seals Viton) KSCP1V

Accessories: see page 70



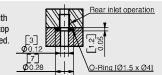




CP-1-C Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 60 N Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 10 N Total Stoke $6 \, \text{mm}$ Weight 0.09 kg 2-10 bar Pressure Range Pressure Range with Springs 2.5-10 bar Ø Cylinder Bore 16 mm Displacement 0.7 cm $0.06 \, s \, / \, 0.06 \, s$ Acuation (open / close) Repeatability $\pm~0.025$

1. Force with spring and air at 6bar 2. Force with spring without air

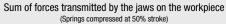
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

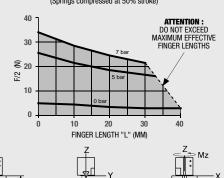


Loading Information

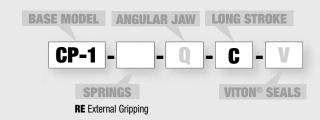
* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)





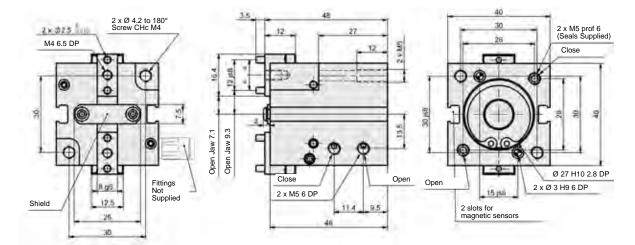
<u> </u>	₩ IVIX		✓ My
Loading Capacity*		Static	Dynamic
Maximum Tensile T		110 N	8 N
Maximum Compresive C		190 N	8 N
Maximum Moment Mx		1 Nm	0.2 Nm
Maximum Moment My		2 Nm	0.3 Nm
Maximum Moment Mz		2 Nm	0.3 Nm

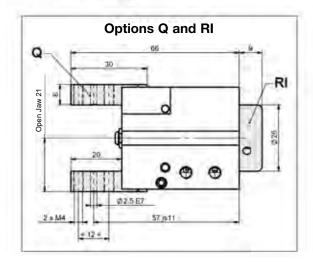


SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP1	1
Viton® Seal Repair Kit	SCP1V	1
Repair Kit (screws, springs, standard seals)	KSCP1	1
Repair Kit (screws, springs, seals Viton)	KSCP1V	1
Accessories: see page 70		

PARALLEL GRIPPER CP-2 COMPACT GRIPPER SERIES



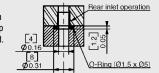




Specifications	CP-2
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	238 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	43 N
Total Stoke	6 mm
Weight	0.21 kg
Pressure Range	2-10 bar
Pressure Range with Springs	2.5-10 bar
Ø Cylinder Bore	25 mm
Displacement	2.7 cm ³
Acuation (open / close)	0.06 s / 0.06 s
Repeatability	± 0.025
1. Force with spring and air at 6bar	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

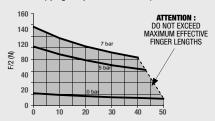
2. Force with spring without air

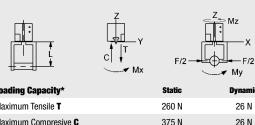


Loading Information

How to Order: (Order Accessories separately from Basic Model)

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)

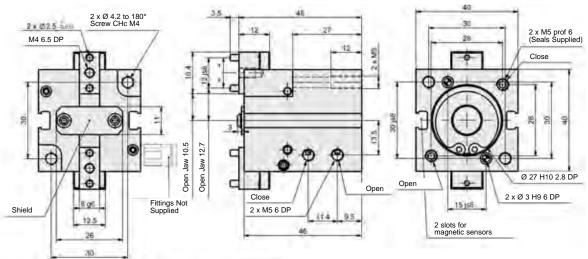


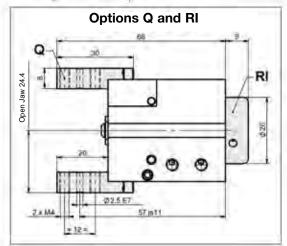


UU	✓ Mx	✓ My	
Loading Capacity*	Stati	c Dynamic	;
Maximum Tensile T	260 I	N 26 N	
Maximum Compresive C	375	N 26 N	
Maximum Moment Mx	5 Nn	0.9 Nm	
Maximum Moment My	8 Nn	1.5 Nm	
Maximum Moment Mz	8 Nn	1.5 Nm	
*The Capacities are per set of laws	and are not simultaneous.		

BASE MODEL	ANGULAR JAW	VITON® SEALS
CP-2	Q	SD - V
RE External Gripping RI Internal Gripping	PRINGS SE	INSOR MOUNTS

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP2	1
Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP2	1
Viton® Seal Repair Kit	SCP2V	1
Repair Kit (screws, springs, standard seals)	KSCP2	1
Repair Kit (screws, springs, seals Viton)	KSCP2V	1
Accessories: see page 70		



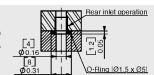


Specifications	CP-2-C
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	161 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	29 N
Total Stoke	9 mm
Weight	0.20 kg
Pressure Range	2-10 bar
Pressure Range with Springs	2.5-10 bar
Ø Cylinder Bore	25 mm
Displacement	2.7 cm ³
Acuation (open / close)	0.06 s / 0.06 s
Repeatability	± 0.025

Force with spring and air at 6bar
 Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

ANGULAR JAW



LONG STROKE

Loading Information

Maximum Moment Mx

Maximum Moment My

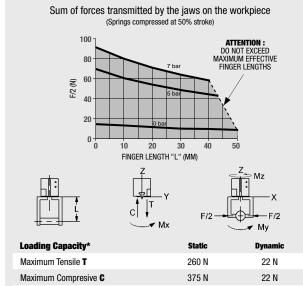
Maximum Moment Mz

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)

BASE MODEL

CD_2



4 Nm

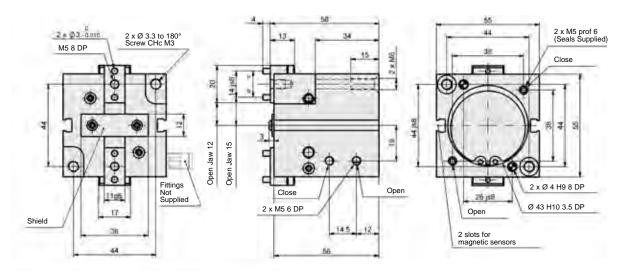
8 Nm

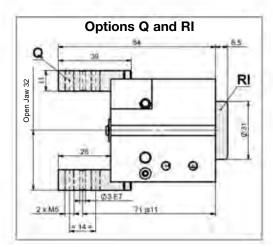
8 Nm

0.7 Nm

1.2 Nm 1.2 Nm

E External Gripping SPRINGS SENSOR MOUNTS	VITON® SI	EALS
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP2	1
Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP2	1
Viton® Seal Repair Kit	SCP2V	1
Repair Kit (screws, springs, standard seals)	KSCP2	1
Repair Kit (screws, springs, seals Viton)	KSCP2V	1
Accessories: see page 70		



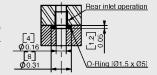


Specifications	CP-3
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	677 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	161 N
Total Stoke	10 mm
Weight	0.45 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	40 mm
Displacement	11.7 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025

1. Force with spring and air at 6bar 2. Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

ANGULAR JAW



VITON® SEALS

Loading Information

Maximum Moment Mx

Maximum Moment My

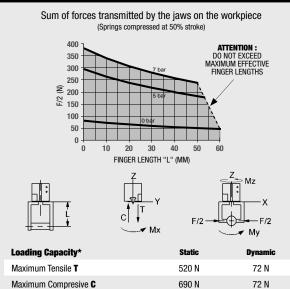
Maximum Moment Mz

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)

BASE MODEL

CP-3 -



11 Nm

18 Nm

17 Nm

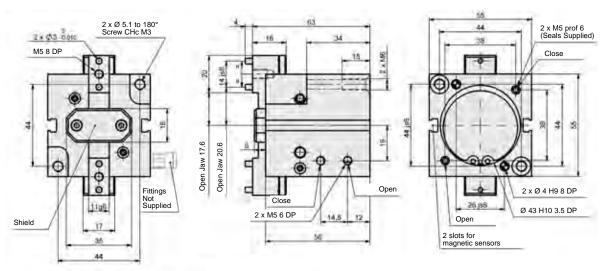
3.5 Nm

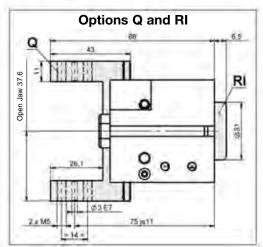
6 Nm

6 Nm

RE External Gripping RI Internal Gripping SPRINGS	SENSOR MOUNTS	
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP3	1
Inductive PNP Sensor with M8 Connector	0ISP-011-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP3	1
Viton® Seal Repair Kit	SCP3V	1
Repair Kit (screws, springs, standard seals)	KSCP3	1
Repair Kit (screws, springs, seals Viton)	KSCP3V	1
Accessories: see page 70		

PARALLEL GRIPPER CP-3-C COMPACT GRIPPER SERIES





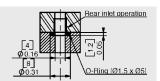
Specifications	GP-3-G
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	407 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	97 N
Total Stoke	16 mm
Weight	0.47 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	40 mm
Displacement	11.7 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025

1. Force with spring and air at 6bar 2. Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing

dimensions shown.

ANGULAR JAW



LONG STROKE

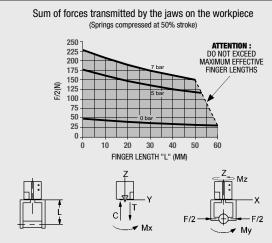
Loading Information

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)

BASE MODEL

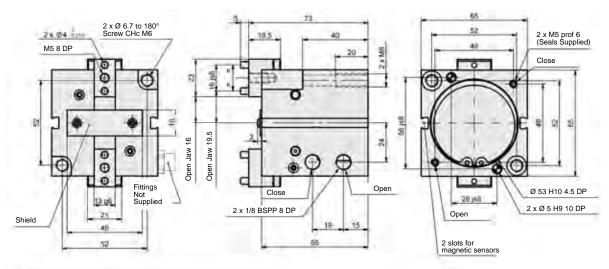
CP-3 -

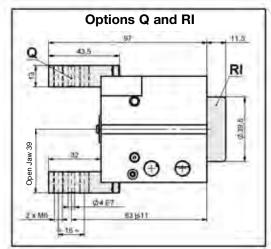


<u> </u> <u>'</u>	c∏	F/2 → F/2 My	
Loading Capacity*		Static	Dynamic
Maximum Tensile T		500 N	55 N
Maximum Compresive C		675 N	55 N
Maximum Moment Mx		9 Nm	2.5 Nm
Maximum Moment My		16 Nm	4 Nm
Maximum Moment Mz		17 Nm	4 Nm

RE External Gripping	WITOUR C	-ALC
RI Internal Gripping SPRINGS SENSOR MOUNTS	VITON® SI	:ALS
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP3	1
Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP3	1
Viton® Seal Repair Kit	SCP3V	1
Repair Kit (screws, springs, standard seals)	KSCP3	1
Repair Kit (screws, springs, seals Viton)	KSCP3V	1
Accessories: see page 70		





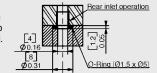


Specifications	CP-4
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	1016 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	222 N
Total Stoke	13 mm
Weight	0.73 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	50 mm
Displacement	24.2 cm ³
Acuation (open / close)	0.07 s / 0.07
Repeatability	± 0.025

Force with spring and air at 6bar
 Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

BASE MODEL ANGULAR JAW VITON® SEALS



s

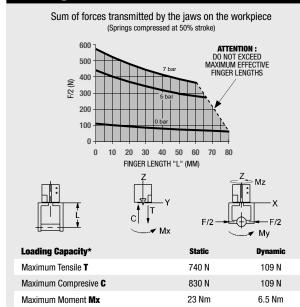
Loading Information

Maximum Moment My

Maximum Moment Mz

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)



35 Nm

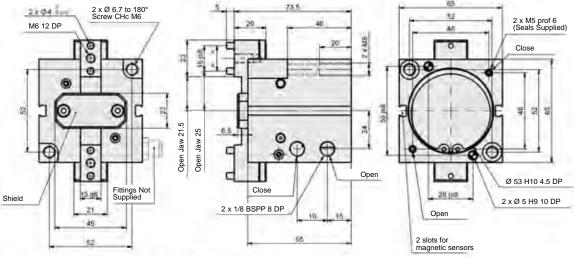
25 Nm

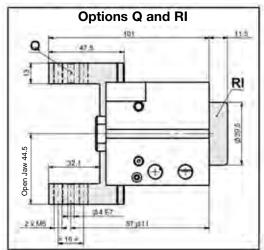
10 Nm

8 Nm

CP-4 - Q	- SD - V	
RE External Gripping RI Internal Gripping SPRINGS	SENSOR MOUNTS	
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP4	1
Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP4	1
Viton® Seal Repair Kit	SCP4V	1
Repair Kit (screws, springs, standard seals)	KSCP4	1
Repair Kit (screws, springs, seals Viton)	KSCP4V	1
Accessories: see page 70		

PARALLEL GRIPPER CP-4-C **COMPACT GRIPPER SERIES**

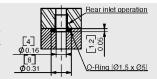




Specifications	CP-4-C
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	665 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	145 N
Total Stoke	20 mm
Weight	0.75 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	50 mm
Displacement	24.2 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025

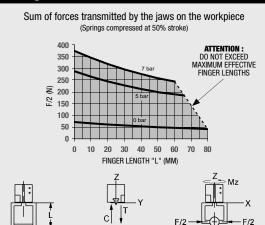
1. Force with spring and air at 6bar 2. Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

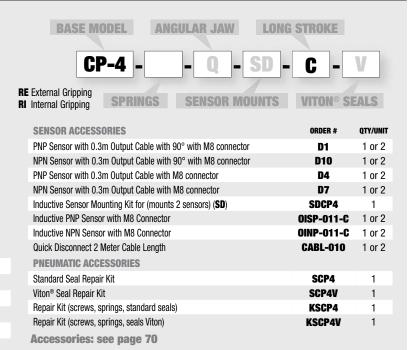


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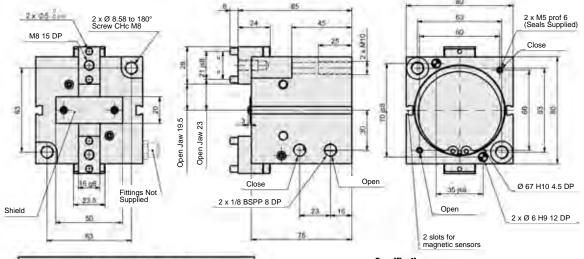
How to Order: (Order Accessories separately from Basic Model)

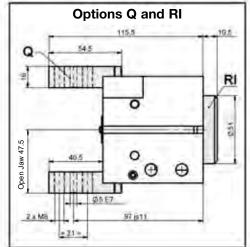


		~· ····y
Loading Capacity*	Static	Dynamic
Maximum Tensile T	710 N	89 N
Maximum Compresive C	800 N	89 N
Maximum Moment Mx	18 Nm	4.7 Nm
Maximum Moment My	30 Nm	7.6 Nm
Maximum Moment Mz	25 Nm	7.6 Nm
* The Capacities are per set of jaws and are not simultaneous.		









Specifications CP-5 Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 1591 N Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 322 N Total Stoke 18 mm Weight 1.25 kg 2-10 bar Pressure Range 3-10 bar Pressure Range with Springs Ø Cylinder Bore 63 mm Displacement 53.5 cm 0.09 s / 0.09 s Acuation (open / close) Repeatability ± 0.025

1. Force with spring and air at 6bar 2. Force with spring without air

Rear inlet operation Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown. O-Ring [Ø1.5 x Ø5]

VITON® SEALS

Loading Information

Maximum Tensile T

Maximum Compresive C

Maximum Moment Mx

Maximum Moment My

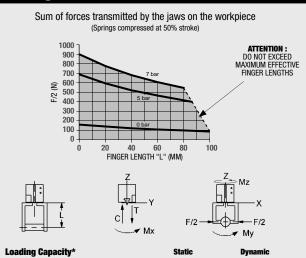
Maximum Moment Mz

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)

BASE MODEL

CP-5



830 N

940 N

27 Nm

44 Nm

30 Nm

169 N

169 N

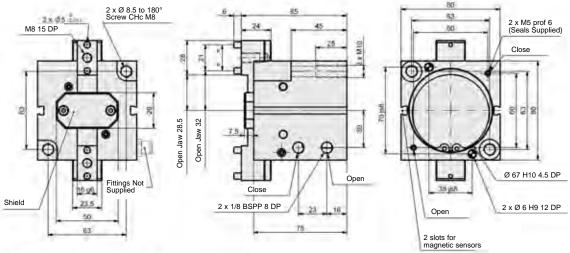
9 Nm

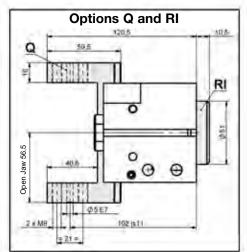
14 Nm

10 Nm

RI Internal Gripping SPRINGS	SENSOR MOUNTS	
SENSOR ACCESSORIES	ORDER #	Q.
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	-
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP5	
Inductive PNP Sensor with M12 Connector	OISP-017-C	1
Inductive NPN Sensor with M12 Connector	OINP-017-C	•
Quick Disconnect 2 Meter M12 Cable Length	CABL-014	-
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP5	
Viton® Seal Repair Kit	SCP5V	
Repair Kit (screws, springs, standard seals)	KSCP5	
Repair Kit (screws, springs, seals Viton)	KSCP5V	
Accessories: see page 70		

ANGULAR JAW

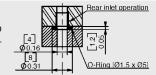




Specifications	CP-5-C
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	1081 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	219 N
Total Stoke	27 mm
Weight	1.27 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	63 mm
Displacement	53.5 cm ³
Acuation (open / close)	0.09 s / 0.09 s
Repeatability	± 0.025
1. Force with spring and air at 6bar	

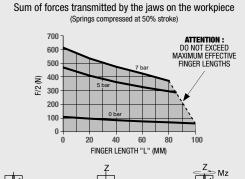
2. Force with spring without air

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Loading Information

How to Order: (Order Accessories separately from Basic Model)

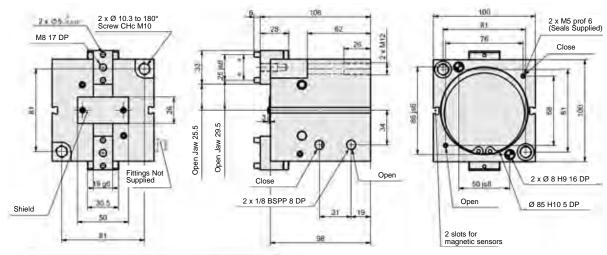


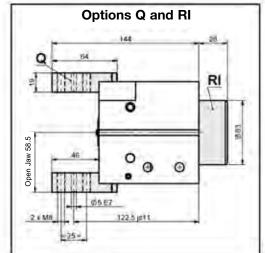
	FINGER LENGTH "	L" (MM)			
	Z Y C	F/2 —•	Z Mz X F/2		
oading Capacity*		Static	Dynamic		
laximum Tensile T		820 N	144 N		

		•
Loading Capacity*	Static	Dynamic
Maximum Tensile T	820 N	144 N
Maximum Compresive C	930 N	144 N
Maximum Moment Mx	22 Nm	7 Nm
Maximum Moment My	40 Nm	13 Nm
Maximum Moment Mz	30 Nm	10 Nm
* The Capacities are per set of jaws and are not simultaneo	us.	

BASE MODEL	ANGULAR JAW	LONG STROKE
CP-5]-	SD - C - V
RE External Gripping RI Internal Gripping	RINGS SENSOR M	OUNTS VITON® SEALS

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP5	1
Inductive PNP Sensor with M8 Connector	OISP-017-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-017-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-014	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP5	1
Viton® Seal Repair Kit	SCP5V	1
Repair Kit (screws, springs, standard seals)	KSCP5	1
Repair Kit (screws, springs, seals Viton)	KSCP5V	1
Accessories: see page 70		

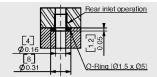




Specifications CP-6 Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 2749 N Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 711 N Total Stoke 24 mm Weight 2.50 kg Pressure Range 2-10 bar 3.5-10 bar Pressure Range with Springs Ø Cylinder Bore 80 mm Displacement 114.8 cm³ Acuation (open / close) 0.12 s / 0.12 s Repeatability ± 0.025

1. Force with spring and air at 6bar 2. Force with spring without air

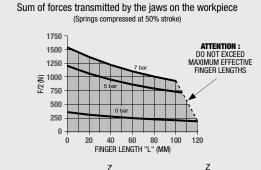
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



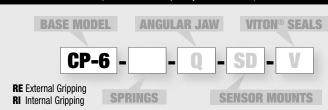
Loading Information

* The Capacities are per set of jaws and are not simultaneous.

How to Order: (Order Accessories separately from Basic Model)

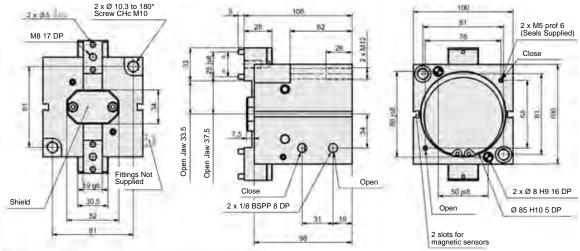


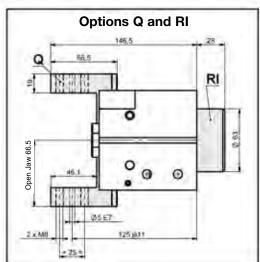
	Z T T C	F/2 - Mz		
Loading Capacity*		Static	Dynamic	
Maximum Tensile T		1375 N	209 N	
Maximum Compresive C		1500 N	209 N	
Maximum Moment Mx		48 Nm	16 Nm	
Maximum Moment My		72 Nm	24 Nm	
Maximum Moment Mz		68 Nm	22 Nm	



SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP6	1
Inductive PNP Sensor with M12 Connector	OISP-017-C	1 or 2
Inductive NPN Sensor with M12 Connector	OINP-017-C	1 or 2
Quick Disconnect 2 Meter M12 Cable Length	CABL-014	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP6	1
Viton® Seal Repair Kit	SCP6V	1
Repair Kit (screws, springs, standard seals)	KSCP6	1
Repair Kit (screws, springs, seals Viton)	KSCP6V	1
Accessories: see page 70		

PARALLEL GRIPPER CP-6-C COMPACT GRIPPER SERIES

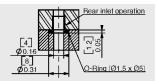




Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	2092 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	541 N
Total Stoke	32 mm
Weight	2.56 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3.5-10 bar
Ø Cylinder Bore	80 mm
Displacement	114.8 cm ³
Acuation (open / close)	0.12 s / 0.12 s
Repeatability	± 0.025

1. Force with spring and air at 6bar 2. Force with spring without air

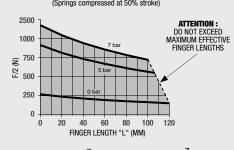
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Loading Information

How to Order: (Order Accessories separately from Basic Model)





	(141141)		
	Y C T Mx	F/2 —	X Mz X F/2
oading Capacity*		Static	Dynamic

		•
Loading Capacity*	Static	Dynamic
Maximum Tensile T	1340 N	279 N
Maximum Compresive C	1450 N	279 N
Maximum Moment Mx	42 Nm	14 Nm
Maximum Moment My	70 Nm	23 Nm
Maximum Moment Mz	64 Nm	21 Nm
* The Capacities are per set of jaws and are not simultaneous.		

BASE MODEL AN	IGULAR JAW	LONG STROP	(E
CP-6 -	-0-	SD - C	- V
RE External Gripping			

SPRINGS SENSOR MOUNTS VITON® SEALS RI Internal Gripping

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP6	1
Inductive PNP Sensor with M8 Connector	OISP-017-C	1 or 2
Inductive NPN Sensor with M8 Connector	OINP-017-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-014	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP6	1
Viton® Seal Repair Kit	SCP6V	1
Repair Kit (screws, springs, standard seals)	KSCP6	1
Repair Kit (screws, springs, seals Viton)	KSCP6V	1
Accessories: see page 70		



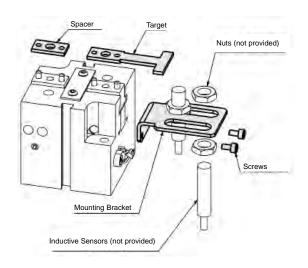
Accessories (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (**SD**) includes: 1 sensor bracket, 1 flag and screws. **Sensors are not provided.**

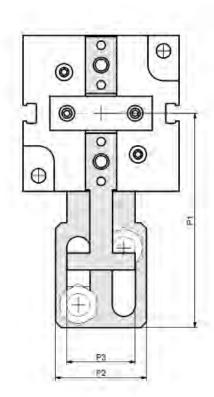
NOTES:

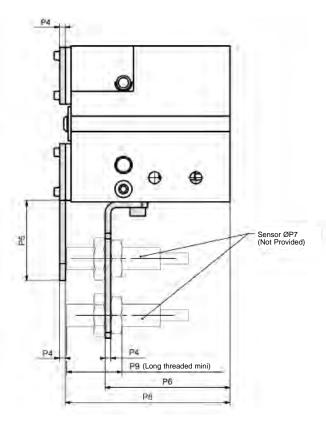
To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (SD).



MODELS	P1	P2	Р3	P4	P5	P6	P7	P8	P9	Order #
CP-1	accessory not available									
CP-1-C					acce	ssory not	availabl	е		
CP-2	58	32	24	2	21.9	35.5	8	48	18	SDCP2
CP-2-C	58	32	24	2	21.9	35.5	8	48	18	SDCP2
CP-3	75.5	32	24	2	28.2	44	8	58	20	SDCP3
CP-3-C	75.5	32	24	2	28.2	44	8	63	24	SDCP3
CP-4	80.5	32	24	2	27	52.5	8	73	26	SDCP4
CP-4-C	80.5	32	24	2	27	52.5	8	73.5	27	SDCP4
CP-5	108	43	28	2.5	38	60	12	85	33	SDCP5
CP-5-C	108	43	28	2.5	38	60	12	85	33	SDCP5
CP-6	118	43	28	2.5	39	76.5	12	108	39	SDCP6
CP-6-C	118	43	28	2.5	39	76.5	12	108	39	SDCP6





Option (V): Viton® Seals

Gripper with Viton® seals allows for use in high temperature environments [-30 ° C or 150 ° C].



REGIDESIGN NOTES

Parallel Grippers-DPP DIRECTCONNECT** **Precision Series**

- Multiple Mounting Locations: All sizes have DIRECTCONNECT top mounting and DIRECTCONNECT thru hole mounting on back side.
- Multiple Air Port Locations: Multiple airport locations: tapped air ports on front, top and both sides are standard. Top port is also manifold ready.
- Sensing options: Magneto resistive or inductive proximity sensors available. Up to 4 positions can be sensed.
- Precision applications: Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.
- Longer finger applications: Rigid design and low friction design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight & size.

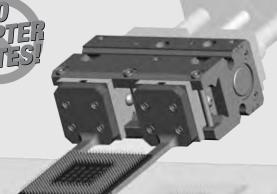
Delicate part handling:

Low friction mechanism allows for repeatable gripping forces for holding delicate parts. Grip force is easily adjusted by regulating air pressure.

Non-synchronous motion:

Non-synchronous option provides independent jaw motion allowing the gripper to pick or place at a point other than its center.

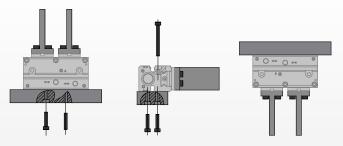
• Spring return: Optional double acting spring assist for increased force or fail-safe operation or operate as a single acting to open and to spring closed.



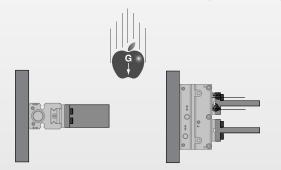


Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with H7 dowel pins for accuracy



Fingers attach to jaws with screws and locate by key slot and/or H7 dowel pins

Technical Specifications:

Pneumatic Specifications
Pressure Operating Range
Standard

-C Spring Closed Option Cylinder Type

Dynamic Seals Valve Required to Operate

Imperial Metric 5-100 psi 0.3-7 bar 20-100 psi 1.5-7 bar **Double Acting or** Single Acting Spring Return or **Double Acting Spring Assist** Internally Lubricated Buna-N 4-way, 2-position for Double Acting

3-way, 2-position for Single Acting

40 Micron or Better

Low Moisture Content (dry)

5 million cycles

10+ million cycles*

Yes

-30°~180° F

-20°~250° F

Not Necessary*

-35°~80° C

-30°~120° C

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

Temperature Operating Range

Buna-N Seals (standard) Viton® Seals (optional)

Maintenance Specifications[†]

Expected Life Normal Application w/Preventative Maintenance Field Repairable

Seal Repair Kits Available

Application Restrictions

- · Dirty or gritty environments
- . Machine operations generating chips
- Environments with loose particulate
- Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life †See Maintenance Section

Product Features

Excellent Accuracy

Excellent parallelism and accuracy between gripper mounting surface and iaw surfaces

Accessory

Mounting Slots

For Magneto Resistive

and Inductive sensors

(Sensors sold

separately)

Superior

Jaw **Support** Jaws are

supported using

"Dual-V" roller

bearing design

Dowel Holes

H7 dowel pin holes

in body and laws.

key slot for better

finger alignment

Top Manifold

Air Ports

Eliminates the

need for airlines

Hardened

Plated Jaws

For wear resistance

and longer life

Standard Purge/ Scavenge Port

Used with a vacuum for clean room environments or positive pressure for harsh environments and jaw surfaces

Hard Coat Anodize

One piece, aircraft quality

aluminum body, has hard-coat

anodize 60 RC with Teflon

impregnation

"Dual-V"

Roller Bearings

Provide low friction motion

and are preloaded for maximum

support and zero side play

Viton Seals

Available for high

temperature applications

Shielded design repels contamination from penetrating the "Dual-V" roller bearings

Shielded Design

Multiple Air Port Locations 4 standard locations; front,

top and both sides

DIRECTCONNECT

Mounting Patterns DIRECTCONNECT™ tapped and dowel mounting surfaces on top and side of body.

Optional Spring Assist For close stroke

Self Lubricating **Dynamic Seals** (Buna-N only)

Adjustable Pre-load Screws

Allows for adjustment of preload on roller bearings

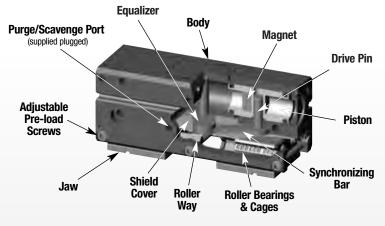
High Grip Force

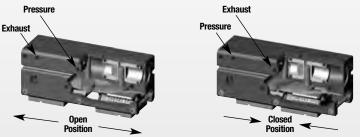
With respect to weight due to extremely efficient drive mechanism

Capable of sensing both jaws in the open and closed positions (up to 4 sensors can be used for multi-position sensing) Sensor magnets on pistons come standard for Magneto Resistive Sensing

Multiple Sensor Capabilities

Operating Principle





- · Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- · Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

Designed, manufactured and assembled in the USA

Style -DPP Parallel Gripper

Size -10M-06

Style: Stroke: 10M-06 6.4 mm 0.25 in. 25 lbs. 0.35 lbs. **Grip Force:** Weight: 0.16 Ka

Size -10M-12

12.7 mm 0.50 in. Stroke: Grip Force: 25 lbs. Weight: 0.45 lbs 0.45 lbs

Style -DPP Parallel Gripper

14M-15 15.9 mm 0.63 in. **Grip Force:** 45 lbs. **Weight:** 1.05 lbs 200 N 1.05 lbs. 0.48 Kg

Style:

Size -14M-25



14M-25 25.4 mm 200 N 1.00 in. 1.25 lbs. 0.57 Kg

Style -DPP Parallel Gripper

Size -20M-25

Style: 20M-25 Stroke: 1.00 in. 25.4 mm Grip Force: 95 lbs. Weight: 2.25 lbs 423 N 2.25 lbs.

See Page

Size -20M-38

Style: 20M-38 Grip Force: 95 lbs. Weight: 3.10 lb. 38.1 mm 423 N



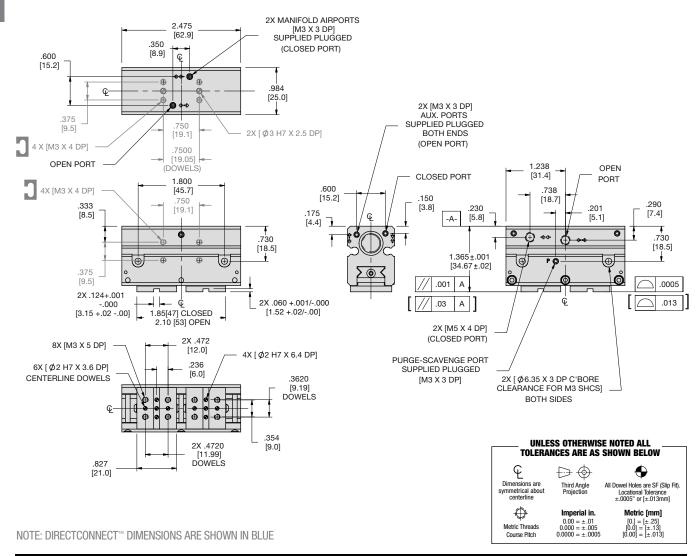
See

PARALLEL GRIPPERS DPP-10M-06 DIRECTCONNECT PRECISION SERIES





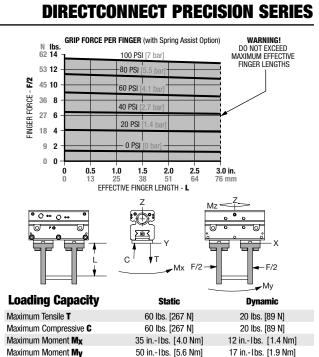
1.76



How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES** ORDER # OTY/UNIT **BASIC MODEL VITON SEALS** Inductive Sensor Mounting Kit (Mounts 2 sensors) **OSMK-119** 1 or 2 NPN Inductive Sensor (with Qk. Disc.)* **OISN-014** DPP-10M-06 PNP Inductive Sensor (with Qk. Disc.)* **OISP-014** 2. 3 or 4 NPN Magneto Resistive Sensor (with Qk. Disc.)*1 OHSN-017 **OHSP-017** PNP Magneto Resistive Sensor (with Qk. Disc.)*1 **NON-SYNCHRONOUS** NPN Magneto Resistive Sensor 90° (with Qk. Disc.)*1 **OHSN-011** 1, 2, 3 or 4 OHSP-011 PNP Magneto Resistive Sensor 90° (with Qk. Disc.)* 1, 2, 3 or 4 Spring Closed Quick Disconnect Cable (2 meters long)* CABL-010 1, 2, 3 or 4 Leave Blank. No Spring Option (standard) CABL-013 Quick Disconnect Cable (5 meters long)* 1, 2, 3 or 4 **JAW SYNCHRONIZATION** NS Non-Synchronous Operation **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Leave Blank for Synchronous (standard) **SLKT-343** Seal Repair Kit (Standard Buna-N) 1 **VITON® SEALS V** High Temperature Viton Seals Seal Repair Kit (Viton) SLKT-343V 1 Manifold Seal Kit (Viton® only) SLKT-241V 1 Adjustable Flow Control-M3 Elbow-3MM OD Tube Push-in Style **VLVF-018** 1 or 2 Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style VLVF-008 1 or 2 **OFSV-004** Fail Safe Valve- M5 1 *Sensor and cable sold separately. †Piston Magnet standard SAMPLE ORDER: DPP-10M-06-C-NS-V Ex: DPP-10 Metric Gripper, 6mm Stroke, Spring Closed, Non Synchronous, Viton Seals



DPP-10M-06 Total Rated Grip Force **F** @ 100 psi, 7 bar*................ 27 lbs. 120 N 0.25 in. 6.4 mm 0.16 Kg Pressure Range (Without Springs) 5-100 psi 0.3-7 bar Pressure Range (With Springs) 20-100 psi 1.4-7 bar Cylinder Bore (2X) 0.406 in. 10.3 mm 0.032 in³. Displacement 0.5 cm³ Temperature Range: Standard Seals -30°~180° F -35°~80° C Viton® Seals -20°~250° F -30°~150° C Actuation (Without Spring/With Spring)...... 0.10/0.11 sec. 0.10/0.11 sec. Accuracy ±0.001 in. $\pm 0.03 \; \text{mm}$ ±0.01 mm Repeatability...... ±0.0005 in. Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting..... 4-way, 2-position *With Springs

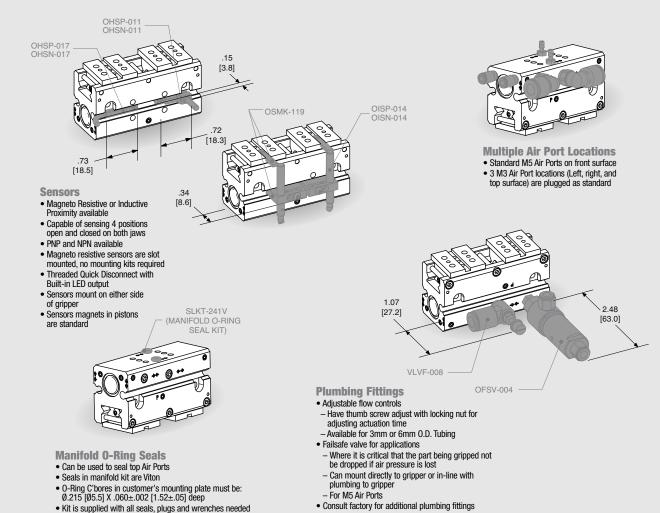


35 in.-Ibs. [4.0 Nm]

12 in.-Ibs. [1.4 Nm]

PARALLEL GRIPPERS DPP-10M-06

Accessory Mounting Technical Data



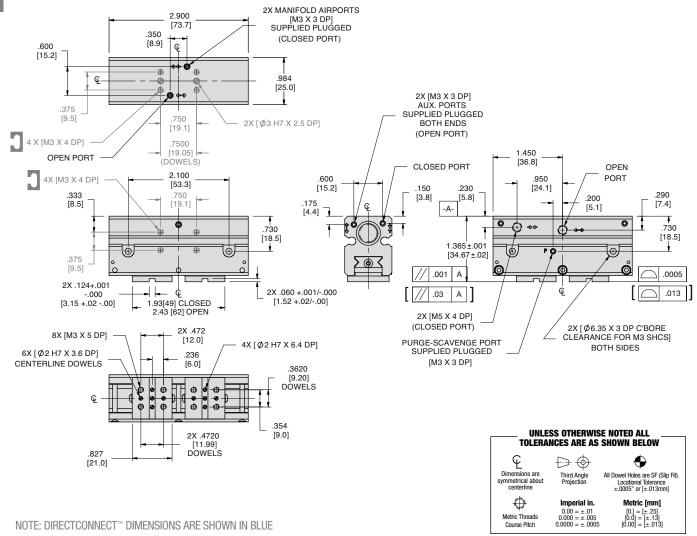
Maximum Moment Mz

Note: Capacities are per set of jaws and are not simultaneous.

PARALLEL GRIPPERS DPP-10M-12 DIRECTCONNECT PRECISION SERIES







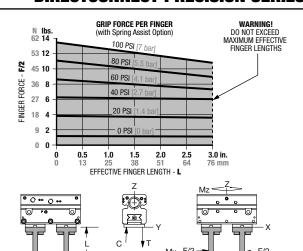
How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES** ORDER # OTY/UNIT **BASIC MODEL VITON SEALS** Inductive Sensor Mounting Kit (Mounts 2 sensors) **OSMK-119** 1 or 2 **OISN-014** NPN Inductive Sensor (with Qk. Disc.)* DPP-10M-1 PNP Inductive Sensor (with Qk. Disc.)* **OISP-014** 2. 3 or 4 NPN Magneto Resistive Sensor (with Qk. Disc.)*1 OHSN-017 **OHSP-017** PNP Magneto Resistive Sensor (with Qk. Disc.)*1 **NON-SYNCHRONOUS** NPN Magneto Resistive Sensor 90° (with Qk. Disc.)*1 **OHSN-011** 1, 2, 3 or 4 OHSP-011 PNP Magneto Resistive Sensor 90° (with Qk. Disc.)* 1, 2, 3 or 4 Spring Closed Quick Disconnect Cable (2 meters long)* CABL-010 1, 2, 3 or 4 Leave Blank. No Spring Option (standard) CABL-013 Quick Disconnect Cable (5 meters long)* 1, 2, 3 or 4 **JAW SYNCHRONIZATION** NS Non-Synchronous Operation **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Leave Blank for Synchronous (standard) **SLKT-343** Seal Repair Kit (Standard Buna-N) 1 **VITON® SEALS V** High Temperature Viton Seals Seal Repair Kit (Viton) SLKT-343V 1 Manifold Seal Kit (Viton® only) SLKT-241V 1 Adjustable Flow Control-M3 Elbow-3MM OD Tube Push-in Style **VLVF-018** 1 or 2 Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style VLVF-008 1 or 2 **OFSV-004** Fail Safe Valve- M5 1 *Sensor and cable sold separately. †Piston Magnet standard SAMPLE ORDER: DPP-10M-12-C-NS-V

Ex: DPP-10 Metric Gripper, 12mm Stroke, Spring Closed, Non Synchronous, Viton Seals



PARALLEL GRIPPERS DPP-10M-12 DIRECTCONNECT PRECISION SERIES

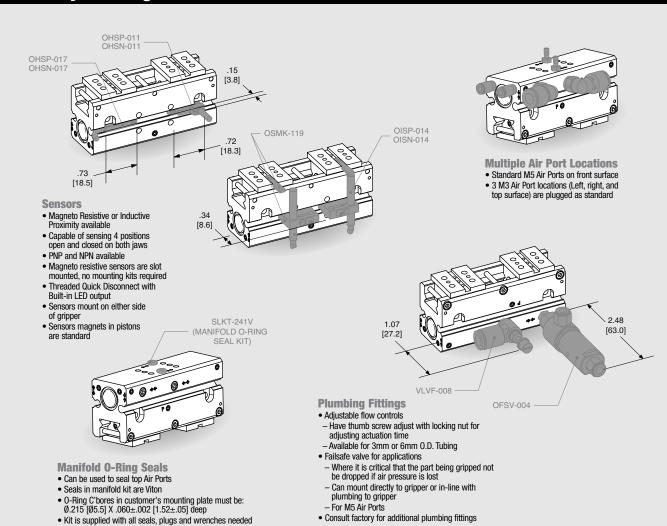
Specifications	DPP-10	M-12
Total Rated Grip Force F @ 100 psi, 7 bar*	27 lbs.	120 N
Stroke	0.50 in.	12.7 mm
Weight	0.45 lbs.	0.20 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	20-100 psi	1.4-7 bar
Cylinder Bore (2X)	0.406 in.	10.3 mm
Displacement	0.065 in ³ .	1.1 cm ³
Temperature Range: Standard Seals	-30°∼180° F	
Viton® Seals	-20°∼250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.11/0.12 sec.	0.11/0.12 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	red to actuate double acting 4-way, 2-position	
*With Springs		



Loading Capacity	Static	Dynamic
Maximum Tensile T	70 lbs. [311 N]	23 lbs. [102 N]
Maximum Compressive C	70 lbs. [311 N]	23 lbs. [102 N]
Maximum Moment M _X	50 in1bs. [5.6 Nm]	17 in1bs. [1.9 Nm]
Maximum Moment My	65 in1bs. [7.3 Nm]	22 in1bs. [2.5 Nm]
Maximum Moment M-	50 in -1hs [5.6 Nm]	17 in - Ihs [1 9 Nm]

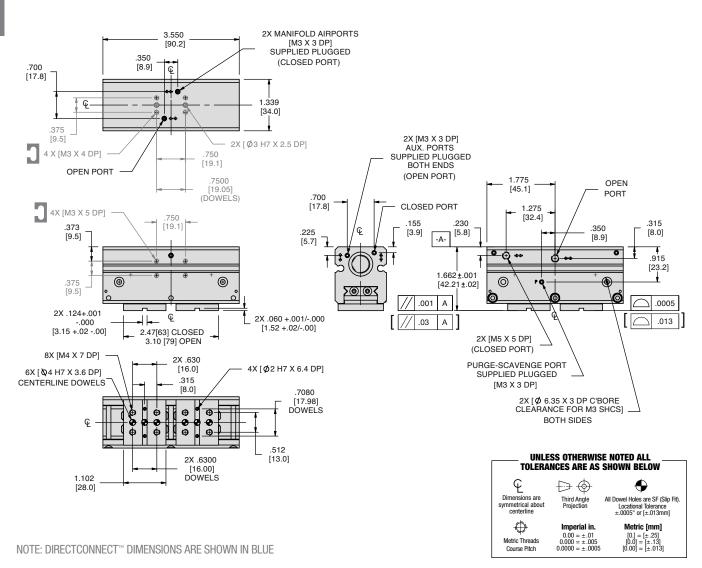
Note: Capacities are per set of jaws and are not simultaneous.

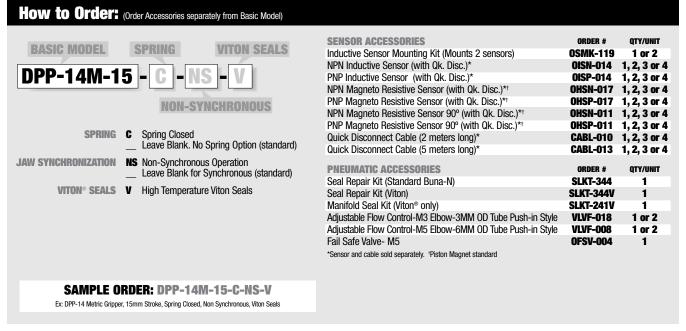
Accessory Mounting Technical Data



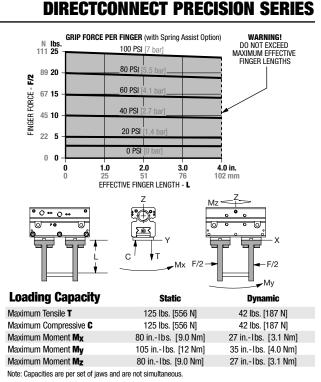
PARALLEL GRIPPERS DPP-14M-15 DIRECTCONNECT PRECISION SERIES



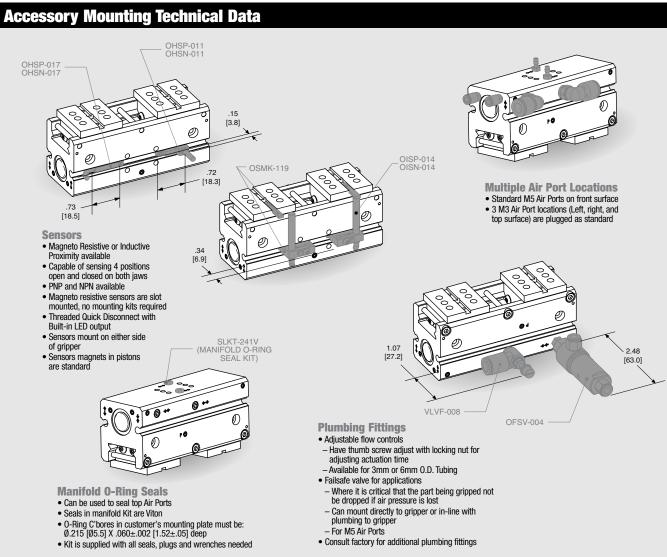




DPP-14I	W-15
51 lbs.	227 N
0.63 in.	15.9 mm
1.05 lbs.	0.48 Kg
5-100 psi	0.3-7 bar
50-100 psi	3.4-7 bar
0.563 in.	14.3 mm
0.156 in ³ .	2.5 cm ³
-30°~180° F	00 00 0
-20°∼250° F	-30°~120° C
0.15/0.16 sec.	0.15/0.16 sec.
±0.001 in.	±0.03 mm
±0.0005 in.	±0.01 mm
3-way, 2-position	
4-way, 2-	oosition
	0.63 in. 1.05 lbs. 5-100 psi 50-100 psi 0.563 in. 0.156 in³30°~180° F -20°~250° F 0.15/0.16 sec. ±0.001 in. ±0.0005 in.



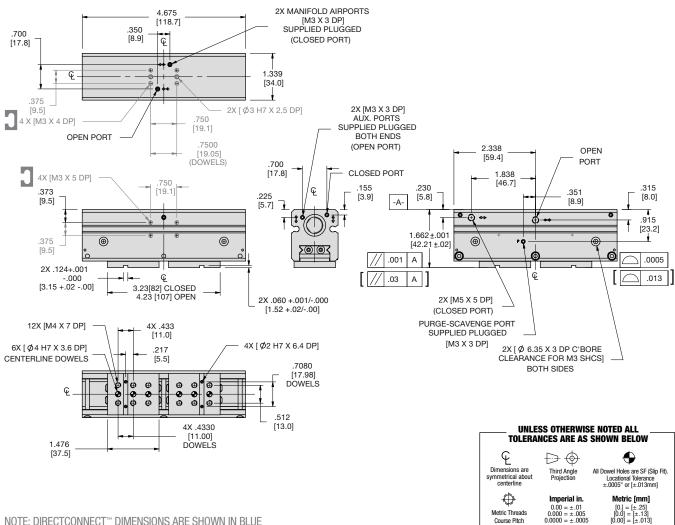
PARALLEL GRIPPERS DPP-14M-15



PARALLEL GRIPPERS DPP-14M-25 **DIRECTCONNECT PRECISION SERIES**







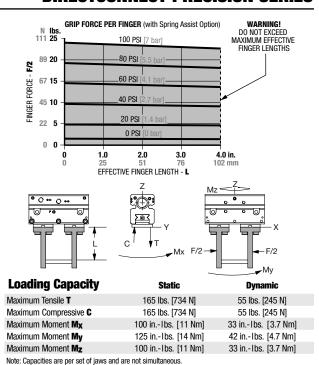
NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES** ORDER # OTY/UNIT **BASIC MODEL VITON SEALS** Inductive Sensor Mounting Kit (Mounts 2 sensors) **OSMK-119** 1 or 2 **OISN-014** NPN Inductive Sensor (with Qk. Disc.)* DPP-14M-25 PNP Inductive Sensor (with Qk. Disc.)* **OISP-014** 2. 3 or 4 NPN Magneto Resistive Sensor (with Qk. Disc.)*1 OHSN-017 1. 2. 3 or 4 **OHSP-017** PNP Magneto Resistive Sensor (with Qk. Disc.)*1 2, 3 or 4 **NON-SYNCHRONOUS** NPN Magneto Resistive Sensor 90° (with Qk. Disc.)*1 **OHSN-011** 1, 2, 3 or 4 OHSP-011 PNP Magneto Resistive Sensor 90° (with Qk. Disc.)* 1, 2, 3 or 4 Spring Closed Quick Disconnect Cable (2 meters long)* CABL-010 1, 2, 3 or 4 Leave Blank. No Spring Option (standard) CABL-013 Quick Disconnect Cable (5 meters long)* 1, 2, 3 or 4 **JAW SYNCHRONIZATION** NS Non-Synchronous Operation **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Leave Blank for Synchronous (standard) **SLKT-344** Seal Repair Kit (Standard Buna-N) 1 **VITON® SEALS V** High Temperature Viton Seals Seal Repair Kit (Viton) SLKT-344V 1 Manifold Seal Kit (Viton® only) SLKT-241V 1 Adjustable Flow Control-M3 Elbow-3MM OD Tube Push-in Style **VLVF-018** 1 or 2 Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style VLVF-008 1 or 2 **OFSV-004** Fail Safe Valve- M5 1 *Sensor and cable sold separately. †Piston Magnet standard SAMPLE ORDER: DPP-14M-25-C-NS-V Ex: DPP-14 Metric Gripper, 25mm Stroke, Spring Closed, Non Synchronous, Viton Seals

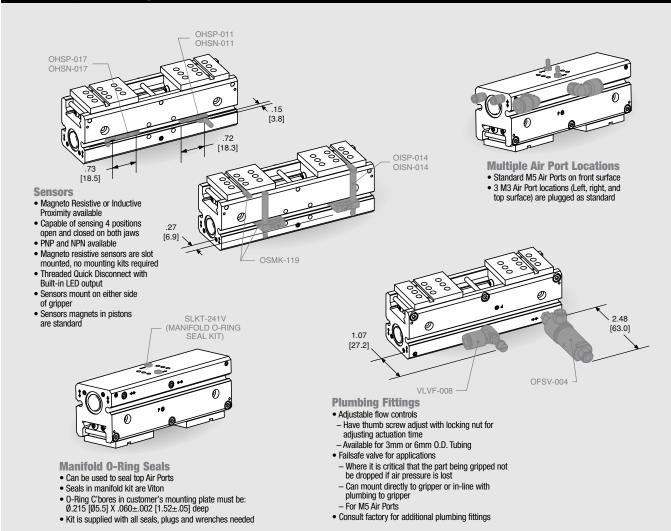


PARALLEL GRIPPERS DPP-14M-25 DIRECTCONNECT PRECISION SERIES

Specifications	DPP-14	M-25
Total Rated Grip Force F @ 100 psi, 7 bar*	48 lbs.	214 N
Stroke	1.00 in.	25.4 mm
Weight	1.25 lbs.	0.57 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	50-100 psi	3.4-7 bar
Cylinder Bore (2X)	0.563 in.	14.3 mm
Displacement	0.249 in ³ .	4.1 cm ³
Temperature Range: Standard Seals	-30°~180° F	
Viton® Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.19/0.20 sec.	0.19/0.20 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2-position	
*With Springs		



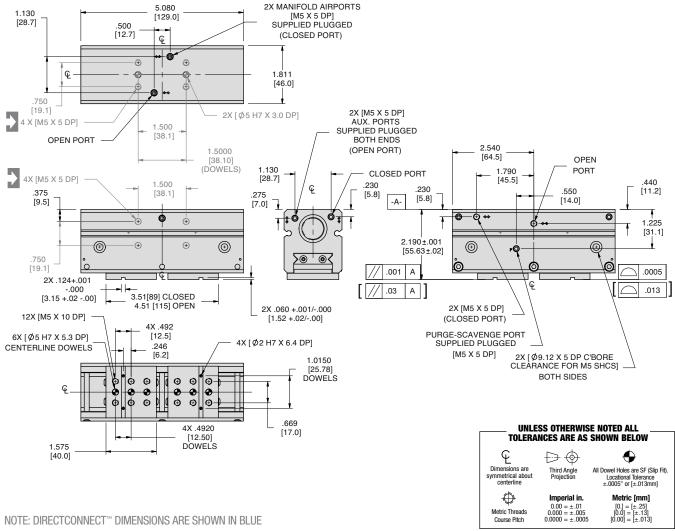
Accessory Mounting Technical Data



PARALLEL GRIPPERS DPP-20M-25 DIRECTCONNECT PRECISION SERIES





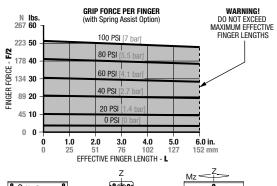


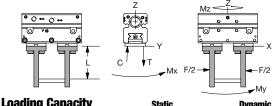
How to Order:	(Order Accessories separately from Basic Model)			
21010 110211		SENSOR ACCESSORIES	ORDER #	QTY/UNIT
BASIC MODEL	SPRING VITON SEALS	Inductive Sensor Mounting Kit (Mounts 2 sensors)	OSMK-120	1 or 2
		NPN Inductive Sensor (with Qk. Disc.)*	OISN-014	1, 2, 3 or 4
DPP-20M-2	5 - C - NS - V	PNP Inductive Sensor (with Qk. Disc.)*	OISP-014	1, 2, 3 or 4
		NPN Magneto Resistive Sensor (with Qk. Disc.)*	OHSN-017	
	NON-SYNCHRONOUS	PNP Magneto Resistive Sensor (with Qk. Disc.)*		1, 2, 3 or 4
	HOIL OT HOIMOHOOD	NPN Magneto Resistive Sensor 90° (with Qk. Disc.)*†		1, 2, 3 or 4
CDDING	Carina Classed	PNP Magneto Resistive Sensor 90° (with Qk. Disc.)*		1, 2, 3 or 4
SPRING	C Spring Closed Leave Blank. No Spring Option (standard)	Quick Disconnect Cable (2 meters long)*		1, 2, 3 or 4
	Leave Dialik. No Spring Option (Standard)	Quick Disconnect Cable (5 meters long)*	CABL-013	1, 2, 3 or 4
JAW SYNCHRONIZATION	NS Non-Synchronous Operation Leave Blank for Synchronous (standard)	PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
	Leave Dialik for Synchronous (Standard)	Seal Repair Kit (Standard Buna-N)	SLKT-345	1
VITON® SEALS	V High Temperature Viton Seals	Seal Repair Kit (Viton)	SLKT-345V	1
		Manifold Seal Kit (Viton® only)	SLKT-242V	1
		Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style	VLVF-008	1 or 2
		Fail Safe Valve- M5	OFSV-004	1
		*Sensor and cable sold separately. †Piston Magnet standard		
0.1151 - 0				
SAMPLE O	RDER: DPP-20M-25-C-NS-V			
Ex: DPP-20 Metric Grippe	er, 25mm Stroke, Spring Closed, Non Synchronous, Viton Seals			



PARALLEL GRIPPERS DPP-20M-25 DIRECTCONNECT PRECISION SERIES

Specifications	DPP-201	M-25
Total Rated Grip Force F @ 100 psi, 7 bar*	103 lbs.	458 N
Stroke	1.00 in.	25.4 mm
Weight	2.25 lbs.	1.02 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	40-100 psi	2.8-7 bar
Cylinder Bore (2X)	0.813 in.	20.7 mm
Displacement	0.519 in ³ .	8.5 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.20/0.22 sec.	0.20/0.22 sec.
Accuracy	±0.001 in.	
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2- ₁	position
		position
*With Springs		



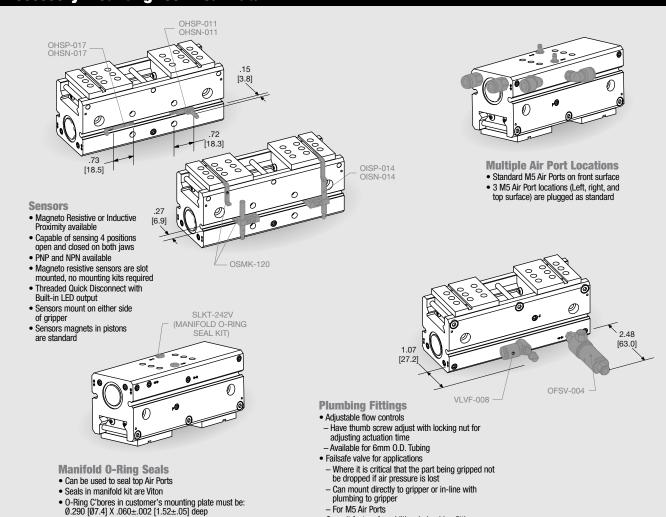


Luauniy vapacity	Static	Dynamic
Maximum Tensile T	150 lbs. [667 N]	50 lbs. [222 N]
Maximum Compressive C	150 lbs. [667 N]	50 lbs. [222 N]
Maximum Moment M _X	300 in1bs. [34 Nm]	100 in1bs. [11 Nm]
Maximum Moment My	350 in1bs. [40 Nm]	117 inIbs. [13 Nm]
Maximum Moment Mz	300 in1bs. [34 Nm]	100 in1bs. [11 Nm]

Note: Capacities are per set of jaws and are not simultaneous.



• Kit is supplied with all seals, plugs and wrenches needed



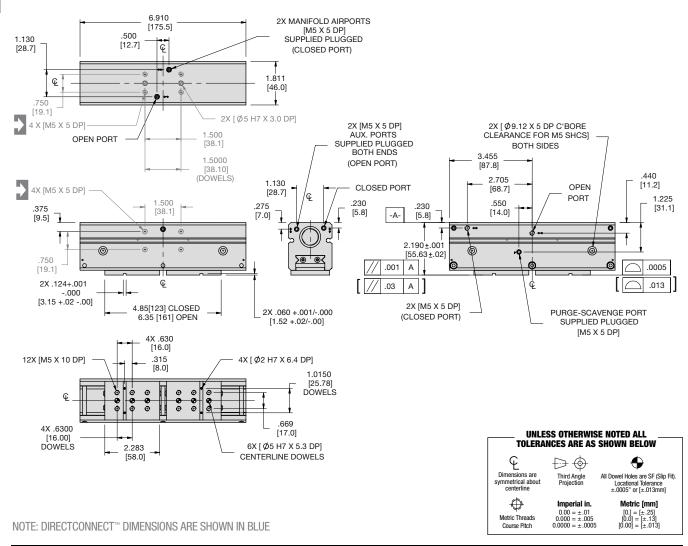
Please see back cover for DE-STA-CO Global Locations. www.destaco.com

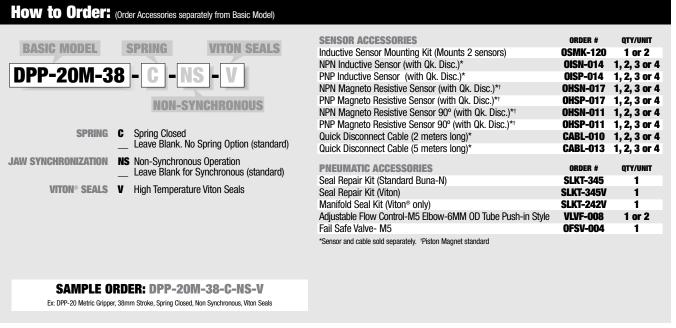
· Consult factory for additional plumbing fittings

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PARALLEL GRIPPERS DPP-20M-38 DIRECTCONNECT PRECISION SERIES

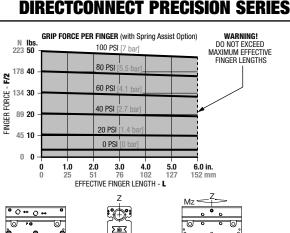




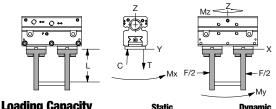




Total Rated Grip Force **F** @ 100 psi, 7 bar*........... 101 lbs. 449 N 38.1 mm 1.41 Kg Pressure Range (Without Springs) 5-100 psi 0.3-7 bar Pressure Range (With Springs) 30-100 psi 2.1-7 bar Cylinder Bore (2X) 0.813 in. 20.7 mm 12.8 cm³ Temperature Range: Standard Seals -30°~180° F -35°~80° C Viton® Seals -20°~250° F -30°~120° C Actuation (Without Spring/With Spring)...... 0.24/0.29 sec. 0.24/0.29 sec. Accuracy ±0.001 in. $\pm 0.03 \; \text{mm}$ ±0.01 mm 3-way, 2-position Valve required to actuate single acting..... Valve required to actuate double acting..... 4-way, 2-position



PARALLEL GRIPPERS DPP-20M-38

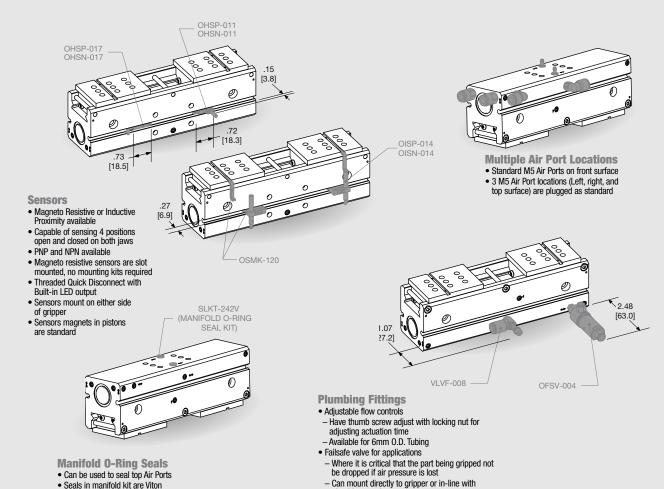


Luauniy Capacity	Static	Dynamic
Maximum Tensile T	200 lbs. [890 N]	67 lbs. [298 N]
Maximum Compressive C	200 lbs. [890 N]	67 lbs. [298 N]
Maximum Moment M _X	400 in1bs. [45 Nm]	133 inIbs. [15 Nm]
Maximum Moment My	450 in1bs. [51 Nm]	150 in1bs. [17 Nm]
Maximum Moment Mz	400 in1bs. [45 Nm]	133 in1bs. [15 Nm]

Note: Capacities are per set of jaws and are not simultaneous.



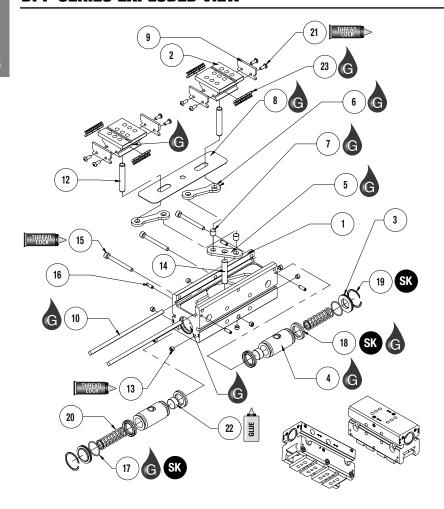
· Kit is supplied with all seals, plugs and wrenches needed



plumbing to gripper

Consult factory for additional plumbing fittings

- For M5 Air Ports



Assembly Procedure:

- 1) Lubricate #1 body (jaw cavity & bore).
- 2) Plug cross ports in body with #13 set screws.
- 3) Press #14 pivot pin into body.
- 4) Insert #22 magnet(s) into each #4 piston making sure magnets repel each other between pistons.
- 5) Lubricate and install #18 seals onto pistons.
- 6) Insert pistons into body with magnet sides facing in toward pivot pin.
- 7) Press #7 equalizer pins into #5 equalizer.
- 8) Assemble equalizer with #6 links and place onto pivot pin in body making sure holes in links line up with holes in pistons.
- 9) Place #8 linkage cover over equalizer and link assembly and seat in body pocket.
- 10) Press #12 drive pin into each #2 iaw.
- 11) Lubricate jaw bearing surfaces and install #9 wiper on each jaw end with #21 mounting screws.
- 12) Place #23 cage and roller bearing assemblies on jaw bearing grooves.
- 13) Place jaws into body aligning the drive pins with the holes in the linkage cover, links, and pistons. If jaws have off center key slot in them, jaws should be installed with this slot farther away from the gripper's center.

- 14) Slide #10 ways into body trapping them between body and jaws.
- 15) Install #16 way locating pins at each end of body to secure ways.
- 16) For -C spring closed option, insert #20 springs into pistons.
- 17) Place # 17 seals onto #3 caps and install onto body with #19 retaining rings.
- 18) Install #15 preload screws and torque per preload adjustment procedure.

Preload Adjustment Procedure:

- 1) Tighten center preload screw first and then outer ones to the torque specification in step 2.
- 2) Use the following torque specification per gripper.

DPP-10M - 6 in-lbs [0.68 Nm]DPP-14M - 8 in-lb [0.90 Nm] DPP-20M - 13 in-lb [1.47 Nm]

Note: Torque specifications provided are factory settings. Fine adjustment may be needed based on intent & application.

Item	Qty	Name
01	1	Body
02	2	Jaw
03	2	Cap
04	2	Piston
05		Equalizer
06	2	Link
07	2	Equalizer Pin
08	1	Linkage Cover
09	4	Wiper
10	2	Way
12	2	Drive Pin
13	10	Set Screw – Air & Purge Plug
14	1	Pivot Pin
15	3	Preload Screw
16	4	Way Locating Pin
17	2	O-Ring – Cap Seal
18	4	U-Cup – Piston Seal
19	2	Retaining Ring
20	2	Spring for -C Spring Closed Option
21*	_	BHCS – Wiper Mounting Screw
22*	_	Magnet
23*	_	S'assy, Cage & Roller Bearings

Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order number and prices.
- 2)* Item #21 quantity varies per gripper size. Size -10M has 4 per unit. Sizes -14M, -20M have 8 per unit.
- 3)* Item #22 quantity varies per gripper size. Size -10M has 4 per unit. Sizes -14M, -20M have 2 per unit.
- 4)* Item #23 quantity and number of different sub-assemblies varies per gripper model. Contact Sales to determine the correct quantity and part numbers needed.



Seal Repair Kit Order #'s See Product Data Sheets

Non-Synchronous Procedure:

- 1) Remove preload screws, press out way locating pins, and slide out ways.
- 2) Pull out jaws and roller bearing assemblies. (If -C spring closed option, remove retaining rings, caps, and springs first.)
- 3) Remove linkage cover from body.
- 4) Remove equalizer and links from body.
- 5) Re-install linkage cover into body.
- 6) Re-install jaws and roller bearing assemblies into body aligning the drive pins with the hole in the linkage cover and each piston.
- 7) Re-install ways, press in way locating pins, and re-install preload screws. (If -C spring closed option, re-install springs, caps and retaining rings.)







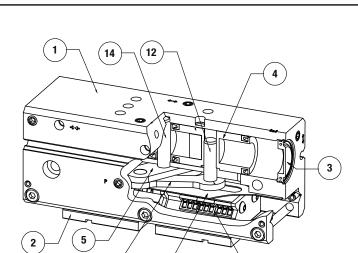












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8

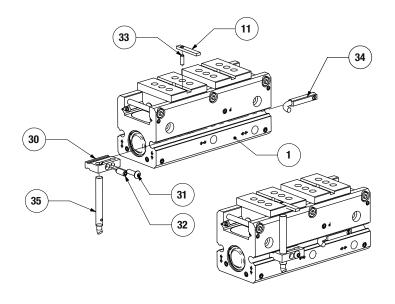
DPP SERIES ASSEMBLED VIEW

Item	Qty	Name
01	1	Body
02	2	Jaw
03	2	Cap
04	2	Piston
05	1	Equalizer
06	2	Link
80	1	Linkage Cover
12	2	Drive Pin
14	1	Pivot Pin
23*	-	S'assy, Cage & Roller Bearings

Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order number and prices.
- 2)* Item #23 quantity and number of different sub-assemblies varies per gripper model. Contact Sales to determine the correct quantity and part numbers needed.

Accessory Installation & Adjustment Instructions



Magneto-Resistive Sensors:

- 1) Install sensors in profile slots of gripper body as shown.
- 2) Set sensors with integrated screw.

Inductive Sensors:

- 1) Insert sensor bracket (#30) into slot of body.
- 2) Insert dowel pin (#33) and target (#11) into jaw slot.
- 3) Insert sensor into bracket and adjust sensor depth so that sensor light indicates on target.
- 4) Tighten sensor locking screw (#31) to hold sensor depth.
- 5) Position sensor bracket for desired stroke detection.
- 6) Tighten sensor bracket with set screw (#32) to lock stroke detection position.











Super Bonder



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Parallel Grippersw Profile Series



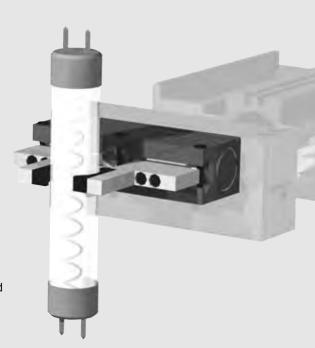
- Precision applications: Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.
- Repeatable grip force: Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

Longer finger applications:

Rigid design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight & size.

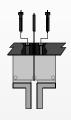
• Non-synchronous motion:

The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.



Mounting Information:

Grippers can be mounted & operated in any orientation





Body mounts with screws and locates with slip fit dowel pins for accuracy



Warning! Protect drive and bearing mechanism from falling debris when mounted upside down





Fingers attach to jaws with screws and locate by keying

Technical Specifications:

Pneumatic Specifications Imperial Metric Pressure Operating Range 5-100 psi .3-7 bar Cylinder Type **Dual Double Acting** Dynamic Seals **Internally Lubricated Buna-N** Valve Required to Operate 4-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better Air Lubrication Not Necessary* Air Humidity **Low Moisture Content (dry)**

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

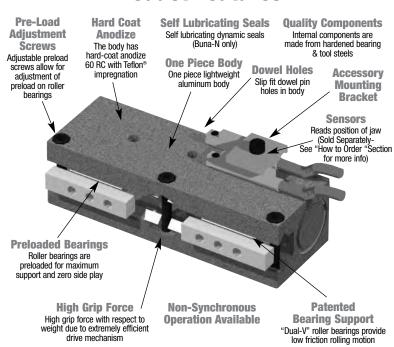
Application Restrictions

- Dirty or gritty environments
- Machining operations generating chips
- · Environments with loose particulate
- Applications where mechanism lubricant could cause contamination

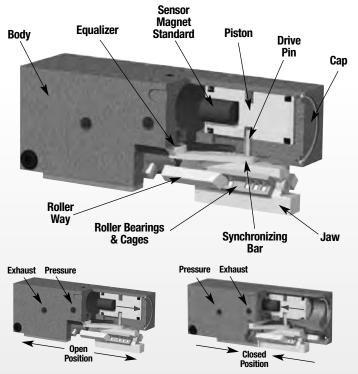
Addition of lubrication will greatly increase service life

See Maintenance Section

Product Features



Operating Principle



- Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- · Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

U.S. Patent # 5,529,359 Designed and manufactured in the USA

Style-RPL Parallel Gripper

 Size
 -1 M
 Style: Stroke: 0.25 in. 6.4 mm
 RPL-1M

 Grip Force: 26 lbs. Weight: .16 lbs. .07 kg



See **1.92** Page **1.92**

Style-RPL Parallel Gripper

 Size
 -2M
 Style: Stroke: 0.50 in. 12.7 mm
 RPL-2 0.50 in. 12.7 mm
 RPL-2 0.50 in. 11.6 N
 RPL-2 0.50 in. 11.6 N
 RPL-2 0.50 in. 12.7 mm
 11.6 N
 <



See **1.93**

Style-RPL Parallel Gripper

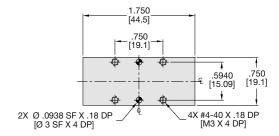
Size -3M Style: RPL-3 Stroke: 0.75 in. 160 N Weight: .32 lbs. .14 Kg



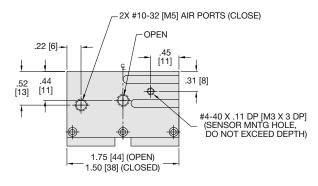
Style-RPL Parallel Gripper Size -4M Style: RPL-4 Stroke: 1.00 in. Grip Force: 36 lbs. Weight: 38 lbs. 17 kg

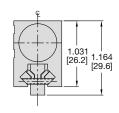
PARALLEL GRIPPER RPL-1M PRECISION DUAL "V" LOW PROFILE SERIES

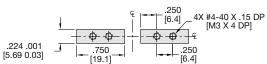




Specifications	RPL-1	RPL-1M
Total Rated Grip Force F @ 100 psi, 7 bar2	6 lbs.	116 N
Stroke	0.25 in.	6.4 mm
Weight	0.16 lbs.	0.07 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.038 in ³ .	0.6 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition







JAW MOUNTING PATTERN (SHOWN IN OPEN POSITION)

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Œ **◆** \oplus Imperial in.

Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

Metric Threads Course Pitch

0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

QTY/UNIT

Loading Information

N lbs. 62 14

53 12

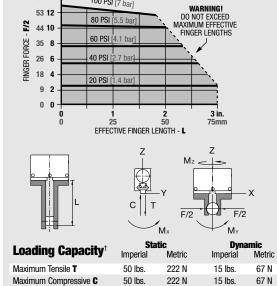
Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

†Capacities are per set of jaws and are not simultaneous

How to Order: (Order Accessories separately from Basic Model)



30 in.-Ibs.

40 in.-lbs.

30 in.-1bs.

3.4 Nm

4.5 Nm

3.4 Nm

10 in.-lbs.

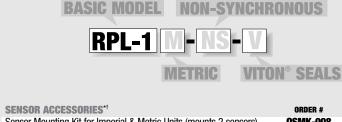
12 in.-lbs. 1.4 Nm

10 in.-lbs. 1.1 Nm

1.1 Nm

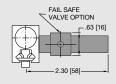
GRIP FORCE PER FINGER

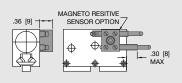
100 PSI [7 bar]



Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors)	OSMK-008	1
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	0FSV-001	1
Fail Safe Valve (Metric)	OFSV-004	1
Standard Seal Repair Kit	SLKT-010	1
Viton® Seal Repair Kit	SLKT-010V	1

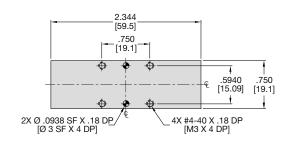
*Sensor and cable sold separately †Piston magnet standard



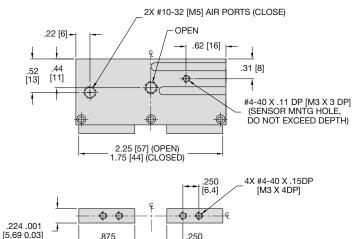




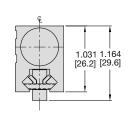
PARALLEL GRIPPER RPL-2M PRECISION DUAL "V" LOW PROFILE SERIES



Specifications	RPL-2	RPL-2M
Total Rated Grip Force F @ 100 psi, 7 bar26 lbs.		116 N
Stroke	0.50 in.	12.7 mm
Weight	0.20 lbs.	0.09 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.075 in ³ .	1.2 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition

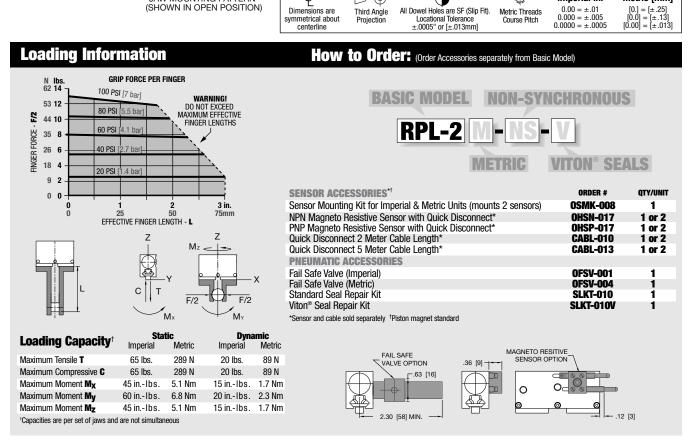


[6.4]

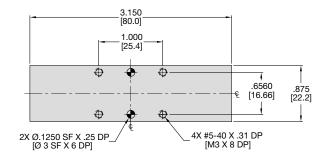




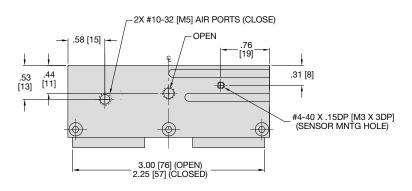


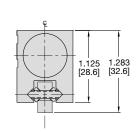


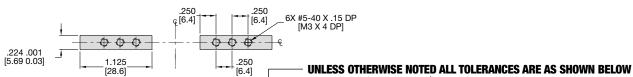




Specifications	RPL-3	RPL-3M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lbs.	160 N
Stroke	0.75 in.	19.1 mm
Weight	0.32 lbs.	0.15 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.147 in ³ .	2.4 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition







JAW MOUNTING PATTERN (SHOWN IN OPEN POSITION)

Third Angle Projection Dimensions are symmetrical about centerline

E

① All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Metric Threads Course Pitch

NON-SYNCHRONOUS

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

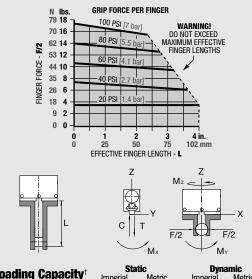
WITOMR CEALC

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Loading Information

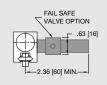
How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL

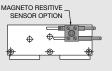


WEIKIG VIII	IN SEALS	
SENSOR ACCESSORIES*†	ORDER #	QTY/UNIT
Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors)	OSMK-008	1
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	OFSV-001	1
Fail Safe Valve (Metric)	0FSV-004	1
Standard Seal Repair Kit	SLKT-012	1
Viton® Seal Repair Kit	SLKT-012V	1
*Sensor and cable sold separately *Piston magnet standard		

Looding Consoitut	Static		Dynamic	
Loading Capacity [†]	Imperial	Metric	Imperial	Metric
Maximum Tensile T	90 lbs.	400 N	30 lbs.	133 N
Maximum Compressive C	90 lbs.	400 N	30 lbs.	133 N
Maximum Moment M _X	60 in1bs.	6.8 Nm	20 in1bs.	2.3 Nm
Maximum Moment My	80 inlbs.	9.0 Nm	25 in1bs.	2.8 Nm
Maximum Moment Mz	60 inlbs.	6.8 Nm	20 in1bs.	2.3 Nm
†Canacities are ner set of laws and are not simultaneous				

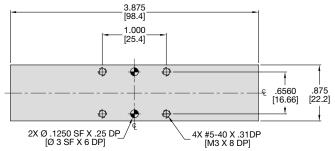




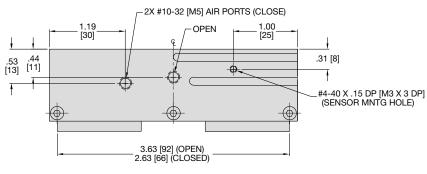


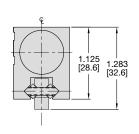


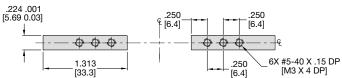
PARALLEL GRIPPER RPL-4M PRECISION DUAL "V" LOW PROFILE SERIES



Specifications	RPL-4	RPL-4M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lbs.	160 N
Stroke	1.00 in.	25.4 mm
Weight	0.38 lbs.	0.17 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.196 in ³ .	3.2 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.19 sec.	0.19 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition







JAW MOUNTING PATTERN (SHOWN IN OPEN POSITION)

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

E Dimensions are symmetrical about centerline $\Rightarrow \Leftrightarrow$ Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

1 Metric Threads Course Pitch

METRIC

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

VITON® SEALS

NON-SYNCHRONOUS

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

QTY/UNIT

1 or 2

1 or 2 1 or 2

1

1

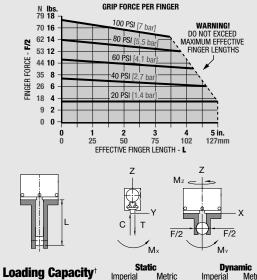
Loading Information

Maximum Tensile T

Maximum Moment My

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL



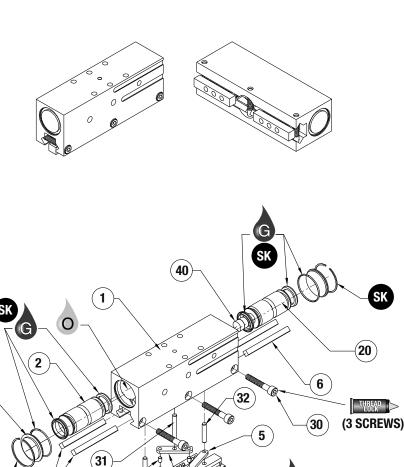
SENSUK AGGESSUKIES	UKDEK #
Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors)	OSMK-008
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017
Quick Disconnect 2 Meter Cable Length*	CABL-010
Quick Disconnect 5 Meter Cable Length*	CABL-013
PNEUMATIC ACCESSORIES	
Fail Safe Valve (Imperial)	OFSV-001
Fail Safe Valve (Metric)	OFSV-004
Standard Seal Repair Kit	SLKT-012
Viton® Seal Repair Kit	SLKT-012V
*Sensor and cable sold separately †Piston magnet standard	











Item	Qty	Name
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
08	2	Jaw
13	2	Pin
20	1	Piston W/Magnet Slot
21	4	S'assy,Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- Lubricate and install seals.
 Press dowel pin into center of body.
- 3) Place links and equalizers into body.
- 4) Press dowel pins into jaws.
- 5) Place jaws through links and into pistons.
- 6) Install cages on jaws.
- 7) Place ways behind cages with flat facing out and install screws.
- 8) Adjust preload.

Preload Adjustment Procedure

- 1) Tighten center screw (#30) so that fingers bind slightly.
- 2) Tighten outer screws in the same fashion.
- 3) Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-Synchronous Procedure

- 1) Remove preload screws (#30) and
- 2) Remove cages, jaws and dowel pins.
- 3) Remove equalizer, links, and roller bearings.
- 4) Re-assemble jaws and dowel pins into pistons.
- 5) Re-install cages on jaws.
- 6) Place ways behind cages with flat facing out and install preload screws.
- 7) Adjust preload.





3



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21







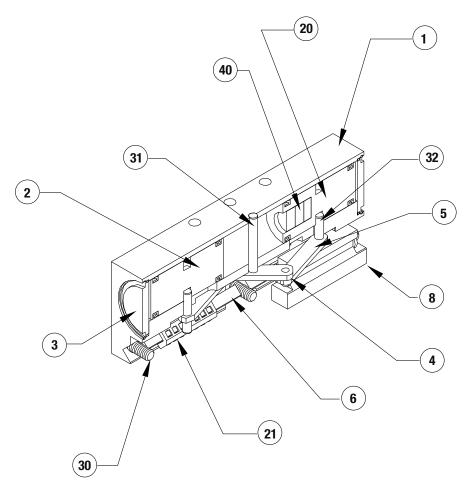






RPL Series Assembled View

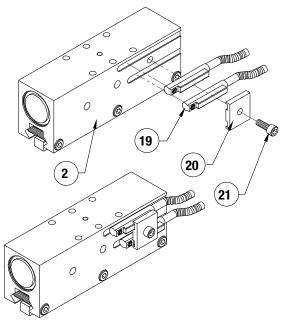




Ite	m Qty	Name
110	iii Qty	Hame
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
80	2	Jaw
13	2	Bearing,Roller
20	1	Piston W/Magnet Slot
21	4	S'assy,Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation

- 1. Install sensors as shown.
- Adjust for desired end of stroke detection.











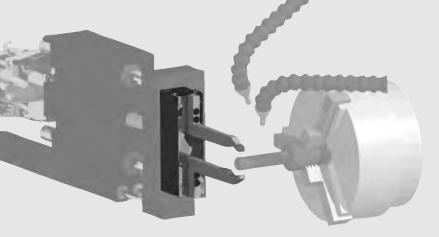




1 00

Parallel Grippers

Clean Room / Harsh Environments Series



• Precision applications:

Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.

• Clean Room rated:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with clean room grade lubricant. The scavenge port can be used with vacuum pressure to prevent escape

of particulate generated by the internal mechanism.

Harsh environments:

All moving components are located within the stainless steel shield. The body has a purge port which can expel contaminates from the mechanism using low air pressure.

• Repeatable grip force:

Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

Longer finger applications:

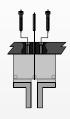
Rigid design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight.

• Non-synchronous motion:

The unit can made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

Mounting Information:

Grippers can be mounted & operated in any orientation







Body mounts with screws and locates with slip fit dowel pins for accuracy



Shields provide protection from falling debris when mounted upside down





Fingers attach to jaws with screws and locate by keying

Technical Specifications:

Pressure Operating Range
Cylinder Type
Dynamic Seals
Valve Required to Operate

Pressure Operating Range
5-100 psi
3-7 bar
Dual Double Acting
Internally Lubricated Buna-N
4-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better
Air Lubrication Not Necessary*
Air Humidity Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

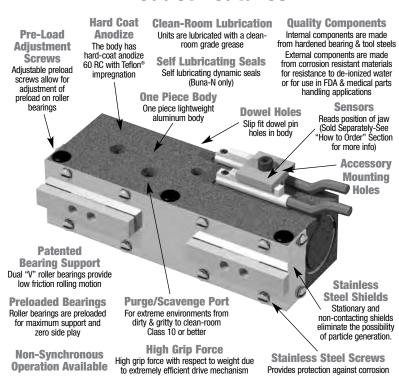
Maintenance Specifications[†]

Expected Life
Normal Application
w/ Preventative Maintenance
Field Repairable

5 million cycles 10+ million cycles* Yes Yes

Seal Repair Kits Available
*Addition of lubrication will greatly increase service life

Product Features



Style-RPLC Parallel Gripper

Size -1M

 Style:
 RPLC-1
 RPLC-1M

 Stroke:
 0.25 in.
 6.4 mm

 Grip Force:
 26 lb
 116 N

 Weight:
 .16 lb
 .07 Kg



See 1.100

Style-RPLC Parallel Gripper

Size -2M

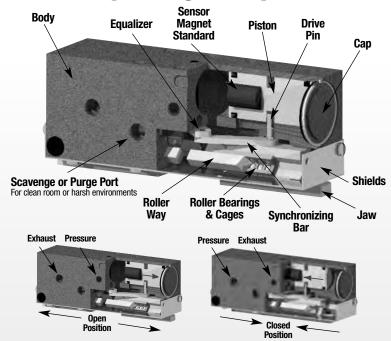
Style: Stroke: Grip Force: Weight:

RPLC-2 RPLC-2M 0.50 in. 12.7 mm 26 lb 116 N .20 lb .09 Kg



See **1.101**

Operating Principle



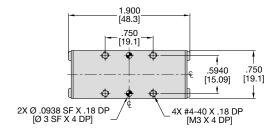
- Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- The purge/scavenge port can be used to expel or retain contaminates using pressure or vacuum respectively.
- Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

U.S. Patent # 5,529,359 Designed and manufactured in the USA

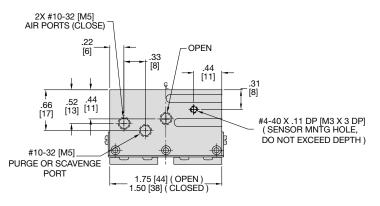


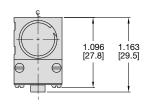


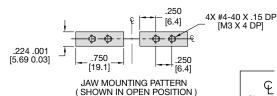




RPLC-1	RPLC-1M
6 lb	116 N
0.25 in.	6.4 mm
0.16 lb	0.07 Kg
5-100 psi	0.3-7 bar
0.438 in.	11.1 mm
0.038 in ³ .	0.6 cm ³
-30°~180° F	-35°~80° C
-20°~250° F	-30°~120° C
0.10 sec.	0.10 sec.
±0.002 in.	±0.05 mm
±0.001 in.	±0.03 mm
4-way, 2-po	osition
	6 lb 0.25 in. 0.16 lb 5-100 psi 0.438 in. 0.038 in ³ 30°~180° F -20°~250° F 0.10 sec. ±0.002 in. ±0.001 in.







— UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch

NON-SYNCHRONOUS

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

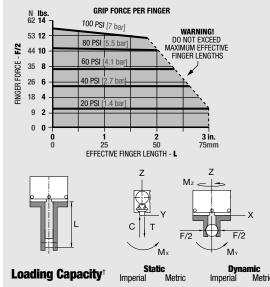
VITON® SEALS

Loading Information

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL

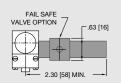
RPLC-1



SENSOR ACCESSORIES**	ORDER #	QTY/UNIT
Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors)	OSMK-008	1
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	OFSV-001	1
Fail Safe Valve (Metric)	OFSV-004	1
Standard Seal Repair Kit	SLKT-010	1
Viton® Seal Repair Kit	SLKT-010V	1
*Sensor and cable sold separately [†] Piston magnet standard		

METRIC

Metric Maximum Tensile T 50 lbs. 222 N 15 lbs. 67 N Maximum Compressive C 50 lbs. 222 N 15 lbs. 67 N Maximum Moment Mx 3 4 Nm 30 in.-lbs. 10 in.-lbs. 1 1 Nm Maximum Moment My 40 in.-lbs. 4.5 Nm 12 in.-lbs. 1.4 Nm Maximum Moment Mz 30 in.-lbs. 3.4 Nm 10 in -lbs 1 1 Nm †Capacities are per set of jaws and are not simultaneous

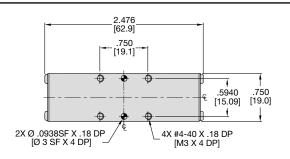




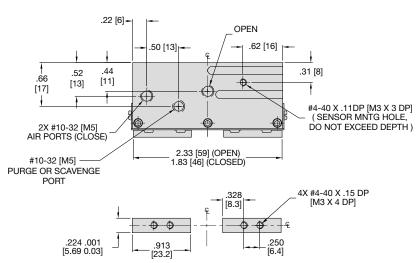


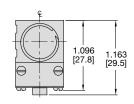


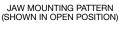
PARALLEL GRIPPER RPLC-2M PRECISION DUAL "V" CLEAN ROOM SERIES



Specifications	RPLC-2	RPLC-2M
Total Rated Grip Force F @ 100 psi, 7 bar2	26 lb	116 N
Stroke	0.50 in.	12.7 mm
Weight	0.20 lb	0.09 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.075 in ³ .	1.2 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition







UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

P Dimensions are symmetrical about

 $\Rightarrow \oplus$ Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Metric Threads Course Pitch

Imperial in. 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

NON-SYNCHRONOUS

Metric [mm]

Loading Information

Maximum Tensile T

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

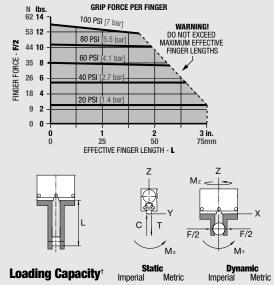
Maximum Moment Mz

†Capacities are per set of jaws and are not simultaneous

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL

RPLC-2



65 lbs

65 lbs.

45 in.-lbs.

60 in.-lbs.

45 in.-lbs.

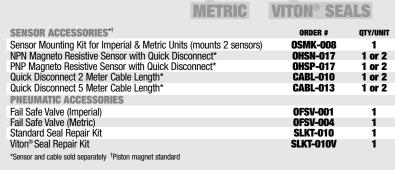
289 N

289 N

5.1 Nm

6.8 Nm

5.1 Nm



MAGNETO RESITIVE FAIL SAFE .36 [9] VALVE OPTION SENSOR OPTION -.63 [16] Фс \oplus \oplus 2.30 [58] MIN

89 N

89 N

1.7 Nm

2.3 Nm

1.7 Nm

20 lb

20 lb

15 in.-lbs.

20 in.-lbs.

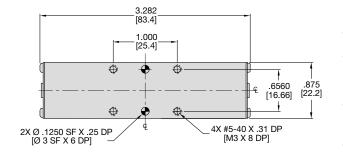
15 in.-lbs.

[5.69 0.03]

PARALLEL GRIPPER RPLC-3M PRECISION DUAL "V" CLEAN ROOM SERIES



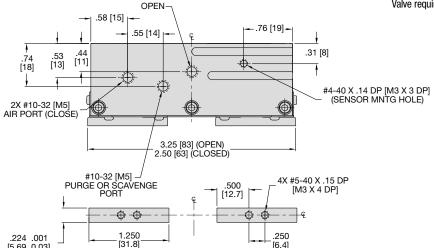
DDI C_2M

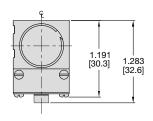


Specifications	KPLU-3	KPLG-3IVI
Total Rated Grip Force F @ 100 psi, 7 bar	36 lb	160 N
Stroke	0.75 in.	19.1 mm
Weight	0.32 lb	0.15 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.147 in ³ .	2.4 cm ³
Temperature Range Standard Seals Viton® Seals Actuation Accuracy Repeatability	-30°~180° F -20°~250° F 0.14 sec. ±0.002 in. ±0.001 in.	-35°~80° C -30°~120° C 0.14 sec. ±0.05 mm ±0.03 mm
Valve required to actuate	4-way, 2-position	

DDI C-2

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JAW MOLINTING PATTERN (SHOWN IN OPEN POSITION)

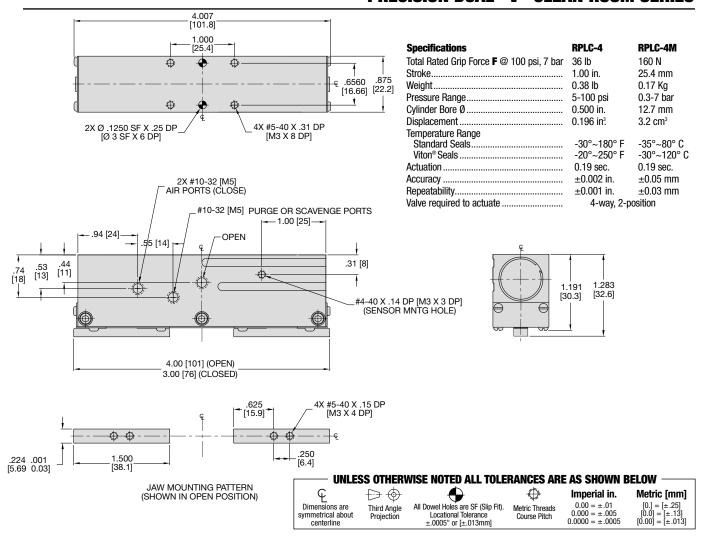
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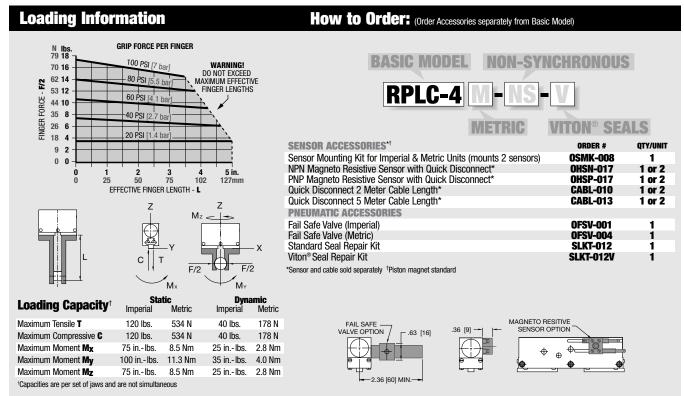
OILL	JO GIIIEIII	HOL HOLLD ALL HOLL	IIAIIULU AI	IL AU UNUTIN D	LLUII
Ç	$\Rightarrow \phi$	⊕	\bigoplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Loading Information How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER N lbs 79 18 **BASIC MODEL** 100 PSI [7 bar] WARNING 70 16 DO NOT EXCEED MAXIMUM EFFECTIVE 62 14 FINGER LENGTHS 53 12 44 10 35 8 FINGER **METRIC VITON® SEALS** 26 6 18 SENSOR ACCESSORIES* ORDER # QTY/UNIT 9 2 Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-008** 0 n NPN Magneto Resistive Sensor with Quick Disconnect* **OHSN-017** 1 or 2 4 in. 102 mm PNP Magneto Resistive Sensor with Quick Disconnect* **OHSP-017** 1 or 2 Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 EFFECTIVE FINGER LENGTH - L Quick Disconnect 5 Meter Cable Length* CABL-013 1 or 2 **PNEUMATIC ACCESSORIES** Fail Safe Valve (Imperial) **OFSV-001** Fail Safe Valve (Metric) **OFSV-004** Standard Seal Repair Kit **SLKT-012** Viton® Seal Repair Kit SLKT-012V С *Sensor and cable sold separately †Piston magnet standard F/2 M× Static **Dynamic** rial Metric **Loading Capacity**[†] Imperial Metric Imperial MAGNETO RESITIVE SENSOR OPTION FAIL SAFE VALVE OPTION Maximum Tensile T 400 N 133 N 90 lbs 30 lbs .36 [9] .63 [16] Maximum Compressive C 90 lbs. 400 N 30 lbs. 133 N Maximum Moment Mx Φ 60 in - lbs 6.8 Nm 20 in - lbs 2 3 Nm Ф Maximum Moment My 80 in.-lbs. 9.0 Nm 25 in.-lbs. 2.8 Nm Maximum Moment Mz 60 in.-lbs. 6.8 Nm 20 in.-lbs. 2.3 Nm -2.36 [60] MIN. †Capacities are per set of jaws and are not simultaneous

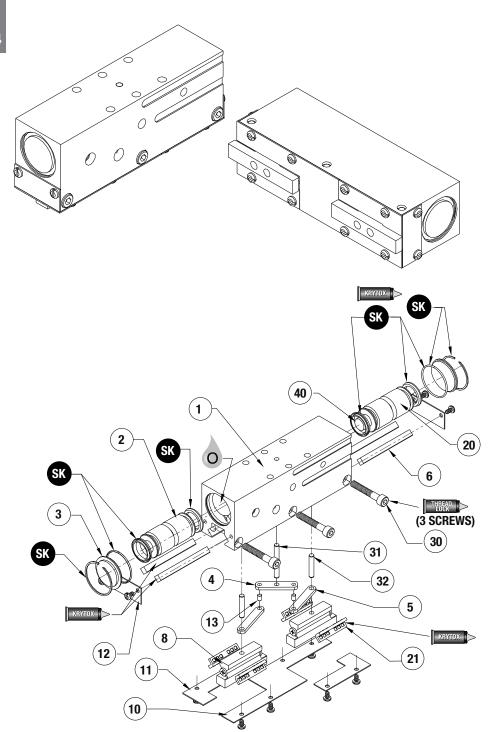


PARALLEL GRIPPER RPLC-4M PRECISION DUAL "V" CLEAN ROOM SERIES









Item	Qty	Name
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
- 08	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Assembly procedure

- 1) Lubricate and install seals.
- 2) Glue magnets into one piston, install pistons, caps and retaining rings.
- 3) Press dowel pin into center of body.
- 4) Place links and equalizers into body.
- 5) Press dowel pins into jaws.
- 6) Place jaws through links and into pistons.
- 7) Install cages on jaws.
 8) Place ways behind cages with flat facing out and install screws.
- 9) Adjust preload.
- 10) Install bottom cover, bottom cover corners and end covers.

Preload adjustment procedure

- 1) Tighten center screw (#30) so that fingers preload adjustment procedure

 2) Tighten outer screws in the same fashion.
- Bind slightly.
- Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-synchronous procedure

- 1) Remove end covers, bottom cover corners, and bottom cover.
- 2) Remove preload screws (#30) and ways.
- 3) Remove cages, jaws and dowel pins.
- 4) Remove equalizer, links, and roller bearings.
- 5) Re-assemble jaws and dowel pins into pistons.
- 6) Re-install cages on jaws.
- Place ways behind cages with flat facing
- 8) Adjust preload. Install preload screws.
- 9) Re-attach bottom cover, bottom cover corners and end covers. Gripper is now non-synchronous.









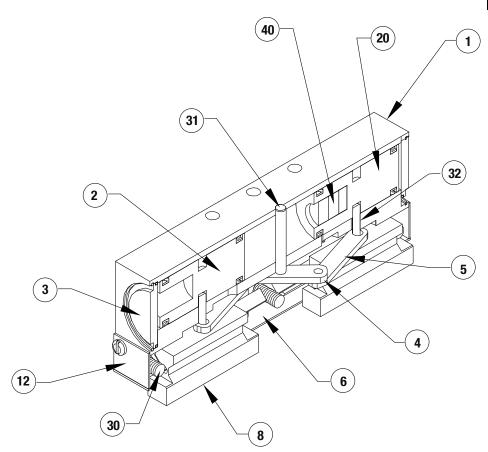












Item	Qty	Name
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
- 08	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

2 24

Installation

- Install sensors as shown.
 Adjust for desired end of stroke detection.







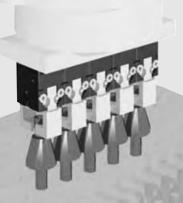








Parallel Grippers-Miniature Series



• Precision applications:

Preloaded dual-"V" roller bearings eliminate side play for excellent part position repeatability.

• Miniature size:

Compact design allows for gripping small parts in small spaces.

• Top manifold:

Grippers can be manifolded through the top mounting surface. This eliminates the need for air fittings and allows grippers to be mounted in close array.

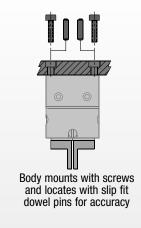
Repeatable grip force:

Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

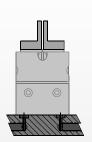


Mounting Information:

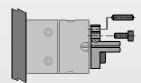
Grippers can be mounted & operated in any orientation







Unit has top manifold ports



Fingers attach to jaws with screws and locate with dowel pins or by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals

Valve Required to Operate

Imperial Metric 40-100 psi 1.3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable

5 million cycles 10+ million cycles* Yes

Seal Repair Kits Available

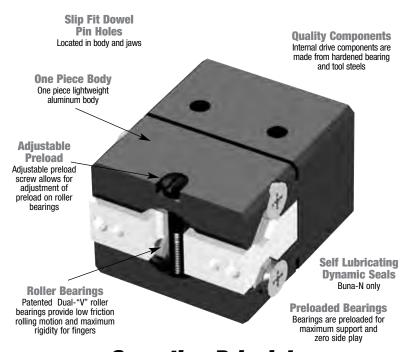
Yes

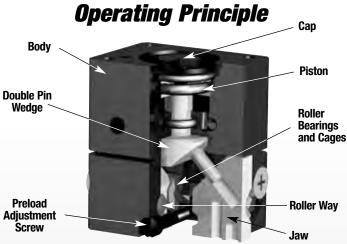
Application restrictions

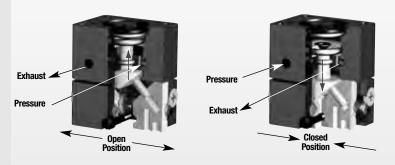
Dirty or gritty environments Machining operations generating chips Environments with loose particulate Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life See Maintenance Section

Product Features







- A double acting piston is connected by a shaft to a double sided pin wedge.
- The pin wedge slides in a hole located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.
- This gripper is suitable for internal or external gripping.

U.S. Patent #5,529,359 & #5,125,708 **Designed and manufactured in the USA**

Style-RPM Parallel Gripper

Size -1M

Style: Stroke: Grip Force: Weight: 0 3.2 mm 36 N 0.13 in. 8 lbs. 0.052 lbs. .02 Kg



See **1.108**

Style-RPM Parallel Gripper

Size -2M

Style: Stroke: 0.19 in. Grip Force: 8 lbs. 0.058 lbs. Weight: .03 Kg

See **1.109**

Style-RPM Parallel Gripper

Size -3M

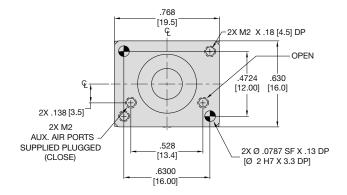
Style: RP Stroke: 0.25 in. Grip Force: 8 lbs. Weight: 0.074 lbs. 6.3 mm 36 N .03 Kg

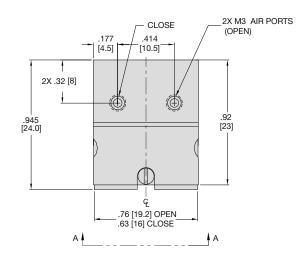


See **1.110**

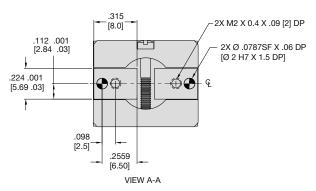
PARALLEL GRIPPER RPM-1M MINIATURE SERIES



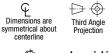




RPM-1M		
lbs.	36 N	
.13 in.	3.2 mm	
0.052 lbs.	0.024 Kg	
40-100 psi	3-7 bar	
0.394 in.	10.0 mm	
0.008 in ³ .	0.13 cm ³	
-30°~180° F	-35°~80° C	
-20°~250° F	-30°~120° C	
0.10 sec.	0.10 sec.	
±0.002 in.	±0.05 mm	
±0.001 in.	±0.03 mm	
4-way, 2-po	osition	
	lbs13 in. 0.052 lbs. 40-100 psi 0.394 in. 0.008 in ³ 30°~180° F -20°~250° F 0.10 sec. ±0.002 in. ±0.001 in.	



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

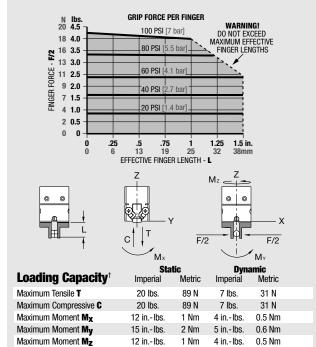


All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Loading Information

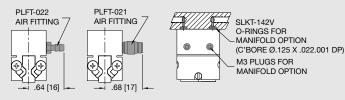
†Capacities are per set of jaws and are not simultaneous

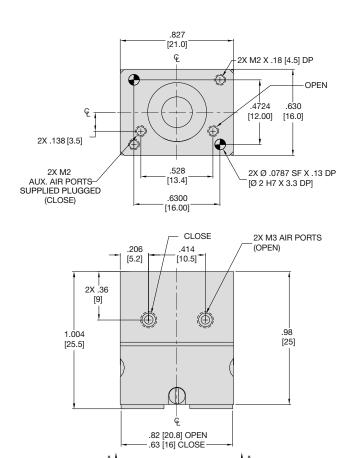
How to Order: (Order Accessories separately from Basic Model)





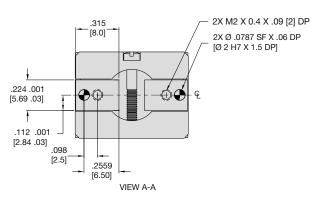
PNEUMATIC ACCESSORIES	Order #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-142V	1





PARALLEL GRIPPER RPM-2M MINIATURE SERIES

Specifications	RPM-2M					
Total Rated Grip Force F @ 100 psi, 7 bar8	lbs.	36 N				
Stroke	.19 in.	4.8 mm				
Weight	0.058 lbs.	0.026 Kg				
Pressure Range	40-100 psi	3-7 bar				
Cylinder Bore Ø	0.394 in.	10.0 mm				
Displacement	0.012 in ³ .	0.20 cm ³				
Temperature Range						
Standard Seals	-30°∼180° F	-35°~80° C				
Viton® Seals	-20°∼250° F	-30°~120° C				
Actuation	0.10 sec.	0.10 sec.				
Accuracy	±0.002 in.	±0.05 mm				
Repeatability	±0.001 in.	±0.03 mm				
Valve required to actuate	4-way, 2-po	osition				



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW



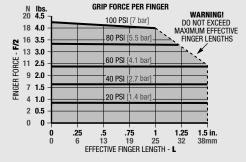
All Dowel Holes are SF (Slip Fit).
Locational Tolerance ±.0005" or [±.013mm]

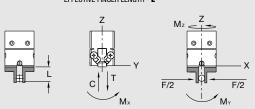
0 Metric Threads Course Pitch

Imperial in. Metric [mm] 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005 $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$



How to Order: (Order Separately)

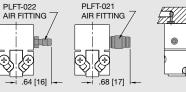




	M _A	(_	My	
Loading Capacity [†]	Sta Imperial	r tic Metric	Dyna Imperial	a mic Metric	
Maximum Tensile T	20 lbs.	89 N	7 lbs.	31 N	
Maximum Compressive C	20 lbs.	89 N	7 lbs.	31 N	
Maximum Moment M _X	12 inlbs.	1 Nm	4 inlbs.	0.5 Nm	
Maximum Moment My	15 inlbs.	2 Nm	5 inlbs.	0.6 Nm	
Maximum Moment Mz	12 inlbs.	1 Nm	4 inlbs.	0.5 Nm	
*Capacities are per set of jaws and ar	e not simultaneou	us			

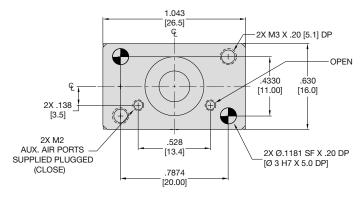


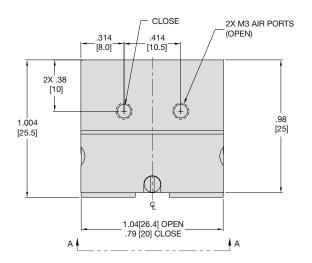
PNEUMATIC ACCESSORIES	Order #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-142V	1



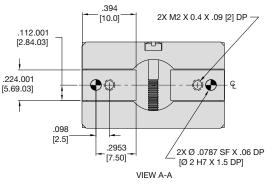
PARALLEL GRIPPER RPM-3M MINIATURE SERIES







RPM-3M **Specifications** Total Rated Grip Force F @ 100 psi, 7 bar8 lbs. 36 N Stroke..... 6.3 mm .25 in. 0.074 lbs. 0.034 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø 10.0 mm 0.394 in. Displacement 0.015 in³. 0.25 cm³ Temperature Range -30°~180° F -35°~80° C Standard Seals -30°~120° C -20°~250° F Viton® Seals Actuation ... 0.10 sec. 0.10 sec. ±0.05 mm Accuracy..... ±0.002 in. Repeatability...... ±0.001 in. ±0.03 mm Valve required to actuate 4-way, 2-position



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW







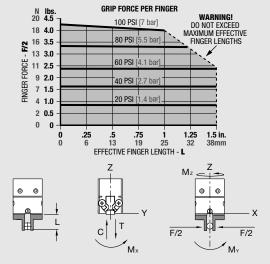
Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

.0005" or [±.013mm] **Metric [mm]**[0.] = [±.25] [0.0] = [±.13] [0.00] = [±.013]

Loading Information

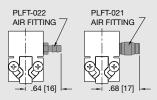
How to Order: (Order Separately)



u	[c '	F/2	- IIII -	F/2	
	M _x			M _Y	
Loading Capacity [†]	Sta Imperial	tic Metric	Dyna Imperial	a mic Metric	
Maximum Tensile T	20 lbs.	89 N	7 lbs.	31 N	
Maximum Compressive C	20 lbs.	89 N	7 lbs.	31 N	
Maximum Moment M _X	12 inlbs.	1 Nm	4 inlbs.	0.5 Nm	
Maximum Moment My	15 inlbs.	2 Nm	5 inlbs.	0.6 Nm	
Maximum Moment Mz	12 inlbs.	1 Nm	4 inlbs.	0.5 Nm	
†Capacities are per set of jaws and	are not simultaneou	IS			



PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-142V	1

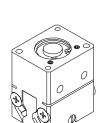


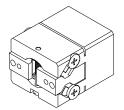


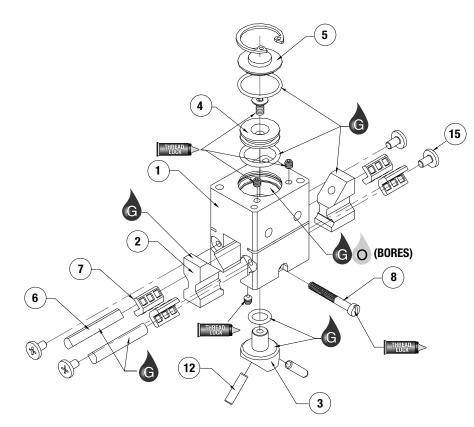
SLKT-142V
O-RINGS FOR
MANIFOLD OPTION
(C'BORE Ø.125 X .022.001 DP)
M3 PLUGS FOR
MANIFOLD OPTION



RPM Series Exploded View







Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Cap
06	2	Way
07	4	Kit, Roller Bearings And Cage
80	1	Preload
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals
- 2) Install pins (12) and wedge (3) into
- 3) Install piston (4), screw, cap (5), & retaining ring
- 4) Install set screws for airport plugs
- 5) Install jaws (2) over pins
- 6) Install ways (6), cages (7), & screws (15)

Preload Adjustment

- 1) Install preload screw (8) w/Loctite on 1st 6-8 threads
- 2) Tighten until there is no side-pay in the jaws
- 3) Cycle gripper (w/fingers preferably)
- 4) Recheck for play in jaws & tighten or loosen as needed









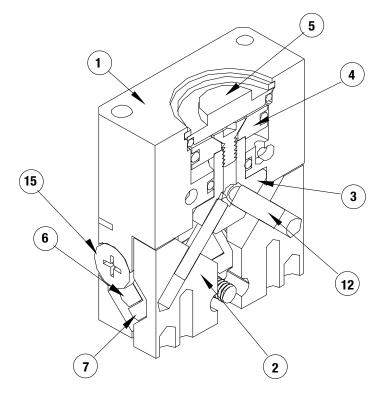












Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Cap
06	2	Way
07	4	Kit,Roller Bearings And Cage
08	1	Preload
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Non-Repairable Items List NONE













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PRECISDESIGN NOTES

1.113

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Parallel Grippers Miniature Clea Room Se



Precision applications:

Preloaded dual-"V" roller bearings eliminate side play for excellent part position repeatability.

Miniature size:

Compact design allows for gripping small parts in small spaces.

Top manifold:

Grippers can be manifolded through the top mounting surface. This eliminates the need for air fittings and allows grippers to be mounted in close array.

Clean room rated:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with clean room grade grease. The scavenge port can be used with vacuum pressure to prevent escape of particulate generated by the internal mechanism.

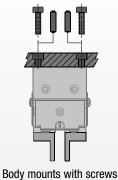
Harsh environments:

All moving components are located within the corrosion resistant cover. The body has a purge port which can expel contaminates from the mechanism using low pressure compressed air.

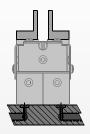


Mounting Information:

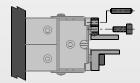
Grippers can be mounted & operated in any orientation



and locates with slip fit dowel pins for accuracy



Unit has top manifold ports



Fingers attach to jaws with screws and locate with dowel pins or by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals

Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications

Expected Life

Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

*Addition of lubrication will greatly increase service life See Maintenance Section

Product Features

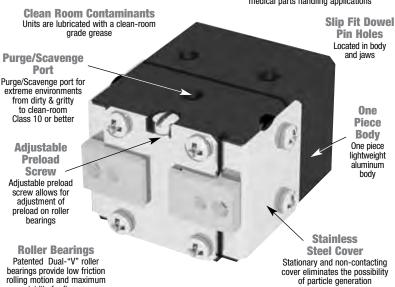
Preload Bearings Bearings are preloaded for maximum support and zero side play

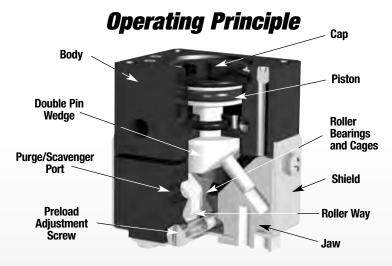
rigidity for fingers

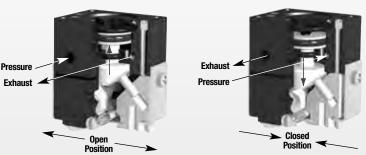
Hard Coat Anodize
The body has hard-coat
anodize 60 RC with
Teflon® impregnation

Quality Components

External components are made from corrosion resistant materials for resistance to de-ionized water or for use in FDA & medical parts handling applications







- A double acting piston is connected by a shaft to a double sided pin wedge.
- The pin wedge slides in a hole located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.
- This gripper is suitable for internal or external gripping.

U.S. Patent #5,529,359 & #5,125,708 Designed and manufactured in the USA

Style-RPMC Parallel Gripper

Size -1M

 Style:
 RPMC-1M

 Stroke:
 0.13 in.
 3.2 mm

 Grip Force:
 8 lb
 36 N

 Weight:
 0.052 lb
 .02 Kg



See **1.116**

Style-RPMC Parallel Gripper

Size -2M

Stroi Grip Weig

 Style:
 RPMC-2M

 Stroke:
 0.19 in.
 4.8 mm

 Grip Force:
 8 lb
 36 N

 Weight:
 0.058 lb
 .03 Kg

See **1.117**

Style-RPMC Parallel Gripper

Size -3M



 Style:
 RPMC-3M

 Stroke:
 0.25 in.
 6.3 mm

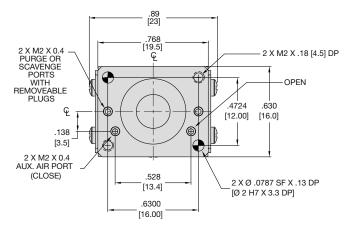
 Grip Force:
 8 lb
 36 N

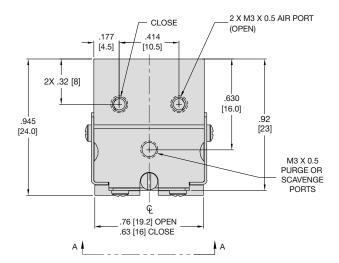
 Weight:
 0.074 lb
 .03 Kg

See **1.118**

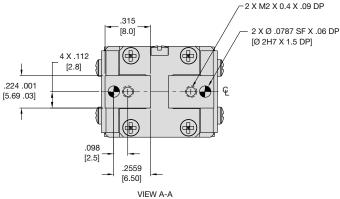
PARALLEL GRIPPER RPMC-1M **MINIATURE CLEAN ROOM SERIES**







RPMC-1M **Specifications** Total Rated Grip Force F @ 100 psi, 7 bar8 lb 36 N Stroke..... .13 in. 3.2 mm Weight ... 0.052 lb 0.024 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø 0.394 in. 10.0 mm Displacement 0.008 in³. 0.13 cm³ Temperature Range Standard Seals..... -30°~180° F -35°~80° C -30°~120° C -20°~250° F Viton® Seals Actuation Time 0.10 sec. 0.10 sec. Accuracy..... ±0.002 in. ±0.05 mm Repeatability..... ±0.03 mm ± 0.001 in. Valve required to actuate 4-way, 2-position



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Q Dimensions are symmetrical about centerline

 $ightarrow \Phi$ Third Anale

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

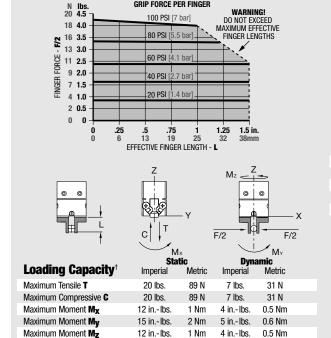
 \bigoplus Metric Threads Course Pitch

Imperial in. 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005 Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$



†Capacities are per set of jaws and are not simultaneous

How to Order: (Order Separately)



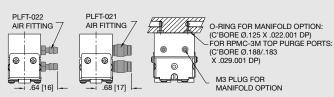
GRIP FORCE PER FINGER

WARNING!



PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1

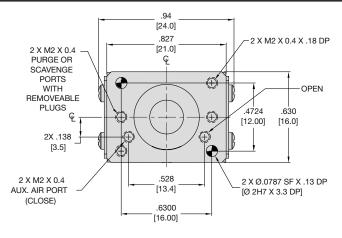
For Detailed Accessory Mounting Technical Data Refer to Accessories Section

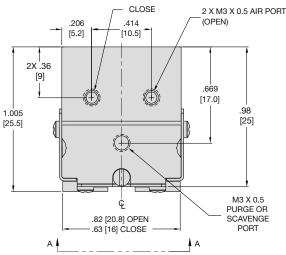




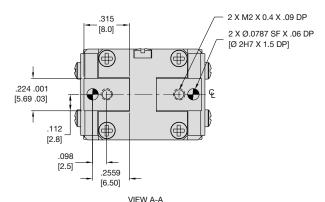


PARALLEL GRIPPER RPMC-2M **MINIATURE CLEAN ROOM SERIES**





Specifications	RPMC-2M					
Total Rated Grip Force F @ 100 psi, 7 bar8	lb	36 N				
Stroke	.19 in.	4.8 mm				
Weight	0.058 lb	0.026 Kg				
Pressure Range	40-100 psi	3-7 bar				
Cylinder Bore Ø	0.394 in.	10.0 mm				
Displacement	0.012 in ³ .	0.20 cm ³				
Temperature Range						
Standard Seals	-30°∼180° F	-35°~80° C				
Viton® Seals	-20°~250° F	-30°~120° C				
Actuation Time	0.10 sec.	0.10 sec.				
Accuracy	±0.002 in.	±0.05 mm				
Repeatability	±0.001 in.	±0.03 mm				
Valve required to actuate	4-way, 2-pc	osition				



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW



All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \oplus Metric Threads Course Pitch

0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

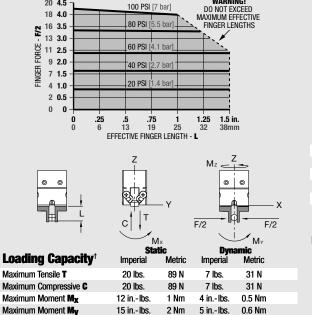


N lbs 20 4.5

Maximum Moment Mz

†Capacities are per set of jaws and are not simultaneous

How to Order: (Order Separately)



12 in.-lbs.

1 Nm

4 in.-lbs.

0.5 Nm

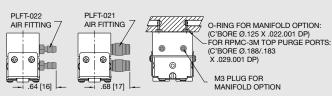
GRIP FORCE PER FINGER

WARNING!



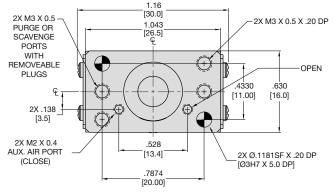
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1

For Detailed Accessory Mounting Technical Data Refer to Accessories Section



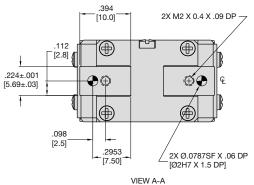
PARALLEL GRIPPER RPMC-3M MINIATURE CLEAN ROOM SERIES





-	.314 [8.0]414 [10.5]414	2X M3 X 0.5 AIR PORTS (OPEN)
2X.38 [10] 1.005 [25.5]	1.04[26.4] OPEN .79 [20] CLOSE	.709 [18.0] .98 [25] M3 X 0.5 PURGE OR SCAVENGE PORTS
A •		A A

Specifications RPMC-3M Total Rated Grip Force F @ 100 psi, 7 bar8 lb 36 N Stroke..... .25 in. 6.3 mm 0.074 lb 0.034 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø 0.394 in. 10.0 mm Displacement 0.015 in³. 0.25 cm³ Temperature Range -35°~80° C Standard Seals -30°~180° F -30°~120° C Viton® Seals..... -20°~250° F Actuation Time 0.10 sec. 0.10 sec. ±0.05 mm Accuracy..... ±0.002 in. Repeatability..... ±0.001 in. ±0.03 mm Valve required to actuate 4-way, 2-position



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

VITON® SEALS

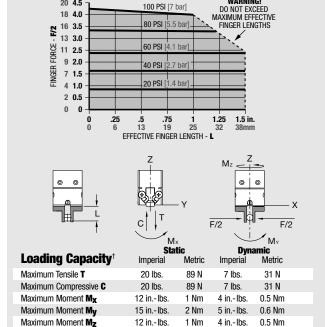
Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Loading Information

†Capacities are per set of jaws and are not simultaneous

N lbs 20 4.5

How to Order: (Order Separately)



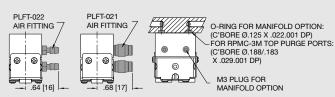
GRIP FORCE PER FINGER

WARNING!



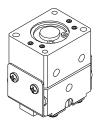
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm O.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton® Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1

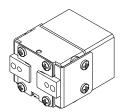
For Detailed Accessory Mounting Technical Data Refer to Accessories Section

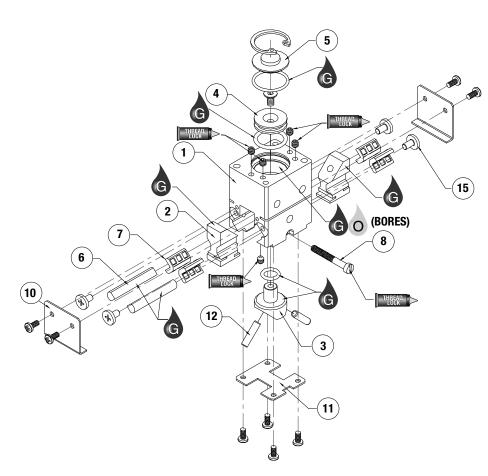












Item	Qty	Name
<u>01</u>	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Cap
06	2	Way
07	4	Kit, Roller Bearings And Cage
80	1	Screw,Preload
10	2	Shield,Side
11	1	Shield,Top
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedures

- 1) Lubricate and install seals. 2) Install pins (12) and wedge (3) into body.
- 3) Install piston (4), screw, cap (5), & Retaining Ring.
- 4) Install set screws for air port plugs. 5) Install jaws (2) over pins.
- 6) Install ways (6), cages (7), & screws (15).

- Preload Adjustment
 1) Install preload screw (8) with Loctite on first 6 -8 threads.
 2) Tighten until there is no side play in
- the jaws.
- 3) Cycle gripper(w/finger assembly) 4) Recheck for play in jaws & tighten or loosen as needed.



Seal Repair Kit Order #'s **See Product Data Sheets**



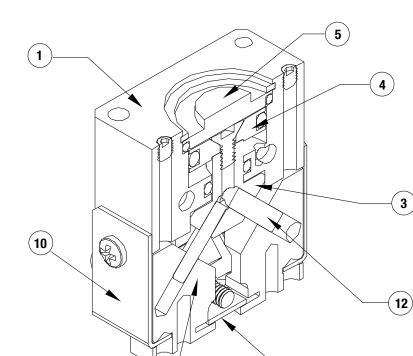












Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Cap
06	2	Way
07	4	Kit,Roller Bearings And Cage
08	1	Screw,Preload
10	2	Shield, Side
11	1	Shield,Top
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.







(11)









AZ MONTH : COMMON COMMO

PRECISDESIGN NOTES

RPMC SERIES

Parallel Grippers-DPG DIRECTCONNECT** Modular Series







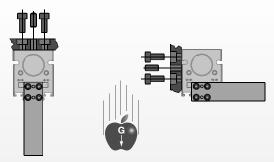




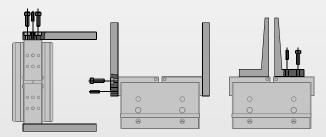
- Multiple air port positions: Tapped air ports on front and both sides are standard. Top air ports with counterbores for o-ring manifolded operation and threads for screw-in type fittings are available.
- Sensing options: Magneto resistive (Hall Effect) or inductive proximity sensors available.
- Sense up to four positions: Up to four jaw positions can be sensed to allow open, closed, part present, or variable part size sensing.
- Shielded to repel contaminate: Design repels chips and particulate. Closed jaw position spacing eliminates "chip compactor" effect.
- Longer finger applications: Rigid design and full body support of jaw allows for longer finger lengths.
- Spring assist, spring return: Cylinders can be double acting, double acting spring assist, failsafe, or single acting in either open or closed direction.
- Non-synchronous motion: Non-synchronous motion option provides independent jaw motion allowing the gripper to pick or place at a point other than it's center.
- Single jaw motion with fixed jaw: This option locks one jaw in a fixed position while the other jaw is free to move.

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying or dowel pin holes

Technical Specifications:

Pneumatic Specifications Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar Cylinder Type **Double Acting** or Single Acting Spring Return or Double Acting Spring Assist **Dynamic Seals Internally Lubricated Buna-N** Valve Required 4-way, 2-position for Double Acting to Operate or 3-way, 2-position for Single Acting

Air Quality Requirements

Air Filtration 40 Micron or Better Air Lubrication Not Necessary* **Low Moisture Content (dry)** Air Humidity

Temperature Operating Range

-30°~180° F -35°~80° C Buna-N Seals (standard) -20°~300° F -30°~150° C Viton® Seals (optional)

Maintenance Specifications[†]

Expected Life

5 million cycles Normal Application w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

Application Restrictions

Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life See Maintenance Section

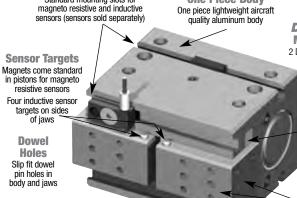
Product Features

Hard Coat Anodize

The body and jaws have hard-coat anodize 60RC with Teflon® impregnation

Sensor Mounting Slots

Standard mounting slots for magneto resistive and inductive sensors (sensors sold separately)



High Temperature Optional Viton® seals are available for

Locations high temperature applications 3 standard airport locations (front & both sides) Optional top airports available **One Piece Body**

DIRECTCONNECT Mounting Patterns

Multiple Air Port

2 DIRECTCONNECT™ mounting surfaces on top and back of body

Superior Jaw Support

Jaws are supported throughout the length of the body

Versatile Finger Mounting

2 finger mounting surfaces on each jaw

Extremely Compact & Robust Design

Self-Lubricating Seals Self lubricating dynamic seals (Buna-N only)

Shielded Design

Shielded design repels

Multiple Sensor Capabilities

Capable of sensing both jaws in the open and closed positions (up to 4 sensors can be used for multi-position sensing)

Optional Features

- Top air ports eliminating the need for airlines
- · Fixed jaw configurations · Spring assist for open or close stroke
- Non-synchronous version

Style -DPG-10M Parallel Gripper

Size -1

Style: D Stroke: 0.25 in. Grip Force: 50 lbs. 6.4 mm 222 N Weight: 0.39 lbs. 0.17 Kg





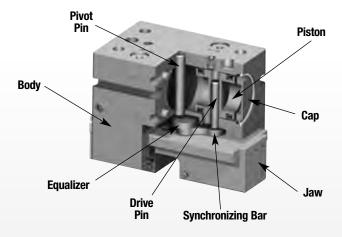
Style -DPG-10M Parallel Gripper

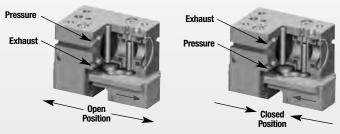
Size -2

Style: D Stroke: 0.50 in. Grip Force: 50 lbs. DPG-10M-2 12.7 mm 222 N 0.53 lbs 0.24 Kg



Operating Principle





- · Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- · Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

Designed and manufactured in the USA

Style -DPG-10M Parallel Gripper

Size -3

Grip Force: 50 lbs.
Weight: 0.68 lbs. 19.1 mm 222 N



See **1.128** Page **1.128**

Style -DPG-10M Parallel Gripper

Size -4

Style: Stroke: Stroke: 1.00 in. Grip Force: 50 lbs. Weight: 0.81 lbs.

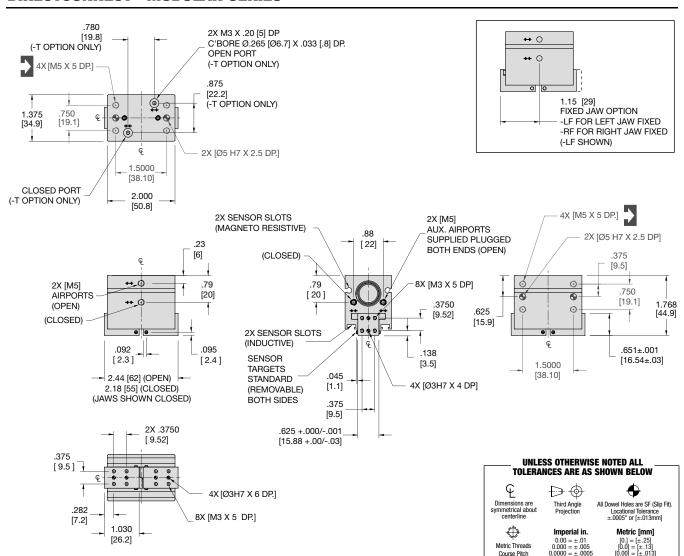
DPG-10M-4 222 N 0.36 Kg



NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

PARALLEL GRIPPER DPG-10M-1 DIRECTCONNECT™ MODULAR SERIES

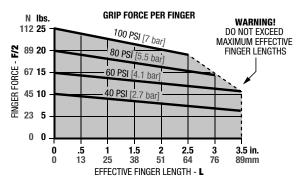




How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES BASIC MODEL SPRING TOP PORTING** Inductive Sensor Mounting Kit (Mounts 2 Sensors) OSMK-097 1 or 2 NPN Inductive Sensor with Qk. Disconnect* **OISN-019** 1,2,3, or 4 **DPG-10M** -PNP Inductive Sensor with Qk. Disconnect* **OISP-019** 1,2,3, or 4 NPN Magneto Resistive Sensor w/Qk. Disconnect* **OHSN-017** 1,2,3, or 4 **OHSP-017** PNP Magneto Resistive Sensor w/Qk. Disconnect* **JAW SYNC VITON® SEALS** 1,2,3, or 4 **OHSN-011** NPN Magneto Resistive Sensor (90°) w/Qk. Disconnect* (See Below) 1,2,3, or 4 PNP Magneto Resistive Sensor (90°) w/Qk. Disconnect* OHSP-011 1,2,3, or 4 Spring Open Spring Closed Leave Blank. No Spring Option (standard) **SPRING DIRECTION** Quick Disconnect Cable (2 meters long)* CABL-010 1,2,3, or 4 Č Quick Disconnect Cable (5 meters long)³ CABL-013 1,2,3, or 4 CABL-015 Quick Disconnect Cable Extension Cord (1 meter long)* 1,2,3, or 4 JAW SYNCHRONIZATION Left Jaw Fixed CABL-016 Quick Disconnect Cable Extension Cord (2 meters long)* 1,2,3, or 4 Right Jaw Fixed Non-synchronous Jaws Leave Blank for Synchronous (standard) **CONFIGURATION** RF NS **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Standard Seal Repair Kit **SLKT-183** 1 Viton® Seal Repair Kit SLKT-183V -T Option Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style PLFT-021 1 or 2 -T Option Plumbing Fitting - M3 male to 2mm ID Tube Barb Style PLFT-022 1 or 2 **OFSV-004** Fail Safe Valve - M5 (Metric) 1 Adjustable Flow Control (Metric) **VLVF-008** 1 or 2 Top Port Manifold Seal Kit SLKT-184V *Sensor and cable sold separately **SAMPLE ORDER: DPG-10M-1-C-V** Ex: DPG-10M Gripper, Metric, Size 1, Spring Close, Viton® Seals

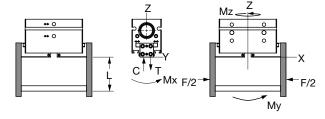


PARALLEL GRIPPER DPG-10M-1 MODULAR SERIES



Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open 6	lbs.	26 N	9 lbs.	40 N
@ Full Close		49 N	6 lbs.	26 N

Specifications	DPG-10N	N-1
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.25 in.	6.4 mm
Weight	0.39 lbs.	0.17 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.076 in ³ .	1.2 cm ³

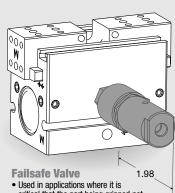


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	175 lbs. [778 N]	20 lbs. [89 N]
Maximum Compressive C	400 lbs. [1779 N]	20 lbs. [89 N]
Maximum Moment M _X	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]
Maximum Moment My	175 in1bs. [20 Nm]	30 in1bs. [3 Nm]
Maximum Moment Mz	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]

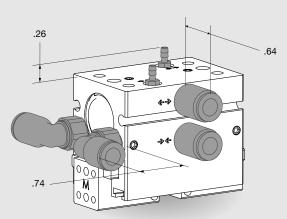
†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-1	
Temperature Range: Standard SealsViton® Seals		
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-position	

Accessory Mounting Technical Data

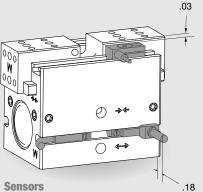


- critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port

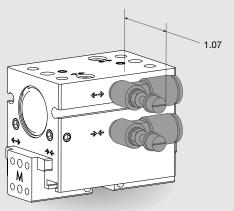


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- · Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper



Flow Controls

- Thumb screw adjust with locking nut for adjusting actuation time

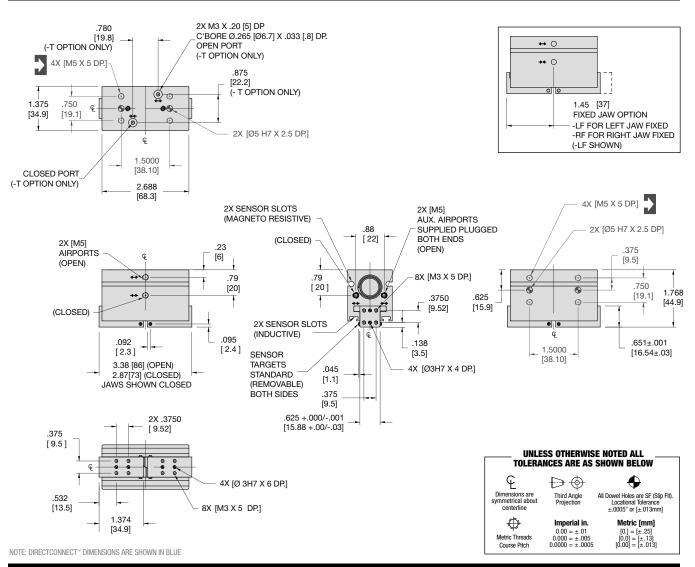
· Available for 5mm OD tubing

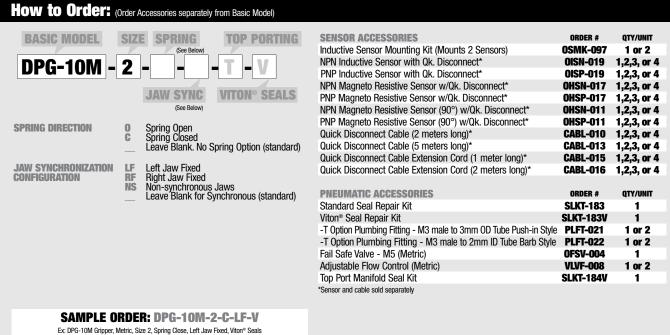
PARALLEL GRIPPER DPG-10M-2 DIRECTCONNECT™ MODULAR SERIES





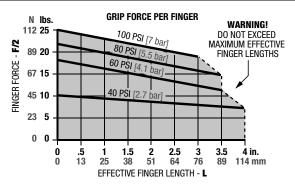
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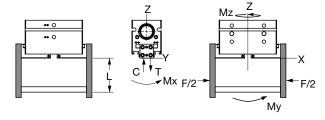


PARALLEL GRIPPER DPG-10M-2 DIRECTCONNECT™ MODULAR SERIES



Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	14 lbs.	62 N
@ Full Close		66 N	6 lbs.	26 N

Specifications	DPG-10)M-2
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.50 in.	12.7 mm
Weight	0.53 lbs.	0.24 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.153 in ³ .	2.5 cm ³

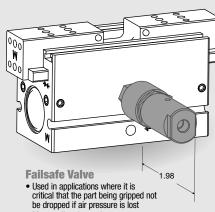


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	200 lbs. [890 N]	25 lbs. [111 N]
Maximum Compressive C	425 lbs. [1890 N]	25 lbs. [111 N]
Maximum Moment M _X	175 in1bs. [20 Nm]	25 in1bs. [3 Nm]
Maximum Moment My	200 in1bs. [23 Nm]	35 in1bs. [4 Nm]
Maximum Moment Mz	175 in1bs. [20 Nm]	25 in1bs. [3 Nm]

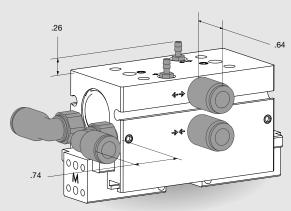
†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-2	
Temperature Range: Standard SealsViton® Seals	-30°~180° F -20°~300° F	
Actuation	0.19 sec.	0.19 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-position	

Accessory Mounting Technical Data

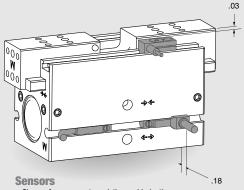


- Mounts directly to gripper
- M5 air port

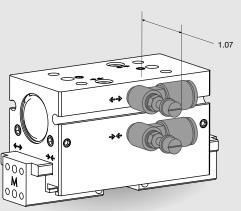


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- · Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper



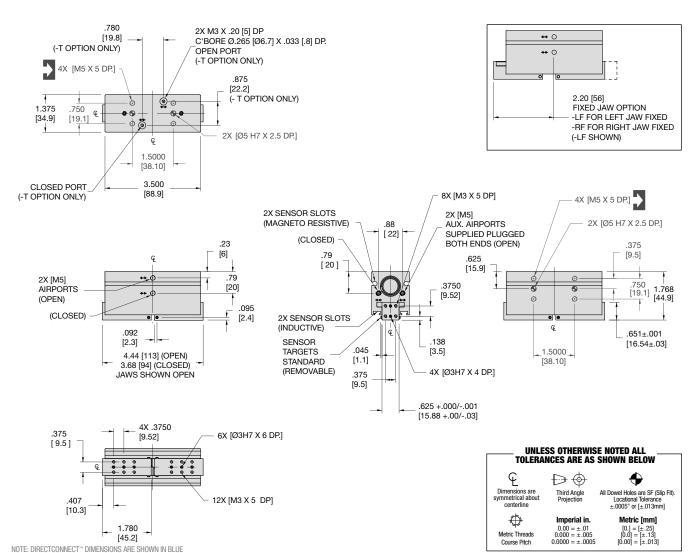
Flow Controls

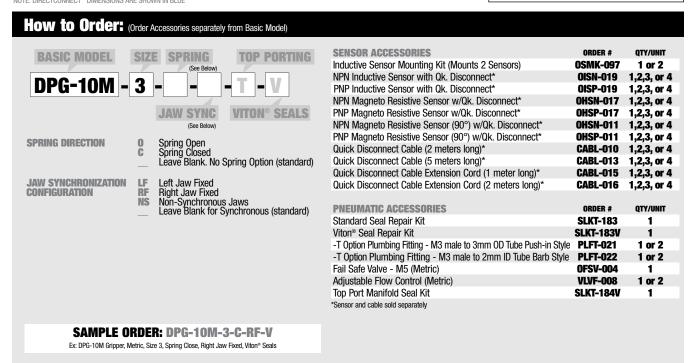
- . Thumb screw adjust with locking nut for adjusting actuation time
- Available for 5mm 0D tubing

PARALLEL GRIPPER DPG-10M-3 DIRECTCONNECT™ MODULAR SERIES



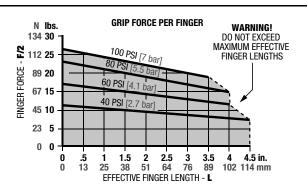






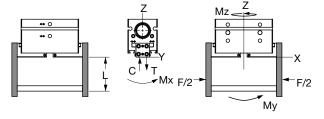
DIRECTCONNE





Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	15 lbs.	66 N
@ Full Close	23 lbs.	102 N	6 lbs.	26 N

Specifications	DPG-10	M-3
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.75 in.	19.1 mm
Weight	0.68 lbs.	0.30 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø		17.5 mm
		3.8 cm ³



DIRECTCONNECT

PARALLEL GRIPPER DPG-10M-3

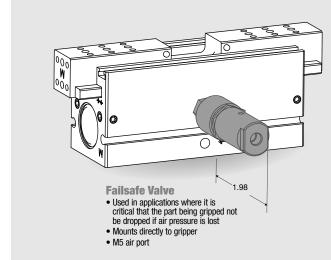
MODULAR SERIES

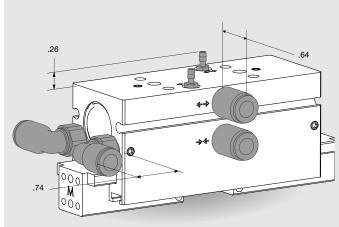
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	225 lbs. [1001 N]	30 lbs. [133 N]
Maximum Compressive C	450 lbs. [2002 N]	30 lbs. [133 N]
Maximum Moment M _X	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]
Maximum Moment My	225 in1bs. [25 Nm]	40 in1bs. [5 Nm]
Maximum Moment Mz	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-3	
Temperature Range: Standard Seals		
Viton® Seals	-20°∼300° F	-30°∼150° C
Actuation	0.29 sec.	0.29 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	osition

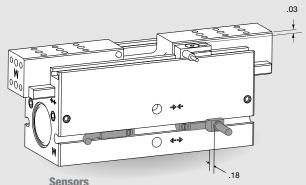
Accessory Mounting Technical Data



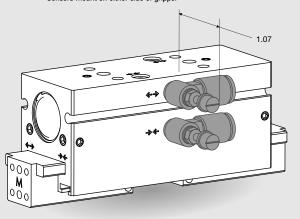


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- Choose from magneto resistive and inductive prox · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper



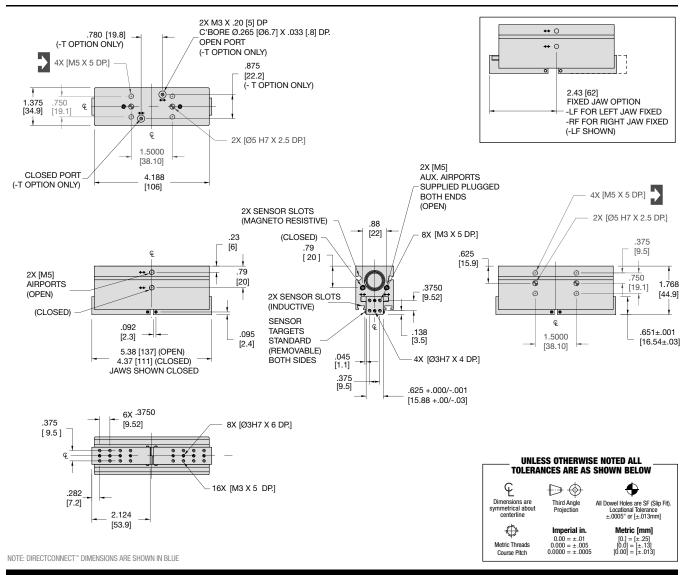
Flow Controls

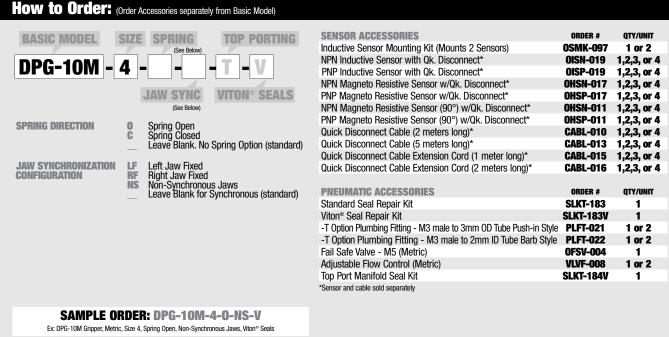
- Thumb screw adjust with locking nut for adjusting actuation time
- · Available for 5mm OD tubing

PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT™ MODULAR SERIES

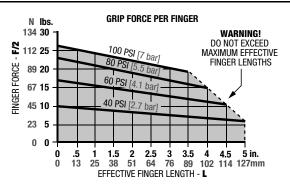








PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT MODULAR SERIES

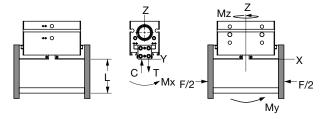


Total Additional Grip Force	Spring	Open .	Spring	Close
@ Full Open		26 N	15 lbs.	66 N
@ Full Close		97 N	6 lbs.	26 N

Specifications	DPG-10	M-4
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	1.00 in.	25.4 mm
Weight	0.81 lbs.	0.36 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm

0.306 in³.

5.0 cm³

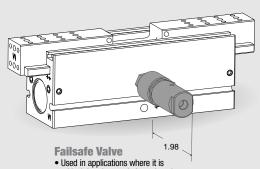


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	250 lbs. [1112 N]	35 lbs. [156 N]
Maximum Compressive C	475 lbs. [2113 N]	35 lbs. [156 N]
Maximum Moment M _X	225 in1bs. [25 Nm]	35 in1bs. [4 Nm]
Maximum Moment My	250 in1bs. [28 Nm]	45 in1bs. [5 Nm]
Maximum Moment Mz	225 in1bs. [25 Nm]	35 in1bs. [4 Nm]

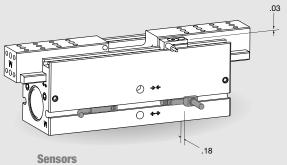
†Capacities are per set of jaws and are not simultaneous

Specifications	DPG-1	OM-4
Temperature Range: Standard SealsViton® Seals		
Actuation	0.40 sec.	0.40 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	osition

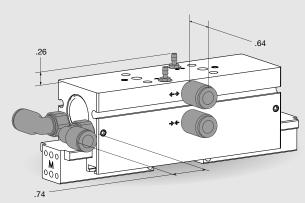
Accessory Mounting Technical Data



- critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port

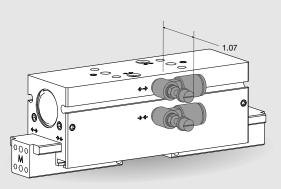


- Choose from magneto resistive and inductive prox
- Capable of sensing 4 positions open and closed on both jaws
- · PNP and NPN available
- Magneto resistive sensors are slot mounted, no mounting kits required
- Threaded quick disconnect with built-in led output
- Sensors mount on either side of gripper



Multiple Air Port Locations

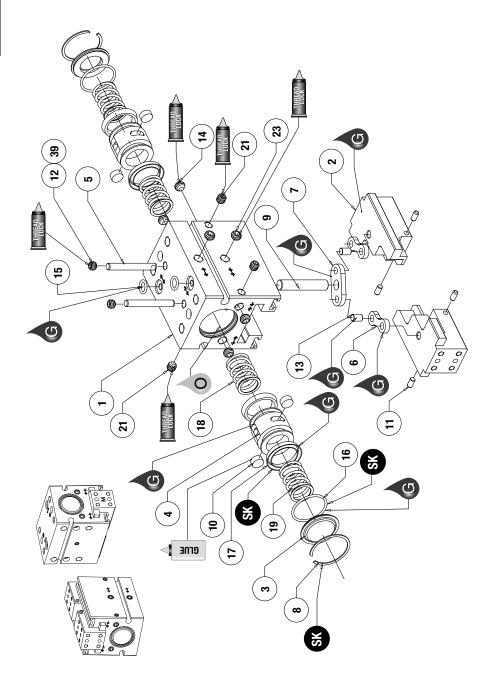
- 3 standard air port locations (front and both sides)
- . Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



Flow Controls

- . Thumb screw adjust with locking nut for adjusting actuation time
- Available for 5mm 0D tubing





	01	
Item	Qty	Name
01	1	Body
02	2	Jaw
03	2	Cap
04	2 2 2 2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
80	2	Retaining Ring
09	1	Pivot Pin
10	4	Magnet
11	4	Targets for Inductive
		Sensors
12	2	Set Screw - Drive Pin
		Access Plug
13	2	Equalizer/Synchronizing
		Bar pivot pin
14	4	Set Screw - End Port
		Plugs
15	2	O-ring - Top Porting
		Manifold Seals (-T option)
16	2 4 2	O-ring - Cap Seals
17	4	U-cup - Piston Seals Springs for "-0"
18	2	Springs for "-0"
		Spring-Open Option Springs for "-C"
19	2	Springs for "-C"
		Spring-Closed Option
21	3	Set Screw - Internal
		Porting Plugs
23	2	Set Screw - Side Porting
		Plugs (-T option)
39	1	Set Screw - Plug (-LF
		and -RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



Assembly Procedure

- 1) Lubricate body.
- Plug cross ports in body.
- Press pivot pin into body.
- Insert magnets into pistons making sure magnets attract to each other.
- Lubricate and install seals onto pistons.
- Insert pistons into body aligning drive pin hole in pistons with the drive pin hole in the body.
- Press pins into equalizer.
- Assemble equalizer with synchronizing bars and place onto pivot pin in body

- making sure holes in synchronizing bars line up with holes in pistons.
- 9) From top body mounting surface insert drive pins through the pistons and into the synchronizing bars making sure not to go through the synchronizing bars.
- 10) Place jaws into body aligning the drive pins with the hole in the jaws.
- Press drive pins into jaws.
- 12) Install drive pin plugs into body.
- Place seals onto caps and install with retaining rings.

Non-Synchronous Procedure

- Remove drive pin plugs.
 Press drive pins out of body from jaw side.
 - Remove jaws from body.
- Remove equalizer and synchronizing bars from body.
- Re-install jaws into body aligning the drive pin with the hole in the jaws
- Press drive pins into jaws.
- 7) Re-install drive pin plugs into body.











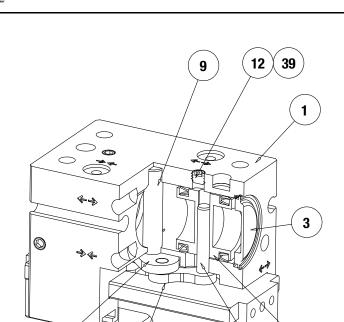








DPG SERIES ASSEMBLED VIEW



6

2

7

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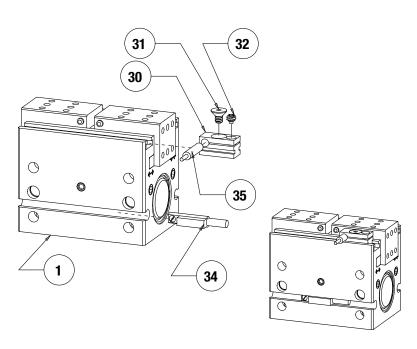
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4

Item	Qty	Name
01	1	Body
02	2	Jaw
03	2	Cap
04	2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
09	1	Pivot Pin
12	2	Set Screw - Drive Pin
		Access Plug
39	1	Set Screw - Plug (-LF and
		-RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation:

Magneto Resistive Sensors

- 1) Install sensors in profile slots of gripper body as shown.
- 2) Set sensors with integrated screw.

Inductive Sensors

- Insert sensor bracket into slot of body.
 Insert sensor into bracket and adjust
- sensor depth so that sensor light indicates on target.
- 3) Tighten sensor locking screw (#31) to hold sensor depth.
- 4) Position sensor bracket for desired stroke detection.
- 5) Tighten sensor bracket with setscrew (#32) to lock stroke detection position.

GLUE 0 Seal Kit Items Thread Locker Lightweight Machine Oil Teflon™ Based Grease Third Angle Projection

Parallel Grippers-DPDS DIRECTCONNECT** **Modular Series**

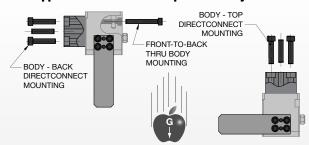




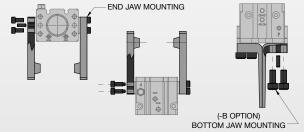
- Multiple mounting locations: DIRECTCONNECT™ tapped and dowel mounting on top and back of body.
- Thru-body mounting: Front-to-back thru-body mounting.
- Multiple air port positions: Tapped air ports on front, top, and back sides are standard.
- Front purge/scavenge port: Negative pressure used as a scavenge port for clean room applications. Positive pressure used as a purge port to repel contaminants in harsh environments. Port can also be used for lubrication.
- Manifold air porting: Top and back air ports can be manifold o-ring sealed.
- Sensing: Full range adjustable magneto resistive sensors.
- Different strokes: All gripper sizes are available in 3 different strokes.
- Multiple jaw styles: All sizes available with end mounts jaws as standard or bottom mount jaws as an option.
- Long finger applications: Rigid design and full body support of jaws allows for longer finger lengths.

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying and/or dowel pins. Fingers can be mounted in any orientation with respect to the jaw.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

20-100 psi 1.5-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Imperial

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary' **Low Moisture Content (dry)**

Metric

Temperature Operating Range

-30°~180° F -35°~80° C Buna-N Seals (standard) Viton® Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

Application Restrictions

Applications where mechanism lubricant could cause contamination (use DPDL gripper with **-E** sealed jaw option)

*Addition of lubrication will greatly increase service life *See Maintenance Section

See **1.136**

Style -DPDS Parallel Gripper DPDS-056M

See **1.138** Page

4.8 mm

DPDS-047M

3.2 mm

0.04 Kg

0.13 in

0.086 lbs.

0.19 in.

22 lbs.

Grip Force: Weight: 0.155 lbs. 0.07 Kg

-B Bottom Jaw Mount Shown

Style -DPDS Parallel Gripper

Style -DPDS Parallel Gripper

Style: Stroke:

Weight:

Style: Stroke:

Grip Force:

Size -047M

-B Bottom Jaw Mount Shown

Size -056M

Size -088M Style: DPDS-088M Stroke: 0.25 in. Grip Force: 50 lbs. Weight: 0.51 lbs 6.4 mm 222 N 0.51 lbs. 0.23 Kg



-B Bottom Jaw Mount Shown

See 1.140 Page 1.140

Style -DPDS Parallel Gripper

Size -125M Style: Stroke: 0.38 in. Grip Force: 100 lbs. Weight: 1.03 lbs. 0.46 Kg



-B Bottom Jaw Mount Shown

Product Features

Hard Coat Anodize

The body and bottom plate have hard-coat anodize 60RC with Teflon® impregnation

Dowel

Holes

Slip fit dowel pin

holes in body

and jaws

Extremely

of the body

Corrosion Resistant

Hardware (-S) or Clean Room (-CR) Options

Both options have stainless and

brass hardware. Clean room option

uses clean room grade greases

High Temperature Optional Viton® seals are available for high temperature applications

Multiple Air Port Locations 3 standard airport locations (front, back, & top)

DIRECTCONNECT

Mounting Patterns

DIRECTCONNECT™ tapped

& dowel mounting surfaces

on top and back of body

Thru-Body

Mounting

Front-to-back thru

C'bores for socket head cap screw mounting

Bottom

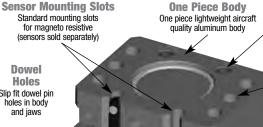
Jaw Mounting (-B) Option

For alternate finger mounting (standard side mount

jaws shown)

Manifold Air Ports Back & top air ports can be 0-ring manifold sealed to eliminate air lines





for magneto resistive (sensors sold separately)

Rugged Design Jaws are supported throughout the length

> **Purge/Scavenge Port** Used with a vacuum for clean room

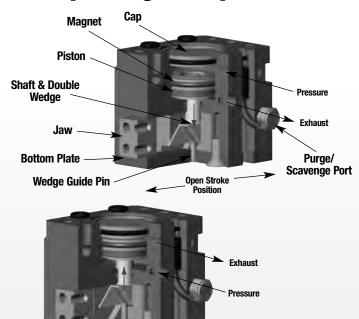
Jaw Components

Hardened and precision ground steel for minimum jaw play with hard plating for wear resistance and long life

Operating Principle

environments or positive pressure

with harsh environments



- A double acting piston is connected by a shaft to a double-sided wedge.
- The wedge slides in a slot located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.

Closed Stroke

- The large surface area of the wedge minimizes friction wear.
- . This gripper is suitable for internal or external gripping and can be mounted in any orientation.

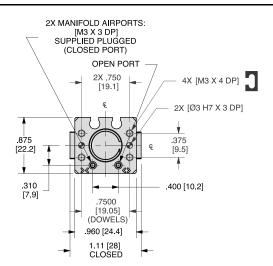
U.S. Patent # 5,125,708 **Designed and manufactured in the USA**

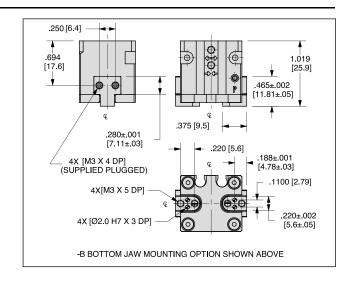
DIRECTOO

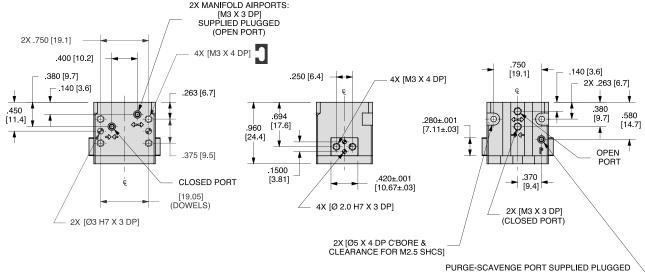
PARALLEL GRIPPER DPDS-047M **DIRECTCONNECT™ MODULAR SERIES**











UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about $\triangleright \oplus$ Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric Threads Course Pitch

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

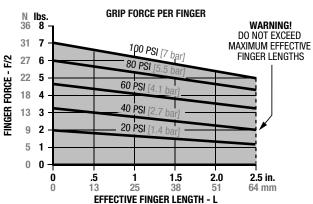
[M3 X 3 DP]

How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES** ORDER # OTY/UNIT **BASIC MODEL STROKE HARDWARE** PNP Magneto Resistive Sensor with Quick Disconnect* **OHSP-017** 1 or 2 NPN Magneto Resistive Sensor with Quick Disconnect* **OHSN-017** 1 or 2 DPDS-047M PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect* **OHSP-011** 1 or 2 **OHSN-011** NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect* 1 or 2 **JAW MOUNTING VITON® SEALS** 1 or 2 Quick Disconnect Cable (2 meters long)* CABL-010 CABL-013 Quick Disconnect Cable (5 meters long)* 1 or 2 .13" [3.2mm] .09" [2.4mm] .06" [1.6mm] STROKE 013 **PNEUMATIC ACCESSORIES** ORDER # OTY/UNIT 009 006 Standard Seal Repair Kit **SLKT-185** Viton® Seal Repair Kit **SLKT-185V JAW MOUNTING** Bottom jaw mounting Leave blank for end jaw mounting (standard) Manifold Seal Kit (Viton®) SLKT-197V Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style **PLFT-021** 1 or 2 Corrosion resistant Corrosion resistant assembled with clean room grade grease **HARDWARE** S CR Plumbing Fitting - M3 male to 2mm ID Tube Barb Style **PLFT-022** 1 or 2 *Sensor and cable sold separately Leave blank for alloy hardware (standard) **VITON®** V High Temperature Viton® Seals SAMPLE ORDER: DPDS-047M-006-B-CR-V Ex: DPDS-047M Gripper, Metric, 1.6mm Stroke, Bottom Jaw Mounting, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals



PARALLEL GRIPPER DPDS-047M DIRECTCONNECT™ MODULAR SERIES

Loading Information



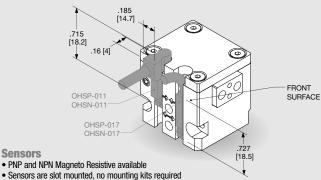
13 3		40 PSI [2			
9 2		_ 20 PSI [1.4 bar]		
5 1					
0 0					_
0	.5	1	1.5	2.0	2.5 in.
0	13	25	38	51	64 mm
0	13 EFFI	25 Ective fin	38 GER LENG	51 TH - L	64 mm
0					64 mm

	-B Option Shown	Mz Z X X X F/2 My
Loading Capacity [†] DPDS-047M	Static	Dynamic
Maximum Tensile T	30 lbs. [134 N]	6 lbs. [27 N]
Maximum Compressive C	50 lbs. [223 N]	10 lbs. [45 N]
Maximum Moment M _X	20 in1bs. [2 Nm]	5 in1bs. [0.6 Nm]
Maximum Moment My	20 in1bs. [2 Nm]	5 in1bs. [0.6 Nm]
Maximum Moment Mz	20 in1bs. [2 Nm]	5 in1bs. [0.6 Nm]
DPDS-047M-B (Bottom Jaw M	Mounting Option)	
Maximum Tensile T	24 lbs. [107 N]	5 lbs. [22 N]
Maximum Compressive C	40 lbs. [178 N]	8 lbs. [36 N]
Maximum Moment M _X	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]
Maximum Moment My	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]
Maximum Moment Mz	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]
†Capacities are per set of jaws and are no	ot simultaneous	

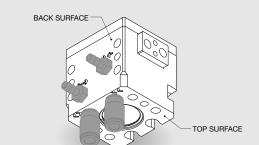
Specifications	DPDS-04	47M
Total Rated Grip Force F @ 100 psi, 7 bar	14 lbs.	− 62 N
Maximum Stroke	0.13 in.	–3.2 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.469 in.	11.9 mm
Displacement	0.013 in ³ .	0.2 cm ³

Specifications (cont.)	DPDS-0	47M
Weight	0.086 lbs.	0.04 Kg
Temperature Range: Standard Seals		-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate		osition

Accessory Mounting Technical Data

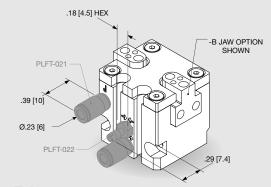


- PNP and NPN Magneto Resistive available
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting • Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



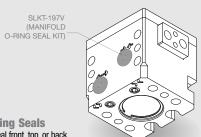
Multiple Air Port Locations

- 3 standard M3 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard



Plumbing Fittings

- M3 fitting for 2mm I.D. tube (PLFT-022 straight barbed style)
- M3 fitting for 3mm 0.D. tube (PLFT-021 straight tube push-in style)
- M3 fittings can be used in any airport including the front purge/scavenge port



Manifold O-Ring Seals

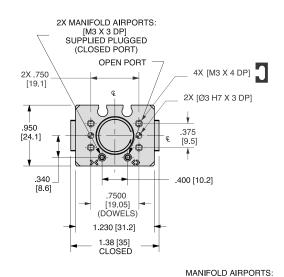
- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- 0-Ring C'bores in customer's mounting plate must be:
- Ø.215 [Ø5.5] X .060±.002 [1.52±.05] deep
- Kit is supplied with all seals, plugs, & wrenches needed

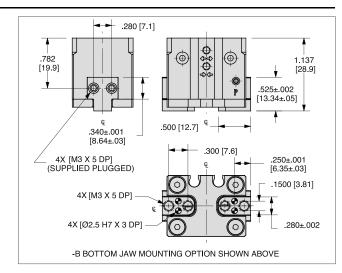
PARALLEL GRIPPER DPDS-056M **DIRECTCONNECT™ MODULAR SERIES**

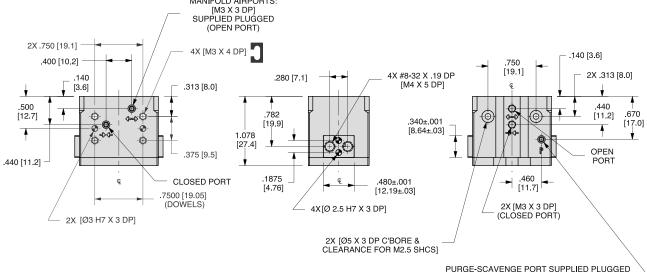












UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about $\triangleright \oplus$ Third Angle Projection

VITON®

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

[M3 X 3 DP]

How to Order: (Order Accessories separately from Basic Model) **BASIC MODEL STROKE HARDWARE** DPDS-056M **JAW MOUNTING VITON® SEALS STROKE** 019 013 **JAW MOUNT** HARDW/

ING	B	Bottom jaw mounting Leave blank for end jaw mounting (standard
ARE	S CR	Corrosion resistant Corrosion resistant assembled with clean room grade grease Leave blank for alloy hardware (standard)

High Temperature Viton® Seals

SAMPLE ORDER: DPDS-056M-009-B-CR-V

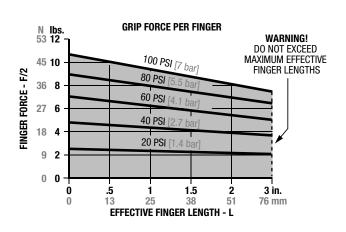
Ex: DPDS-056M Gripper, Metric, 2.4mm Stroke, Bottom Jaw Mounting, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSOR ACCESSORIES ORDER # OTY/UNIT PNP Magneto Resistive Sensor with Quick Disconnect* OHSP-017 1 or 2 NPN Magneto Resistive Sensor with Quick Disconnect* **OHSN-017** 1 or 2 PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect* **OHSP-011** 1 or 2 **OHSN-011** NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect* 1 or 2 1 or 2 Quick Disconnect Cable (2 meters long)* CABL-010 Quick Disconnect Cable (5 meters long)* CABL-013 1 or 2 **PNEUMATIC ACCESSORIES** ORDER # OTY/UNIT Standard Seal Repair Kit **SLKT-186** Viton® Seal Repair Kit **SLKT-186V** Manifold Seal Kit (Viton®) SLKT-197V Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style **PLFT-021** 1 or 2 Plumbing Fitting - M3 male to 2mm ID Tube Barb Style **PLFT-022** 1 or 2 *Sensor and cable sold separately



PARALLEL GRIPPER DPDS-056M DIRECTCONNECT™ MODULAR SERIES

-B Option Shown

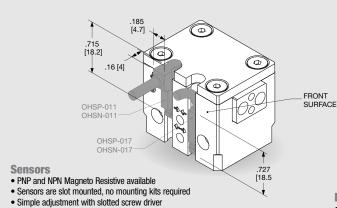


<u> </u>	T C Mx	F/2 My
Loading Capacity [†] DPDS-056M	Static	Dynamic
Maximum Tensile T	60 lbs. [267 N]	10 lbs. [45 N]
Maximum Compressive C	90 lbs. [401 N]	15 lbs. [67 N]
Maximum Moment M _X	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
Maximum Moment My	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
Maximum Moment Mz	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
DPDS-056M-B (Bottom Jaw	Mounting Option)	
Maximum Tensile T	48 lbs. [214 N]	8 lbs. [36 N]
Maximum Compressive C	72 lbs. [320 N]	12 lbs. [53 N]
Maximum Moment M _X	32 in1bs. [4 Nm]	6 in1bs. [1 Nm]
Maximum Moment My	32 in1bs. [4 Nm]	6 in1bs. [1 Nm]
Maximum Moment Mz	32 in1bs. [4 Nm]	6 inIbs. [1 Nm]
†Capacities are per set of jaws and are r	ot simultaneous	

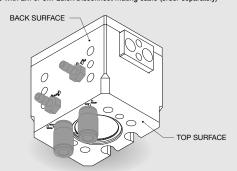
Specifications	DPDS-0	56M
Total Rated Grip Force F @ 100 psi, 7 bar	22 lbs	–98 N
Maximum Stroke	0.19 in.	–4.8 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.563 in.	14.3 mm
Displacement	0.028 in ³ .	0.5 cm ³

Specifications (cont.)	DPDS-	056M
Weight Temperature Range: Standard Seals	-30°~180° F	0.07 Kg -35°~80° C -30°~150° C
Actuation	0.16 sec. ±0.002 in.	0.16 sec. ±0.05 mm
AccuracyRepeatability		±0.03 mm
Valve Required to Actuate		oosition

Accessory Mounting Technical Data

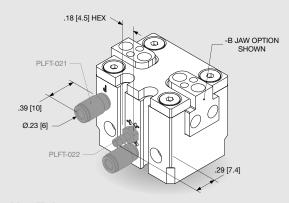


- · Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



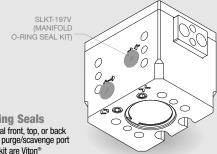
Multiple Air Port Locations

- 3 standard M3 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard



Plumbing Fittings

- M3 fitting for 2mm I.D. tube (PLFT-022 straight barbed style)
- M3 fitting for 3mm 0.D. tube (PLFT-021 straight tube push-in style)
- M3 fittings can be used in any airport including the front purge/scavenge port



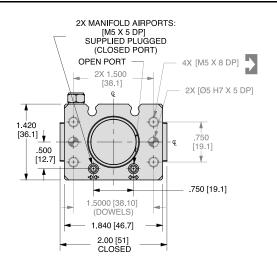
Manifold O-Ring Seals

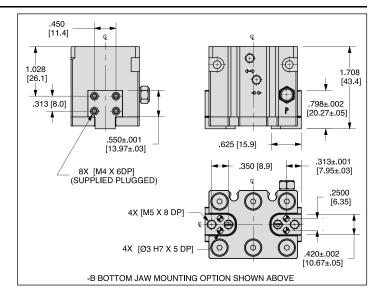
- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- . O-Ring C'bores in customer's mounting plate must be:
- Ø.215 [Ø5.5] X .060±.002 [1.52±.05] deep
- Kit is supplied with all seals, plugs, & wrenches needed

PARALLEL GRIPPER DPDS-088M DIRECTCONNECT™ MODULAR SERIES









NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

ORDER #

OHSP-017

OHSN-017

OHSP-011

OHSN-011

CABL-010

CABL-013

ORDER #

SLKT-187

SLKT-187V

SLKT-199V

VLVF-008

OFSV-004

OTY/UNIT

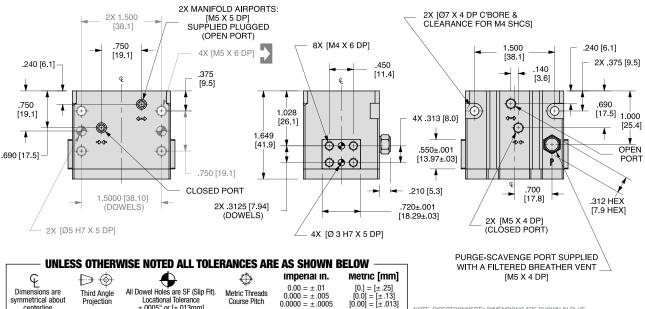
1 or 2

OTY/UNIT

1

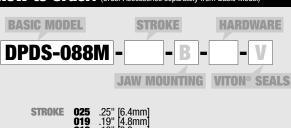
1

1 or 2



How to Order: (Order Accessories separately from Basic Model)

Projection



±.0005" or [±.013mm]

Course Pitch

013 **JAW MOUNTING** В HARDWARE

with clean room grade grease

V **VITON®**

[6.4mm] [4.8mm] [3.2mm] **PNEUMATIC ACCESSORIES** Standard Seal Repair Kit Viton® Seal Repair Kit Bottom jaw mounting Leave blank for end jaw mounting (standard) Manifold Seal Kit (Viton® Adjustable Flow Control M5 Elbow - 6mm OD Push-in (Metric) Corrosion resistant Fail Safe Valve M5 Corrosion resistant assembled *Sensor and cable sold separately Leave blank for alloy hardware (standard) High Temperature Viton® Seals

SENSOR ACCESSORIES

PNP Magneto Resistive Sensor with Quick Disconnect*

NPN Magneto Resistive Sensor with Quick Disconnect*

Quick Disconnect Cable (2 meters long)*

Quick Disconnect Cable (5 meters long)*

PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect*

NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect*

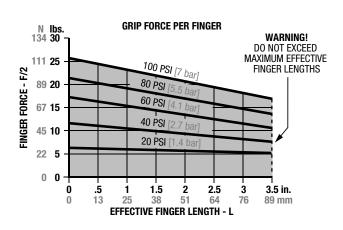
SAMPLE ORDER: DPDS-088M-019-B-CR-V

Ex: DPDS-088M Gripper, Metric, 4.8mm Stroke, Bottom Jaw Mounting, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals



PARALLEL GRIPPER DPDS-088M DIRECTCONNECT™ MODULAR SERIES

-B Option Shown

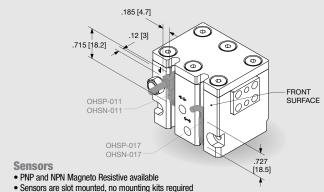


	T C Mx	F/2 - X - F/2 - F/2
Loading Capacity [†] DPDS-088M	Static	Dynamic
Maximum Tensile T	138 lbs. [614 N]	25 lbs. [111 N]
Maximum Compressive C	275 lbs. [1224 N]	25 lbs. [111 N]
Maximum Moment M _X	120 in1bs. [14 Nm]	20 in1bs. [2 Nm]
Maximum Moment My	120 in1bs. [14 Nm]	20 in1bs. [2 Nm]
Maximum Moment Mz	120 in1bs. [14 Nm]	20 in1bs. [2 Nm]
DPDS-088M-B (Bottom Jaw	Mounting Option)	
Maximum Tensile T	110 lbs. [490 N]	20 lbs. [89 N]
Maximum Compressive C	220 lbs. [979 N]	20 lbs. [89 N]
Maximum Moment M _X	96 in1bs. [11 Nm]	16 inIbs. [2 Nm]
Maximum Moment My	96 in1bs. [11 Nm]	16 inIbs. [2 Nm]
Maximum Moment Mz	96 in1bs. [11 Nm]	16 inIbs. [2 Nm]
*Capacities are per set of laws and are	not simultaneous	

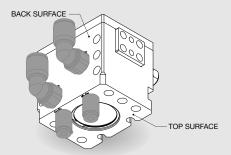
Specifications	DPDS-08	88M
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs	—222 N
Maximum Stroke	0.25 in. ———	− 6.4 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.875 in.	22.2 mm
Displacement	0.090 in ³ .	1.5 cm ³

Specifications (cont.)	DPDS-0	88M
Weight Temperature Range: Standard Seals	-30°~180° F	0.23 Kg -35°~80° C -30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy		±0.05 mm ±0.03 mm
Valve Required to Actuate	4-way, 2-p	oosition

Accessory Mounting Technical Data

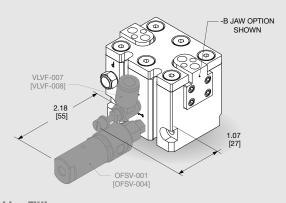


- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Multiple Air Port Locations

- 3 standard M5 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard

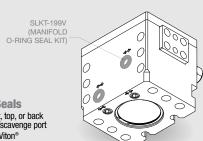


Plumbing Fittings • Adjustable flow controls:

- Have thumb screw adjust with locking nut for adjusting actuation time:
 Available for 6mm 0.D. tubing

- Failsafe valve for applications:
 Where it is critical that the part being gripped not be dropped if air pressure is lost

 - Can mount directly to gripper or in-line with plumbing to gripper
- M5 air port



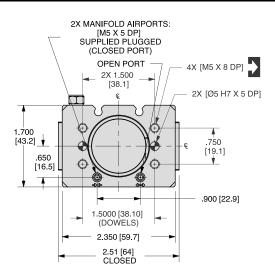
Manifold O-Ring Seals

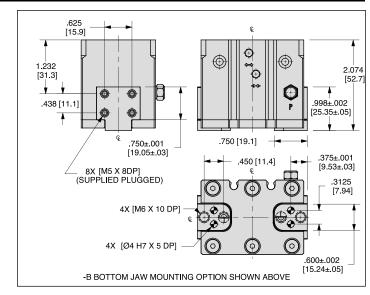
- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- . 0-Ring C'bores in customer's mounting plate must be: Ø.290 [Ø7.4] X .060±.002 [1.52±.05] deep
- Kit is supplied with all seals, plugs, & wrenches needed

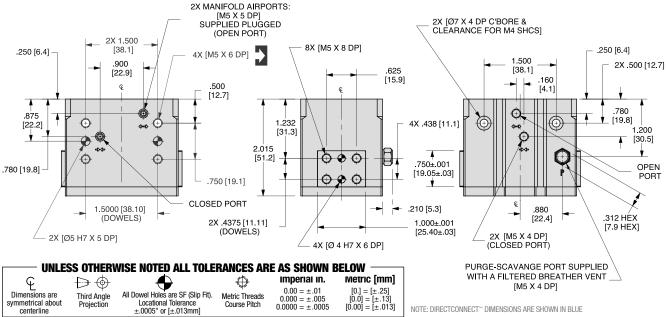
PARALLEL GRIPPER DPDS-125M DIRECTCONNECT™ MODULAR SERIES











How	to Order! (Order Accessor)	

Projection

BASIC MODEL DPDS-125N	STROKE - B -	HARDWARE V
CTDOVE 000	JAW MOUNTING	VITON® SEALS
STROKE 038 025 019	.38" [9.5mm] .25" [6.4mm] .19" [4.8mm]	

Course Pitch

	UIS	.19 [4.011111]
JAW MOUNTING	B	Bottom jaw mounting Leave blank for end jaw mounting (standard)
HARDWARE	S	Corrosion resistant

with clean room grade grease Leave blank for alloy hardware (standard) VITON® V High Temperature Viton® Seals

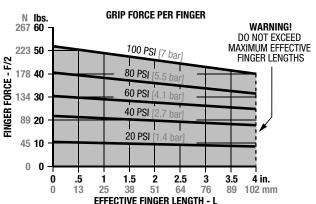
SAMPLE ORDER: DPDS-125M-025-B-CR-V

Ex: DPDS-125M Gripper, Metric, 6.4mm Stroke, Bottom Jaw Mounting, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSUR AUGESSURIES	UKDEK #	QTY/UNIT
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect*	OHSP-011	1 or 2
NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
PNEUMATIC ACCESSORIES Standard Seal Repair Kit	ORDER # SLKT-188	QTY/UNIT 1
		QTY/UNIT 1 1
Standard Seal Repair Kit	SLKT-188	1
Standard Seal Repair Kit Viton® Seal Repair Kit	SLKT-188 SLKT-188V	1
Standard Seal Repair Kit Viton® Seal Repair Kit Manifold Seal Kit (Viton®)	SLKT-188 SLKT-188V SLKT-199V	1 1 1
Standard Seal Repair Kit Viton® Seal Repair Kit Manifold Seal Kit (Viton®) Adjustable Flow Control M5 Elbow - 6mm OD Push-in (Metric)	SLKT-188 SLKT-188V SLKT-199V VLVF-008	1 1 1

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE





0	13	25 FFFFC	38 TIVE F	51 INGER	64	76 GTH - L	89	102 mm
	,			aLi		u		
Specifications						Di	PDS-	125M
Total Rated Grip Fo	rce F @	100 p	si, 7 b	ar		100 lbs.		—445 N
Maximum Stroke				0.38 in.		—9.5 mm		
Maximum Operating Pressure Range				20-100	psi	1.5-7 bar		
Maximum Vacuum for Scavenge Port				8 in. Hg		200 mm Hg		
Maximum Pressure for Purge Port					20 psi		1.4 bar	

1.250 in.

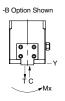
0.274 in³.

31.8 mm

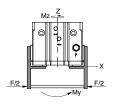
4.5 cm3



†Capacities are per set of jaws and are not simultaneous



PARALLEL GRIPPER DPDS-125M DIRECTCONNECT™ MODULAR SERIES



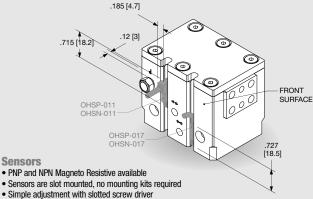
Loading Capacity [†] DPDS-125M	Static	Dynamic
Maximum Tensile T	500 lbs. [2225 N]	65 lbs. [289 N]
Maximum Compressive C	950 lbs. [4228 N]	65 lbs. [289 N]
Maximum Moment M _X	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
Maximum Moment My	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
Maximum Moment Mz	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
DPDS-125M-B (Bottom Jav	Mounting Option)	
Maximum Tensile T	400 lbs. [1780 N]	52 lbs. [231 N]
Maximum Compressive C	760 lbs. [3382 N]	52 lbs. [231 N]
Maximum Moment M _X	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]
Maximum Moment My	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]
Maximum Moment Mz	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]

Specifications (cont.)	DPDS-125M		
Weight	1.03 lbs.	0.46 Kg	
Temperature Range: Standard SealsViton® Seals		-35°~80° C -30°~150° C	
Actuation	0.30 sec.	0.30 sec.	
Accuracy	±0.003 in.	±0.08 mm	
Repeatability	±0.001 in.	±0.03 mm	
Valve Required to Actuate	4-way, 2-position		

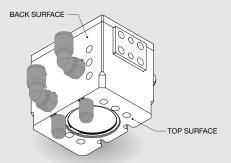
Mounting Technical Data Accessory

Cylinder Bore Ø

Displacement.

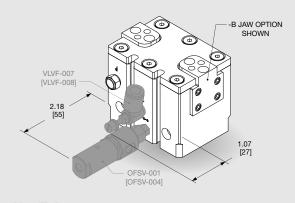


- Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Multiple Air Port Locations

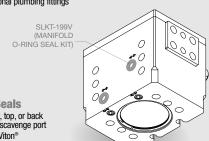
- 3 standard M5 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard



Plumbing Fittings

- · Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
 Available for 6mm 0.D. tubing

- Failsafe valve for applications:
 Where it is critical that the part being gripped not be dropped
 - if air pressure is lost
- Can mount directly to gripper or in-line with plumbing to gripper
- · Consult factory for additional plumbing fittings

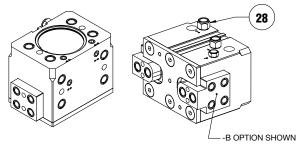


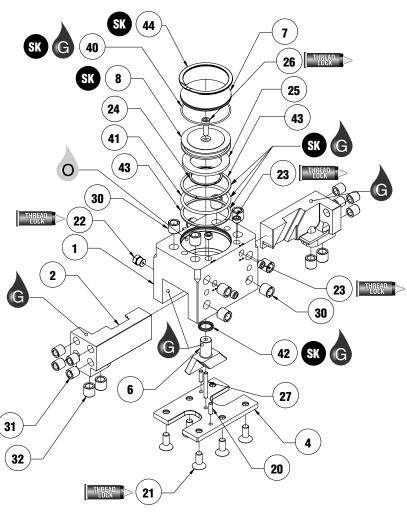
Manifold O-Ring Seals

- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- 0-Ring C'bores in customer's mounting plate must be: Ø.290 [Ø7.4] X .060±.002 [1.52±.05] deep
- Kit is supplied with all seals, plugs, & wrenches needed

DPDS SERIES EXPLODED VIEW







Assembly Procedure:

- 1) Install #23 airport plugs with thread-locker. 2) Press pins #20 & #27 Into Plate #4.
- 3) Install threaded inserts #30, #31, & #32.
- 4) Install #22 vent or plug with thread-locker.
 5) Mount magnet #25 to piston #8 with
- retainer Ring #24.
 6) Install #28 metric plumbing fitting adapters.
- 7) Lubricate body #1 (jaw cavity & bores).
- 8) Lubricate & install all seals into body, piston, & cap.
- 9) Sub-assemble the #2 jaws on either side of

the #6 shaft wedge with lubrication.

- 10) Insert the jaws and shaft wedge sub-assembly into body.
- 11) Insert piston #8 into the body bore and fasten it to the shaft wedge with Mounting
- screw # 26 using thread locker.
 12) Install cap #7 into body with retaining ring #44.
- 13) Insert #4 bottom plate with pressed-in pins onto the body and fasten with #21 screws with thread-locker.

Item	Qty	Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
04 06	1	Shaft Wedge
07	1	Cap
08 20	1	Piston
20	2	Bottom Plate
		Locating Dowels
21 22*	6	Bottom Plate Screws
22*	1	Breather Vent Plug
		(Purge)
23 24 25 26 27 28*	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
28*	2	Plumbing Fitting -
		Adapter - 1/8NPT male
		to 1/8BSPP female
30* 31*	8	Threaded Inserts (Body)
31*	8	Threaded Inserts (Jaw -
		End Mount)
32*	4	Threaded Inserts
		(Jaw - Bottom Mount
		"-B" option only)
40	1	Cap O-ring
41	1	Piston 0-ring
42 43*	1	U-cup
43*	2	Piston Teflon Ring
44	1	Cap Ret. Ring
_		

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #30 is for size -175 and -250 only.
- 3) Item #31 and #32 are for size -250 only.
- 4) Item #22 Breather vent plug is a set screw plug for sizes -047 & -056.
- 5) Item #43 is for size -175 and -250 only.
- 6) Item #28 is for metric size -175M and -250M only.













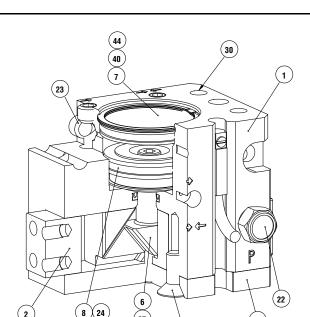








DPDS SERIES ASSEMBLED VIEW



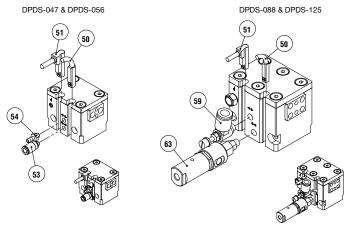
(21

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #30 is for size -175 and -250 only.
- 3) Item #31 and #32 are for size -250 only.
- 4) Item #22 breather vent plug is a set screw plug for sizes -047 & -056.
- 5) Item #43 is for size -175 and -250 only.
- 6) Item #28 is for metric size -175M and -250M only.

Item	Qty	Name
01	1	Body
02	2	Jaw
04 06	1	Bottom Plate
06	1	Shaft Wedge
07	1	Cap
08 20	1	Piston
20	2	Bottom Plate
		Locating Dowels
21 22*	6	Bottom Plate Screws
22*	1	Breather Vent Plug
		(Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
24 25 26 27 28*	1	Shaft guide dowel pin
28*	2	Plumbing Fitting -
		Adapter - 1/8NPT male
		to 1/8BSPP female
30* 31*	8	Threaded Inserts (Body)
31*	8	Threaded Inserts (Jaw -
		End Mount)
32*	4	Threaded Inserts
		(Jaw - Bottom Mount
		"-B" option only)
40	1	Cap 0-ring
41	1	Piston 0-ring
42	1	U-cup
43*	2	Piston Teflon Ring
44	1	Cap Retainer Ring

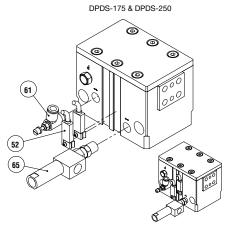
Accessory Installation & Adjustment Instructions



(25)(26) (41)(43)

Ite	em Qty	Name
50	1 or 2	Magneto Resistive Sensor (short barrel) w/Qk. Disconnect
51	1 or 2	Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect
52	1 or 2	Magneto Resistive Sensor (12mm Dovetail) w/Qk. Disconnect
53	1,2 or 3	Plumbing Fitting - M3 male to 3mm OD Push-in Style
54	1,2 or 3	Plumbing Fitting - M3 male to 2mm ID Barb Style
59	1 or 2	Adjustable Flow Control (Metric) M5 elbow - 6mm OD Push-in Style
61	1 or 2	Adjustable Flow Control (Metric) G1/8 elbow - 6mm OD Push-in Style
63	1	Fail Safe Valve (Metric) M5
65	1	Fail Safe Valve (Metric) G1/8 (1/8 BSPP)

NOTE: Other Plumbing Fittings are available for each size - Consult Factory



Magneto-Resistive Sensors:

- 1) Insert sensors #50 or #51 from either end of the profile slots and set the sensor with the integrated screw.
- 2) Insert sensor #52 into the dovetail slot at any point and set the sensor with the integrated screw & locking shoe.

Plumbing Fittings:

- 1) M3 plumbing fittings #53 & #54 can be used in any airport or purge/scavenge port.
- 2) Flow controls can be inserted and used in any open or closed airport to help control the stroke actuation.
- 3) Fail-safe valve can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Parallel Grippers-DPDL DIRECTCONNECT** **Modular Series**

- Multiple mounting locations: DIRECTCONNECT™ tapped and dowel mounting on top and back of body.
- Thru body mounting: Front-toback thru-body mounting.
- Multiple air port positions: Tapped air ports on front, top, and back sides are standard.
- Manifold air porting: Top and back air ports can be manifold o-ring sealed.
- Front purge/scavenge port: Negative pressure used as a scavenge port used for cleanroom applications. Positive pressure used as a purge port to repel contaminants in harsh environment. Port can also be used for lubrication.
- Sensing: Full range adjustable magneto resistive sensors.

- Different strokes: All gripper sizes are available in 3 different strokes.
- Multiple jaw styles: All sizes available with end mounts jaws as standard or bottom mount jaws as an option.
- True sealed jaw option: Rugged integral rubber boot seals the unit against harsh environments. Designed to be used in machine coolant and metal chip environment applications.
- Long finger applications: Rigid design and full body support of jaws allows for longer finger lengths.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals

Valve Required to Operate

Air Quality Requirements Air Filtration

Air Lubrication Air Humidity

Imperial Metric 1.5-7 bar 20-100 psi Double Acting Internally Lubricated Buna-N 4-way, 2-position

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range Buna-N Seals (standard)

-30°∼180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life

5 million cycles Normal Application w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

-E Option Seals Jaw Rubber Boot Specifications 60 Durometer Buna-N (Nitrile)

Boot Material Temperature Rating (boot only) Compatible Chemicals:

Non-Compatible Chemicals:

-20°~250° F -30°~120° C Water, Coolant, Petroleum Oils, Silicone Lubricants, Dilute Acids & Alkalis, Hydraulic Fluid,

Transmission Fluid Ozone, Ketones, Strong

Example Applications:

Acids, Brake Fluid **Grinding Dust, Machine Chip** & Coolant, Painting, Paper **Dust, Washdown Applications**

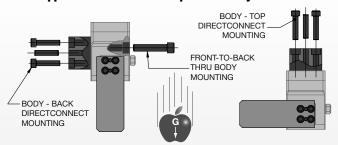
Application Restrictions

Applications where mechanism lubricant could cause contamination (use -E sealed jaw option)

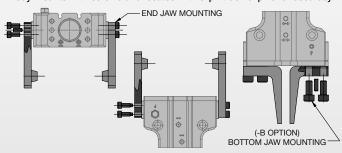
*Addition of lubrication will greatly increase service life

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying and/or dowel pins. Fingers can be mounted in any orientation with respect to the jaw.

Style -DPDL Parallel Gripper

Multiple Air Port

Locations

3 standard airport locations

(front, back, & top)

Manifold Air Ports

Back & top air ports can be 0-ring manifold sealed to

eliminate air lines

DIRECTCONNECT

Mounting Patterns

Hardened and precision

ground steel for minimum jaw play with hard plating for wear

resistance and long life

Size -047M

Style: Stroke: DPDL-047M 9.5 mm 0.38 in Grip Force: Weight: 0.186 lbs. 0.08 Kg



-B Bottom Jaw Mount Shown

Style -DPDL Parallel Gripper

Size -056M

Style: Stroke: 0.50 in. 12.7 mm Grip Force: Weight: 22 lbs. 0.315 lbs. 0.14 Kg



-B Bottom Jaw Mount Shown

See **1.150** Page

Style -DPDL Parallel Gripper

Size -088M

Style: Stroke: 0.75 in. Grip Force: 50 lbs. Weight: 0.95 lbs 19.1 mm 222 N 0.95 lbs. 0.43 Kg



-B Bottom Jaw Mount Shown

See 1.152

Style -DPDL Parallel Gripper

Size -125M

25.4 mm 445 N .00 in. Grip Force: 100 lbs. Weight: 1.99 lbs. 1.99 lbs.



-B Bottom Jaw Mount Shown

Extremely DIRECTCONNECT™ tapped & Rugged dowel mounting surfaces on Design top and back of body Jaws are Thru-Body supported **Mounting** throughout Front-to-back thru C'bores the length of the body for socket head cap screw mounting **Bottom Jaw Mounting** Sealed Jaws (-E) Option (-B) Option Buna-N bellows seal jaws against damaging hazardous environments For alternate (machining chips & coolant, grinding dust, paper mill environments, etc.) finger mounting **Purge/Scavenge Port** (standard side mount Used with a vacuum for clean room jaws shown) environments or positive pressure **Corrosion Resistant** with harsh environments Hardware (-S) or Clean **Jaw Components** Room (-CR) Options

Product Features

High Temperature

Optional Viton® seals are available

for high temperature applications

One Piece Body

One piece lightweight aircraft

quality aluminum body

Hard Coat Anodize

The body and bottom plate have hard-coat anodize 60RC with Teflon® impregnation

Sensor Mounting Slots

Standard mounting slots

for magneto resistive

(sensors sold separately)

Both options have stainless and

brass hardware. Clean room option

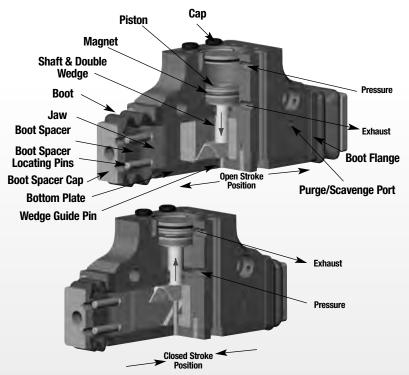
uses clean room grade greases

Operating Principle

Dowel Holes

Slip fit dowel pin holes

in body and jaws

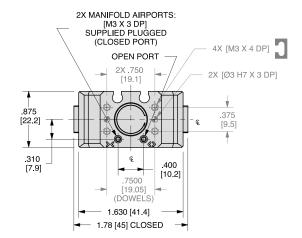


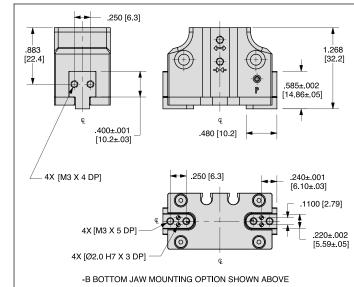
- A double acting piston is connected by a shaft to a double-sided wedge.
- The wedge slides in a slot located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.
- The large surface area of the wedge minimizes friction wear.
- · This gripper is suitable for internal or external gripping and can be mounted in any orientation.

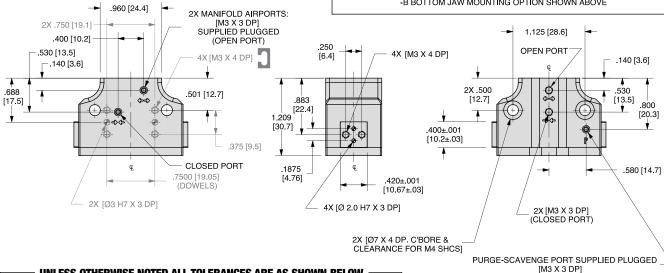
U.S. Patent # 5,125,708 Designed and manufactured in the USA

PARALLEL GRIPPER DPDL-047M **DIRECTCONNECT™ MODULAR SERIES**









UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Imperial in. \bigoplus

Dimensions are symmetrical about centerline

 \triangleright Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

Metric Threads Course Pitch

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL	STROKE	JAW SEAL**	HARDWARE
DPDL-047M]-	-B-E	
	JAW M	OUNTING	/ITON® SEALS

STROKE [9.5mm] [6.4mm] [4.8mm] 038 025

Bottom jaw mounting Leave blank for end jaw mounting (standard) **JAW MOUNTING**

JAW BOOT SEAL** E Buna-N rubber bellows **HARDWARE**

Corrosion resistant CR Corrosion resistant assembled with clean room grade grease

Leave blank for alloy hardware (standard) **VITON®**† V High Temperature Viton® Seals

SAMPLE ORDER: DPDL-047M-038-E-CR-V

Ex: DPDL-047M Gripper, Metric, 6.4mm Stroke, Jaw Boot Seal. Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSP-011	1 or 2
NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2

PNEUMATIC ACCESSURIES	UNDER #	Q11/UNII
Standard Seal Repair Kit	SLKT-185	1
Viton® Seal Repair Kit	SLKT-185V	1
Manifold Seal Kit (Viton®)	SLKT-197V	1
Sealed Jaw Boot Replacement (1 boot, Buna-N only)	SLKT-191	1 or 2
Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style	PLFT-021	1 or 2
Plumbing Fitting - M3 male to 2mm ID Tube Barb Style	PLFT-022	1 or 2

Sensor and cable sold separately

** - E Jaw Boot Seal option is not available with -B Bottom Jaw Mounting option.

See Accessory Mounting Data Section for -E Seal option dimensions.

-E Rubber Jaw Boot seals are Buna-N (Nitrile) material even if the -V Viton* gripper option is selected.

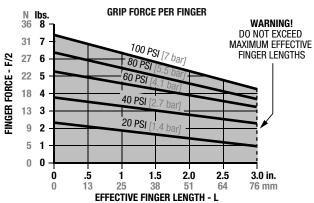
See page 1.66 for more detailed technical specifications on the -E option Jaw Boot material

-B.IAW OPTION



PARALLEL GRIPPER DPDL-047M DIRECTCONNECT™ MODULAR SERIES

Loading Information



9 2 20 PSI [1.4 bar] 5 1 0 0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm EFFECTIVE FINGER LENGTH - L	5 1 0 0 0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm EFFECTIVE FINGER LENGTH - L	5 1 0 0 0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm	FINGER F0	3			PSI [2.7 ba			
0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm	0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm EFFECTIVE FINGER LENGTH - L	0 .5 1 1.5 2.0 2.5 3.0 in. 0 13 25 38 51 64 76 mm EFFECTIVE FINGER LENGTH - L	_	_		201	31 [1.4 ba	ar]	_	
	EFFECTIVE FINGER LENGTH - L	EFFECTIVE FINGER LENGTH - L	0) 0	0	1 25				
		pecifications DPDL-047M			Ü	 				70 111111

-B Option Shown	z ←1★
T C Mx	F/2 My

Loading Capacity [†] DPDL-047M	Static	Dynamic
Maximum Tensile T	100 lbs. [445 N]	15 lbs. [67 N]
Maximum Compressive C	150 lbs. [668 N]	25 lbs. [111 N]
Maximum Moment M _X	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
Maximum Moment My	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
Maximum Moment Mz	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
DPDL-047M-B (Bottom Jaw	Mounting Option)	
Maximum Tensile T	80 lbs. [356 N]	12 lbs. [53 N]
Maximum Compressive C	120 lbs. [534 N]	20 lbs. [89 N]
Maximum Moment M _X	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
Maximum Moment My	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
Maximum Moment Mz	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
†Capacities are per set of jaws and are	not simultaneous	

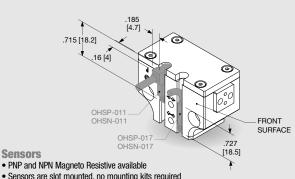
Specifications	DPDL-0	47M
Total Rated Grip Force F @ 100 psi, 7 bar	14 lbs	—62 N
Maximum Stroke	0.38 in. ——	—9.5 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.469 in.	11.9 mm
Displacement	0.038 in ³ .	0.6 cm ³

Specifications (cont.)	DPDL-0	47M
Weight	0.186 lbs.	0.08 Kg
Temperature Range: Standard SealsViton® Seals		-35°~80° C -30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-p	oosition

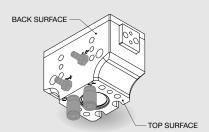
.18 [4.5] HEX

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Accessory Mounting Technical Data

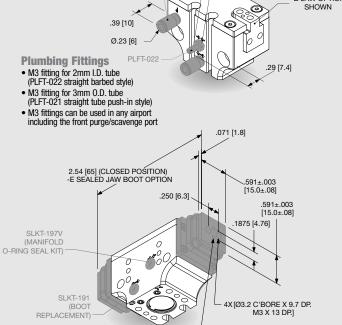


- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Multiple Air Port Locations

- 3 standard M3 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard



Manifold O-Ring Seals

- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- . O-Ring C'bores in customer's mounting plate must be: Ø.215 [Ø5.5] X .060±.002 [1.52±.05] deep
- Kit is supplied with all seals, plugs, & wrenches needed

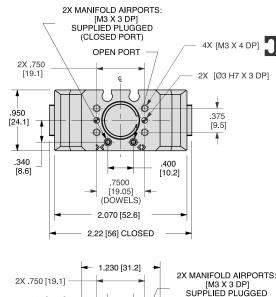
Sealed Jaw Boot Option

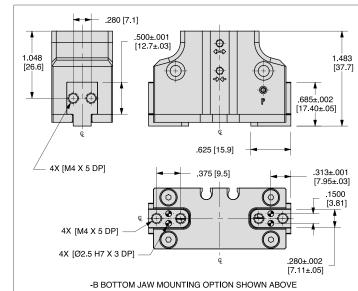
└ 4X [2.0 H7 X 2 DP.]

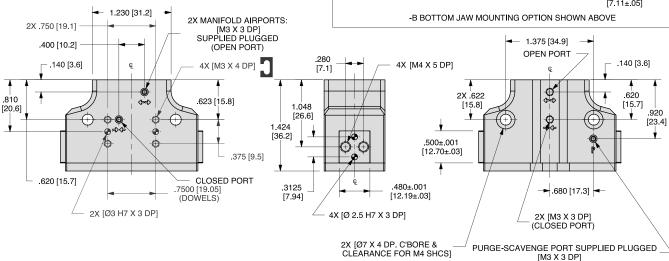
- Can be used to seal jaws in harsh environments
- · Boot replacement available as an accessory
- · Boot material is Buna-N (Nitrile) only

PARALLEL GRIPPER DPDL-056M **DIRECTCONNECT™ MODULAR SERIES**









UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] \bigoplus Imperial in. Metric [mm] \triangleright $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Dimensions are Third Angle Metric Threads symmetrical about Projection Course Pitch

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order:	(Order Accessories separately from Basic Model)

BASIC MODEL	STROKE	JAW SEAL**	HARDWARE
DPDL-056M	_	- B - E	- V
	JAW M	OUNTING	VITON® SEALS

STROKE	050 038 025	.50" [12.7mm] .38" [9.5mm] .25" [6.4mm]

JAW MOUNTING B Bottom jaw mounting Leave blank for end jaw mounting (standard)

JAW BOOT SEAL** E Buna-N rubber bellows

HARDWARE S CR

centerline

Corrosion resistant Corrosion resistant assembled with clean room grade grease

Leave blank for alloy hardware (standard) VITON®† V High Temperature Viton® Seals

SAMPLE ORDER: DPDL-056M-038-E-CR-V

Ex: DPDL-056M Gripper, Metric, 12.7mm Stroke, Jaw Boot Seal Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSP-011	1 or 2
NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2

UKDEK #	QTY/UNIT
SLKT-186	1
SLKT-186V	1
SLKT-197V	1
SLKT-192	1 or 2
PLFT-021	1 or 2
PLFT-022	1 or 2
	SLKT-186 SLKT-186V SLKT-197V SLKT-192 PLFT-021

Sensor and cable sold separately

"Sensor and cable solur separately

** - E Jaw Boot Seal option is not available with - B Bottom Jaw Mounting option.

See Accessory Mounting Data Section for -E Seal option dimensions.

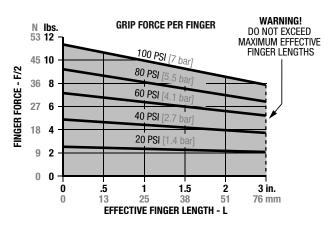
† -E Rubber Jaw Boot seals are Buna-N (Nitrile) material even if the -V Viton® gripper option is selected.

See page 1.66 for more detailed technical specifications on the -E option Jaw Boot material

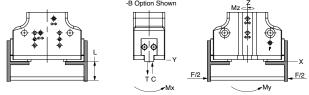


PARALLEL GRIPPER DPDL-056M **DIRECTCONNECT™ MODULAR SERIES**

Loading Information



Specifications	DPDL-05	6M
Total Rated Grip Force F @ 100 psi, 7 bar	22 lbs	—98 N
Maximum Stroke	0.50 in.	—12.7 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.563 in.	14.3 mm
Dienlacement	0.074 in^3	1.2 cm ³



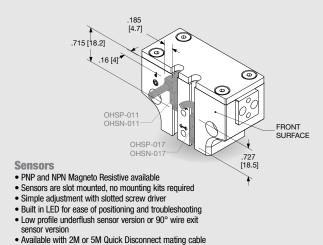
Loading Capacity [†] DPDL-056M	Static	Dynamic	
Maximum Tensile T	125 lbs. [556 N]	25 lbs. [111 N]	
Maximum Compressive C	250 lbs. [1113 N]	25 lbs. [111 N]	
Maximum Moment Mx	115 inlbs. [13 Nm]	20 inIbs. [2 Nm]	
Maximum Moment My	115 inIbs. [13 Nm]	20 in1bs. [2 Nm]	
Maximum Moment Mz	115 inlbs. [13 Nm]	20 in1bs. [2 Nm]	
DPDL-056M-B (Bottom Jav	/ Mounting Option)		
Maximum Tensile T	100 lbs. [445 N]	20 lbs. [89 N]	
Maximum Compressive C	200 lbs. [890 N]	20 lbs. [89 N]	
Maximum Moment M _X	92 in1bs. [10 Nm]	16 inIbs. [2 Nm]	
Maximum Moment My	92 in1bs. [10 Nm]	16 inIbs. [2 Nm]	

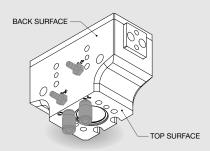
Maximum Moment Mz	92 in1bs.	[10 Nm]
*Capacities are per set of laws and are not	simultaneous	

Specifications (cont.)	DPDL-05	56M
Weight	0.315 lbs.	0.14 Kg
Temperature Range: Standard Seals		-35°~80° C
Viton® Seals		-30°~150° C
Actuation	0.25 sec.	0.25 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-position	

16 in.-lbs. [2 Nm]

Accessory Mounting Technical Data

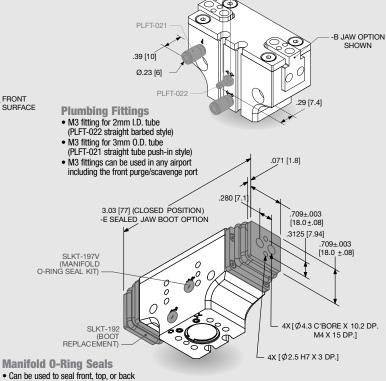




Multiple Air Port Locations

(order separately)

- 3 standard M3 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard



Sealed Jaw Boot Option

- Can be used to seal jaws in harsh environments
- · Boot replacement available as an accessory
- · Boot material is Buna-N (Nitrile) only

air ports and front purge/scavenge port Seals in Manifold kit are Viton®

Ø.215 [Ø5.5] X .060±.002 [1.52±.05] deep

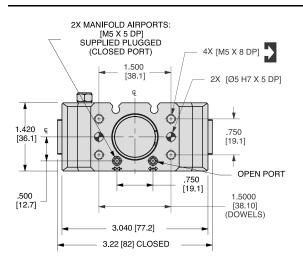
. O-Ring C'bores in customer's mounting plate must be:

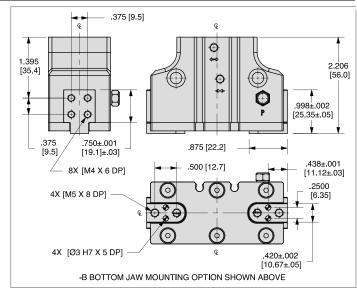
· Kit is supplied with all seals, plugs, & wrenches needed

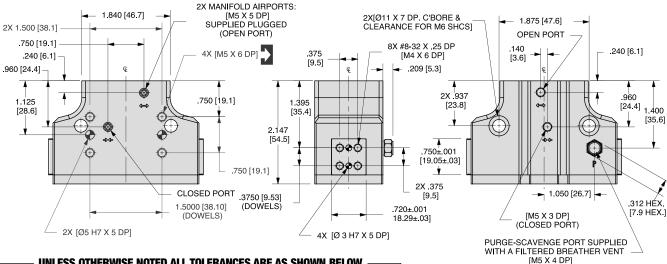
PARALLEL GRIPPER DPDL-088M DIRECTCONNECT™ MODULAR SERIES











UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about $ightarrow \Phi$ Third Angle Projection

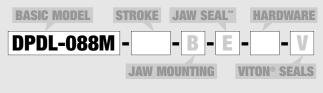
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric Threads Course Pitch

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)



.75" [19.1mm] .50" [12.7mm] .38" [9.5mm] **STROKE** 075 050 038

Bottom jaw mounting Leave blank for end jaw mounting (standard) **JAW MOUNTING** В

JAW BOOT SEAL** E Buna-N rubber bellows

HARDWARE

Corrosion resistant Corrosion resistant assembled with clean room grade grease Leave blank for alloy hardware (standard)

VITON®† V High Temperature Viton® Seals

SAMPLE ORDER: DPDL-088M-050-E-CR-V

Ex: DPDL-088M Gripper, Metric, 12.7mm Stroke, Jaw Boot Seal, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSP-011	1 or 2
NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2

UNDER #	Q11/UNII
SLKT-187	1
SLKT-187V	1
SLKT-199V	1
SLKT-193	1 or 2
ric) VLVF-008	1 or 2
OFSV-004	1 or 2
	SLKT-187 SLKT-187V SLKT-199V SLKT-193 ric) VLVF-008

Sensor and cable sold separately

Seriou and cause sour separatery
** - E Jaw Boot Seal option is not available with -B Bottom Jaw Mounting option.

See Accessory Mounting Data Section for -E Seal option dimensions.

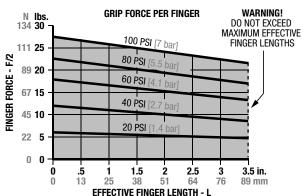
-E Rubber Jaw Boot seals are Buna-N (Nitrile) material even if the -V Viton® gripper option is selected.

See page 1.66 for more detailed technical specifications on the -E option Jaw Boot material

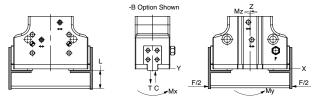


PARALLEL GRIPPER DPDL-088M DIRECTCONNECT™ MODULAR SERIES

Loading Information



	134 30 -	1	u 101102	Littingen	DO NOT	
	111 25 -		100 PS	[7 bar]	Maximum Finger i	EFFECTIVE LENGTHS
. F/2		_	80 PSI [5.5 bar]		
P.CF.	00 20		60 PSI [4.1 bar]		
B EO	67 15 -		40 PSI [)
FINGER FORCE - F/2	45 10 -		20 PSI			
	22 5		20 F31	r.4 parj		
	0 0-					
	(.5	1 1.5	2 2.5	3 3.5 iı	1.
	(0 13	25 38	51 64	76 89 m	m
		El	FFECTIVE FIN	GER LENGTH :	- L	



Loading Capacity [†] DPDL-088M	Static	Dynamic		
Maximum Tensile T	350 lbs. [1558 N]	40 lbs. [178 N]		
Maximum Compressive C	650 lbs. [2893 N]	40 lbs. [178 N]		
Maximum Moment M _X	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
Maximum Moment My	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
Maximum Moment Mz	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
DPDL-088M-B (Bottom Jaw Mounting Option)				
Maximum Tensile T	280 lbs. [1246 N]	32 lbs. [142 N]		
Maximum Compressive C	520 lbs. [2314 N]	32 lbs. [142 N]		
Maximum Moment M _X	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		
Maximum Moment My	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		
Maximum Moment Mz	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		

Specifications	DPDL-088M	
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs	—222 N
Maximum Stroke	0.75 in. ——	—19.1 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)		1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.875 in.	22.2 mm
Displacement	0.269 in ³ .	4.4 cm ³

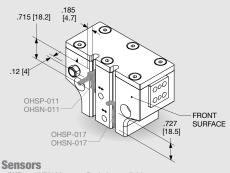
Specifications (cont.)	DPDL-088M	
Weight		0.43 Kg
Temperature Range: Standard Seals		-35°~80° C
Viton® Seals	-20°~300° F 0.30 sec.	-30°~150° C 0.30 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-position	

†Capacities are per set of jaws and are not simultaneous

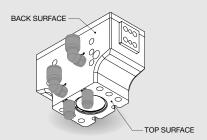
VLVF-008

[55]

Accessory Mounting Technical Data



- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)

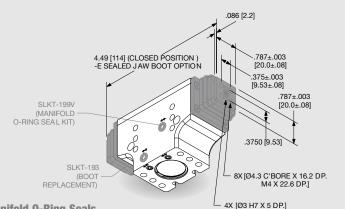


Multiple Air Port Locations

- 3 standard M5 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard

Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut
- for adjusting actuation time:
 Available for 6mm 0.D. tubing
- Failsafe valve:
- For applications where it is critical that the part being gripped not be dropped if air pressure is lost:
- Can mount directly to gripper or in-line with plumbing to gripper
- M5 air port
- · Consult factory for additional plumbing fittings



Manifold O-Ring Seals

- Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- O-Ring C'bores in customer's mounting plate must be: Ø.290 [Ø7.4] X .060±.002 [1.52±.05] deep
- · Kit is supplied with all seals, plugs, & wrenches needed

Sealed Jaw Boot Option

- Can be used to seal jaws in harsh environments
- · Boot replacement available as an accessory
- · Boot material is Buna-N (Nitrile) only



B JAW OPTION

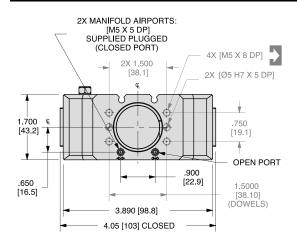
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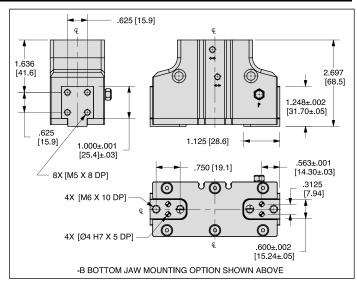
[27]

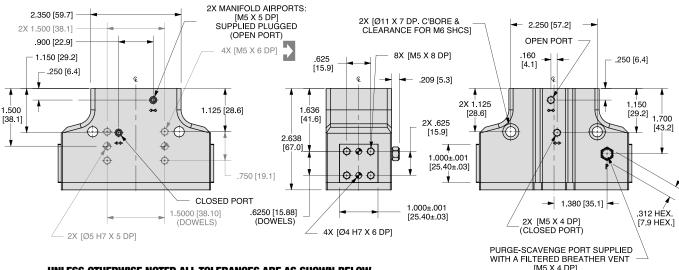
PARALLEL GRIPPER DPDL-125M DIRECTCONNECT™ MODULAR SERIES











UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about

 $ightarrow \Phi$ Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

 \bigoplus Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL	STROKE	JAW SEAL**	HARDWARE
	_		
DPDL-125N	/ I-	- B - E	V
	JAW M	OUNTING	VITON® SEALS

1.00" [25.4mm] .75" [19.1mm] .50" [12.7mm] 075 050

JAW MOUNTING Bottom jaw mounting Leave blank for end jaw mounting (standard)

JAW BOOT SEAL** E Buna-N rubber bellows

HARDWARE S

Corrosion resistant Corrosion resistant assembled with clean room grade grease

Leave blank for alloy hardware (standard) VITON®† V High Temperature Viton® Seals

SAMPLE ORDER: DPDL-125M-075-E-CR-V

Ex: DPDL-125M Gripper, Metric, 25.4mm Stroke, Jaw Boot Seal, Corrosion Resistant Hardware with Clean Room Grade Grease, Viton® Seals

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSP-011	1 or 2
NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc.*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2

PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Standard Seal Repair Kit	SLKT-188	1
Viton® Seal Repair Kit	SLKT-188V	1
Manifold Seal Kit (Viton®)	SLKT-199V	1
Sealed Jaw Boot Replacement (1 boot, Buna-N only)	SLKT-194	1 or 2
Adj. Flow Control M5 Elbow - 6mm OD Push-in (Metric)	VLVF-008	1 or 2
Fail Safe Valve M5	0FSV-004	1 or 2

Sensor and cable sold separately

** - E Jaw Boot Seal option is not available with -B Bottom Jaw Mounting option.

See Accessory Mounting Data Section for -E Seal option dimensions.

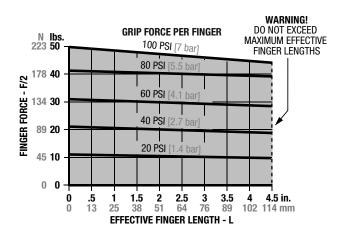
† -E Rubber Jaw Boot seals are Buna-N (littile) material even if the -V Viton* gripper option is selected.

See page 1.66 for more detailed technical specifications on the -E option Jaw Boot material

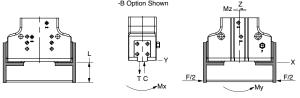




Loading Information



Specifications	DPDL-1	25M
Total Rated Grip Force F @ 100 psi, 7 bar	100 lbs	− 445 N
Maximum Stroke	1.00 in.	—25.4 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)		1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	0.730 in ³ .	12.0 cm ³



PARALLEL GRIPPER DPDL-125M DIRECTCONNECT™ MODULAR SERIES

Loading Capacity [†] DPDL-125M	Static	Dynamic		
Maximum Tensile T	675 lbs. [3004 N]	90 lbs. [401 N]		
Maximum Compressive C	1300 lbs. [5785 N]	90 lbs. [401 N]		
Maximum Moment M _X	650 in1bs. [73 Nm]	110 inIbs. [12 Nm]		
Maximum Moment My	650 in1bs. [73 Nm]	110 in1bs. [12 Nm]		
Maximum Moment Mz	650 in1bs. [73 Nm]	110 in1bs. [12 Nm]		
DPDL-125M-B (Bottom Jaw Mounting Option)				
Maximum Tensile T	540 lbs. [2403 N]	72 lbs. [320 N]		
Maximum Compressive C	1040 lbs. [4628 N]	72 lbs. [320 N]		

520 in.-Ibs. [59 Nm]

88 in.-1bs. [10 Nm]

88 in.-Ibs. [10 Nm]

88 in.-1bs. [10 Nm]

-B JAW OPTION SHOWN

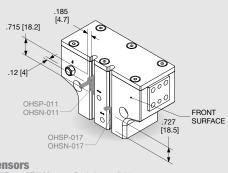
Maximum Moment wy	520 III108. [59 NIII]
Maximum Moment Mz	520 in1bs. [59 Nm]
†Capacities are per set of jaws and are	not simultaneous

VLVF-008

Maximum Moment Mx

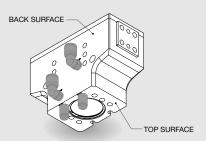
Specifications (cont.)	DPDL-125M	
WeightTemperature Range: Standard Seals	-30°~180° F	0.90 Kg -35°~80° C -30°~150° C
Actuation	0.50 sec.	0.50 sec.
Accuracy	±0.003 in.	±0.08 mm
RepeatabilityValve Required to Actuate		±0.03 mm position

Accessory Mounting Technical Data



Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



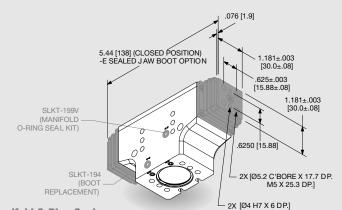
Multiple Air Port Locations

- 3 standard M5 air port locations (front, top, and back surface)
- Top and Back air ports are plugged as standard

Plumbing Fittings • Adjustable flow controls:

- Have thumb screw adjust with locking nut for adjusting actuation time:

 - Available for 6mm 0.D. tubing
- Failsafe valve:
- For applications where it is critical that the part being gripped not be dropped if air pressure is lost
- Can mount directly to gripper or in-line with plumbing to gripper - M5 air port
- · Consult factory for additional plumbing fittings



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Manifold O-Ring Seals

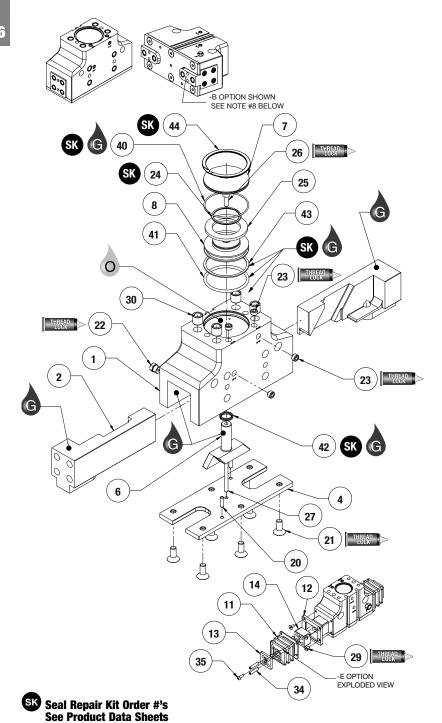
- . Can be used to seal front, top, or back air ports and front purge/scavenge port
- Seals in Manifold kit are Viton®
- O-Ring C'bores in customer's mounting plate must be: Ø.290 [Ø7.4] X .060±.002 [1.52±.05] deep
- · Kit is supplied with all seals, plugs, & wrenches needed

Sealed Jaw Boot Option

- Can be used to seal jaws in harsh environments
- · Boot replacement available as an accessory
- · Boot material is Buna-N (Nitrile) only

DPDL SERIES EXPLODED VIEW





Item	Q	ty Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
04 06* 07	1	Shaft Wedge
07	1	Cap
80	1	Piston
11	2	Boot
12	2	Boot Flange
13	2	Boot Spacer Cap
14		Boot Spacer
20	2	Bottom Plate Locating Dowels
21 22*	6	Bottom Plate Screws
22*	1	Breather Vent Plug (Purge)
23	4	Manifold Port Plugs
24 25	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
27 29	8	Boot Flange Mounting Screws
34	4	Boot Spacer Dowel Pins
35*	2	Boot Spacer Mtg Screws
40	1	Cap 0-ring
41	1	Piston 0-ring
42	1	U-cup
44	1	Cap Ret. Ring

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 4) Item #22 Breather vent plug is a set screw plug for sizes -047 & -056.
- 7) Item #35 is for sizes -088 thru -125 only.
- 8) End-of-jaw mounting holes on -B option are supplied plugged to prevent debris from entering the gripper. These set screws can be removed for customer finger mounting. It is recommend that all unused holes be plugged for the same reason.

Assembly Procedure:

- 1) Install #23 airport plugs with thread-locker. 2) Press pins #20 & #27 into plate #4.
- 3) Install #22 vent or plug with thread-locker.
- 4) Mount magnet #25 to piston #8 with retaining ring #24.
- 5) Lubricate body #1 (jaw cavity & bores).
- 6) Lubricate & install all seals into body, piston, & cap.
- 7) Sub-assemble the #2 jaws on either side of the #6 shaft wedge with lubrication.
 8) Insert the jaws and shaft wedge
- sub-assembly into body.

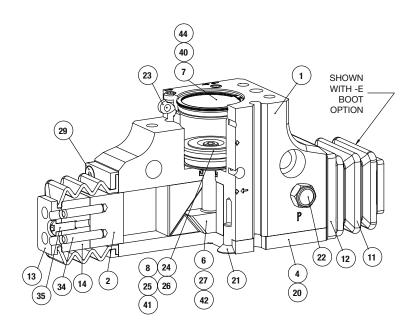
- 9) Insert piston #8 into the body bore and fasten it to the shaft wedge with Mounting screw # 26 using thread locker.
- 10) Install cap #7 into body with retaining ring #44.
- 11) Insert #4 bottom plate with pressed-in pins onto the body and fasten with #21 screws with thread-locker.

-E Option Assembly Procedure:

- 1) Insert pins #34 into the jaw dowel pin holes.
- 2) Place #14 boot spacer over pins
- 3) Fasten boot #11 and flange #12 to body #1 with #29 screws.
- 4) Fasten the spacer cap #13 to the spacer #14 with #35 screw.

DPDL SERIES ASSEMBLED VIEW



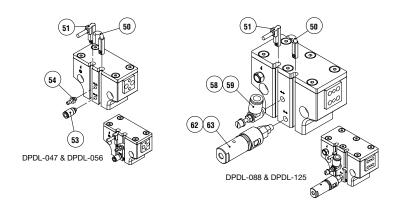


Item	Qty	Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
06*	1	Shaft Wedge
07	1	Cap
08	1	Piston
11	2	Boot
12	2	Boot Flange
13	2	Boot Spacer Cap
14	2	Boot Spacer
20	2	Bottom Plate Locating Dowels
21	6	Bottom Plate Screws
22*	1	Breather Vent Plug (Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
27 29	8	Boot Flange Mounting Screws
34	4	Boot Spacer Dowel Pins
35*	2	Boot Spacer Mtg Screws
40	1	Cap O-ring
41	1	Piston 0-ring
42	1	U-cup
44	1	Cap Ret. Ring

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #22 breather vent plug is a set screw plug for sizes -047 & -056.

Accessory Installation & Adjustment Instructions



Magneto-Resistive Sensors:

1) Insert sensors #50 or #51 from either end of the profile slots and set the sensor with the integrated screw.

Plumbing Fittings:

- 1) M3 plumbing fittings #53 & #54 can be used in any airport or purge/scavenge port.
- 2) Flow controls can be inserted and used in any open or closed airport to help control the stroke actuation.
- 3) Fail-safe valve can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Ite	em Qty	Name
50	1 or 2	Magneto Resistive Sensor (short barrel) w/Qk. Disconnect
51	1 or 2	Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect
53	1,2, or 3	Plumbing Fitting - M3 male to 3mm OD Push-in Style
54	1,2, or 3	Plumbing Fitting - M3 male to 2mm ID Barb Style
59	1 or 2	Adj. Flow Control (Metric) M5 elbow - 6mm OD Push-in Style
63	1	Fail Safe Valve (Metric) M5

NOTE: Other Plumbing Fittings are available for each size - Consult Factory



Compact and robust design

This gripper is designed for use in confined spaces, combining long strokes with the high gripping force provided by two simultaneously acting pistons.

• For long finger applications:

Jaws are supported throughout the length of the body, enabling long fingers.

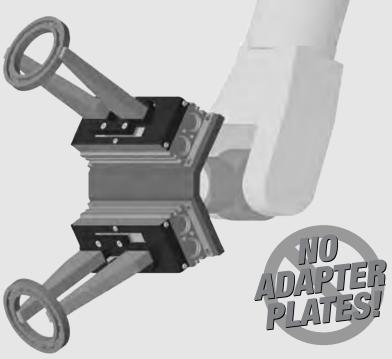
• Multipurpose gripper:

A wide range of options and accessories (safety springs, in-line jaws, magneto resistive or inductive sensors) allow these grippers to be used in a number of applications.

• Harsh environments:

Enclosed, shielded design repels chips and other particulate from internal drive mechanism.

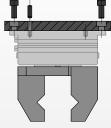
• Spring assist, spring return: Can be used as failsafe, single acting spring return, or double acting spring assist.

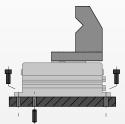


Mounting Information:

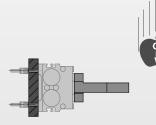
Grippers can be mounted & operated in any orientation

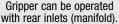
The gripper is protected from falling debris when it is mounted and operated upside down.

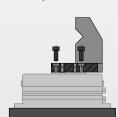




Gripper locates from the top with 2 dowel pins and can be assembled with 4 screws from the top or bottom.







Fingers are located on jaws with 2 dowel pins and assembled with 2 screws.

Technical Specifications:

Imperial	Metric
30-100 psi	2-7 bar
60-100 psi	4-7 bar
Double Acting	
Internally Lubric	ated Buna-N
y, 2-position for I	Double Acting
ay, 2-position for	r Single Acting
	30-100 psi 60-100 psi Double A Internally Lubric y, 2-position for l

Air Quality Requirements

Air Filtration 40 Micron or Better Not Necessary* Air Lubrication Air Humidity **Low Moisture Content (dry)**

Temperature Operating Range

Buna-N Seals (Standard) -4°~180° F -20°~80° C

Maintenance Specifications[†]

Expected Life

5 million cycles Normal Application 10+ million cycles* w/ Preventative Maintenance Field Repairable Yes Seal Repair Kits Available Yes

*Addition of lubrication will greatly increase service life †See Maintenance Section





Size -2520

In-Line Jaws

Optional In-I ine Jaws

for simplified finger

design: 2 interfaces can

be fixed on to the jaws.

Gripper Mounting Either from the top

or bottom

Inductive Sensor

Mounting Kit

Mounting kit has 2 flags and

Style: Stroke: **DPL-2520** 7 in. 40 mm 1.57 in. Grip Force: 182 lbs. Weight: 3.04 lbs.



See 1.160

1.38 Kg

Style-DPL Parallel Gripper

Size -2535

Style: Stroke: Grip Force: Weight:

70 mm 173 lbs. 768 N 3.97 lbs. 1.80 Kg



See **1.161**



Operating Principle

Magnetic Sensor

Piston is equipped with the

magnet and the body has

mounting slots.

Product Features

Shielded Design

Gripper body is shielded to repel chips and other

particulate from internal

drive mechanism.

Quality Components

Made of aluminum alloy with Teflon™ impregnated hard coat anodize.

The device's main components

are made of heat treated steel.

Spring Assist

Option (-R) to restrain the component, should the air supply fail or to use

the gripper in single acting mode by

clamping on the shaft or the bore.

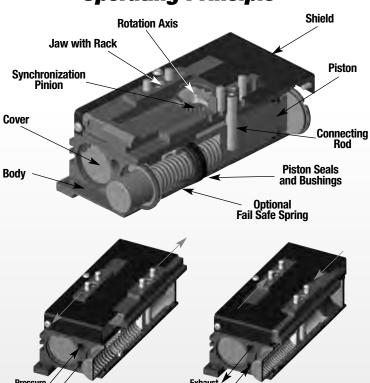
DIRECTCONNEC Mounting Patterns DIRECTCONNECT™ mounting surface on back of body

Air Ports

Either lateral on

2 sides (couplings) or at the rear

(manifold sealing)



- Dual double acting pistons connected to both jaws and synchronized by the pinion actuate in opposite directions.
- Each jaw is guided by a T-slot in the body.
- Jaw Synchronization is achieved by a rack and pinion system.
- For Non-Synchronous operation, the pinion can be removed.
- Suitable for internal or external gripping.

Style-DPL Parallel Gripper

Size -3230

Style: Stroke: Grip Force: Weight:

DPL-3230 2.36 in. 306 lbs. 1359 N 4.98 lbs.

See **1.162** Page

2.26 Kg

Style-DPL Parallel Gripper

Size -3250

Style: Stroke: Grip Force: Weight:

DPL-3250 3.94 in. 100 mm 294 lbs. 1306 N 6.66 lbs. 3.02 Kg



See 1.163

Style-DPL Parallel Gripper

Size -4040

Style: Stroke:

DPL-4040 3.15 in. 457 lbs. 9.48 lbs. 2035 N

4.30 Kg



See 1.164 Page 1.164

Style-DPL Parallel Gripper

Size -4070

Style: **Stroke:** 5.51 in. **Grip Force:** 456 lbs. **Weight:** 13.23 lbs.

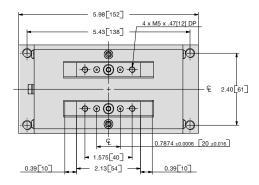
140 mm 2029 N 13.23 lbs.

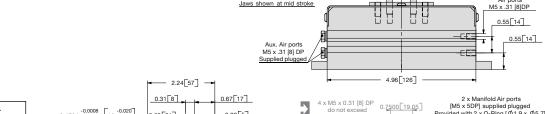


PARALLEL GRIPPER DPL-2520 TWO JAW LONG STROKE

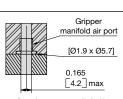


Specifications	DPL-2520		
Total Rated Grip Force F @ 100 psi, 7 bar*	182 lbs.	811 N	
Stroke	1.57 in	40 mm	
Weight	3.04 lbs.	1.38 kg	
Pressure Range (without springs)	30-100 psi	2-7 bar	
Pressure Range (with springs)	60-100 psi	4-7 bar	
Cylinder Bore Ø	0.98 in.	25 mm	
Displacement	2.38 in ³ .	39 cm ³	
Temperature Range	-4°~180° F	-20°~80° C	
Actuation (open/close)	0.3/0.3 se	c.	
Accuracy	±0.003 in.	±0.08 mm	
Repeatability	±0.0010 in.	±0.025 mm.	
Valve required to actuate single acting	3-way 2-p	osition	
Valve required to actuate double acting	4-way, 2-p	osition	



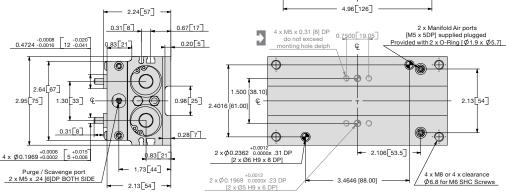


Jaws shown at mid stroke



* With springs.

Our grippers are supplied with open side air ports and top air ports plugged. When operating top air ports, produce manifold sealing as shown (seals are provided with your gripper in a sealed bag)



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

 $\Rightarrow \phi$ Third Angle Projection

†Capacities are per set of jaws and are not simultaneous

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

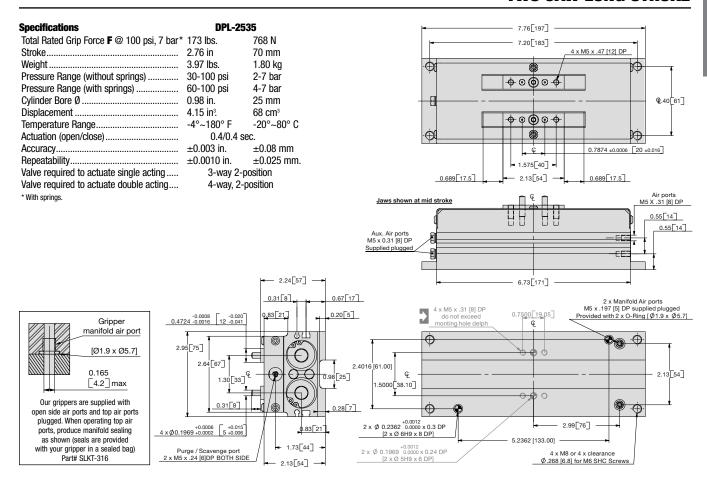


NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Separately) **Loading Information BASIC MODEL NON-SYNCHRONOUS** GRIP FORCE PER FINGER (springs compressed at mid-stroke) 400 WARNING DPL-2520 DO NOT EXCEED MAXIMUM EFFECTIVE 300 67 72 SPRING FINGER LENGTHS FINGER FORCE **SENSOR ACCESSORIES*** 200 PNP Magneto Resistive Sensor Long Barrel w/Qk Disc* **OHSP-017** 1 to 3 NPN Magneto Resistive Sensor Long Barrel w/Qk Disc* **OHSN-017** 1 to 3 100 22 PNP Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSP-011** 1 to 3 NPN Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSN-011** 1 to 3 Inductive Sensor Mounting Kit (3 Holders + 2 Flags) **OSMK-099** 0 10 in. M8 PNP Inductive Sensor with Quick Disconnect* **OISP-011** 1 to 3 100 M8 NPN Inductive Sensor with Quick Disconnect* **OISN-011** 1 to 3 EFFECTIVE FINGER LENGTH Quick Disconnect 2 Meter Cable Length* CABL-010 1 to 3 Mz CABL-013 Quick Disconnect 5 Meter Cable Length* 1 to 3 **PNEUMATIC ACCESSORIES** Standard Seal Repair Kit **SLKT-233** 1 **SLKT-316** Rear Inlet Seal Repair Kit 1 F/2 Fitting Push-in Straight M5 - 6mm O.D. Tube **PLFT-037** 1 to 2 Мν Fitting Push-in 90° Elbow M5 - 6mm O.D. Tube PLFT-041 1 to 2 **MOUNTING ACCESSORIES** Dynamic Static Loading Capacity[†] Metric Imperial Metric Imperial In-Line Jaw Mounting Kit **ODPL-001** 1 Maximum Tensile T 225 lbs. 1000 N 34 lbs. 150 N *Sensor and cable sold separately. Maximum Compressive C 283 lbs. 1260 N 34 lbs. 150 N See detailed option and accessory information at the end of this section. Maximum Moment Mx 372 in.-lbs. 42 Nm 35 in.-lbs. 4 Nm 81 in.-lbs. Maximum Moment My 100 Nm 9 Nm 885 in.-lbs. Maximum Moment Mz 531 in.-lbs. 60 Nm 81 in.-lbs. 9 Nm



PARALLEL GRIPPER DPL-2535 TWO JAW LONG STROKE





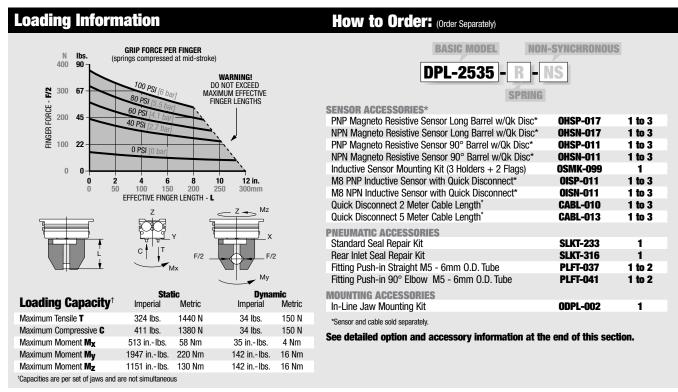
Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]



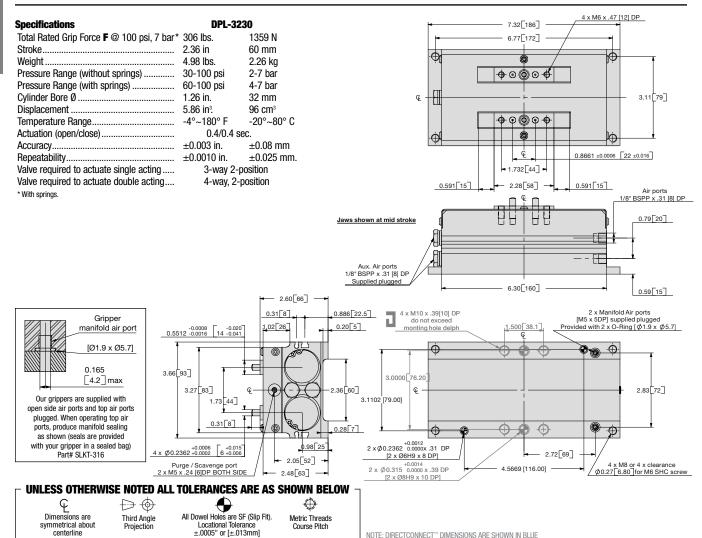
NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

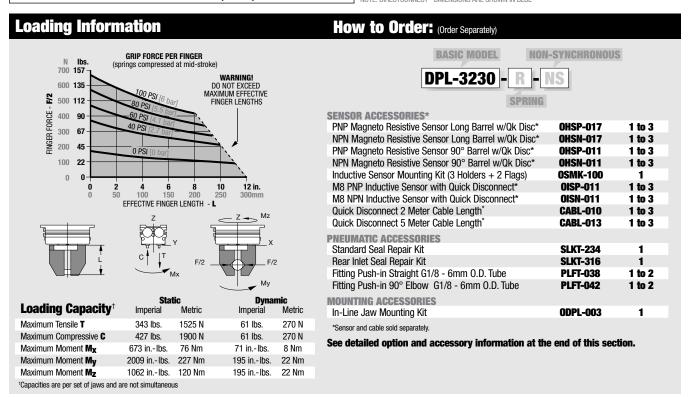


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PARALLEL GRIPPER DPL-3230 TWO JAW LONG STROKE

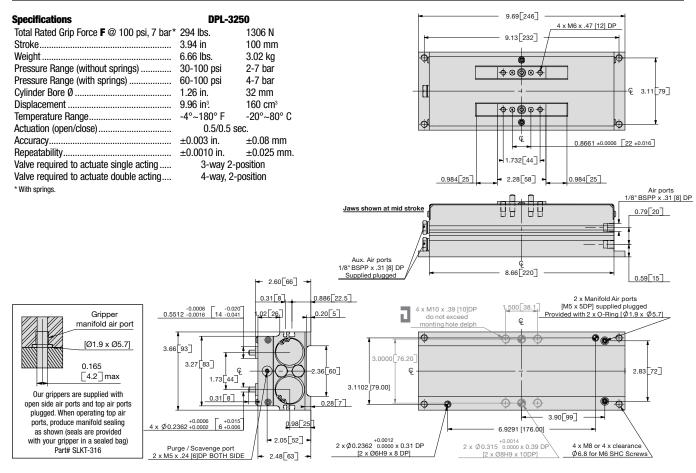








PARALLEL GRIPPER DPL-3250 TWO JAW LONG STROKE





Dimensions are symmetrical about centerline Third Angle Projection

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]



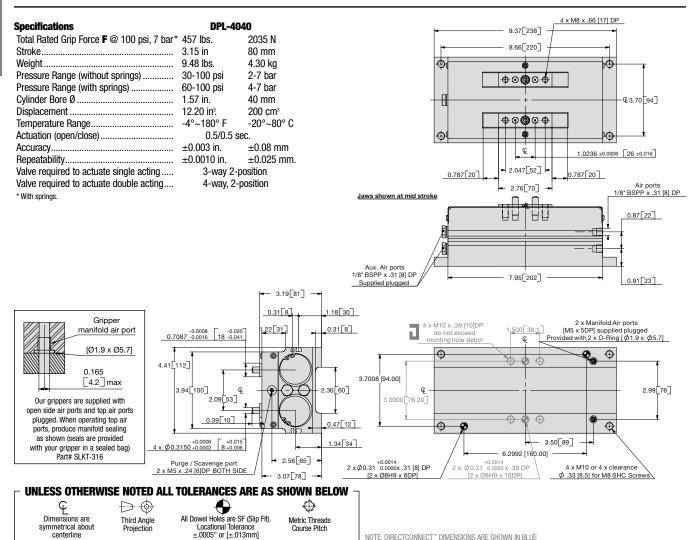
NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

Loading Information How to Order: (Order Separately) **BASIC MODEL NON-SYNCHRONOUS** GRIP FORCE PER FINGER (springs compressed at mid-stroke) 700 157 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE **DPL-3250** 600 135 72 500 112 SPRING FINGER LENGTHS FINGER FORCE 400 **SENSOR ACCESSORIES*** PNP Magneto Resistive Sensor Long Barrel w/Qk Disc* **OHSP-017** 1 to 3 300 67 NPN Magneto Resistive Sensor Long Barrel w/Qk Disc* **OHSN-017** 1 to 3 200 45 PNP Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSP-011** 1 to 3 100 22 NPN Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSN-011** 1 to 3 Inductive Sensor Mounting Kit (3 Holders + 2 Flags) **OSMK-100** 0 0 16 in. M8 PNP Inductive Sensor with Quick Disconnect* **OISP-011** 1 to 3 M8 NPN Inductive Sensor with Quick Disconnect* **OISN-011** 1 to 3 EFFECTIVE FINGER LENGTH - L Quick Disconnect 2 Meter Cable Length* CABL-010 1 to 3 Mz Quick Disconnect 5 Meter Cable Length* CABL-013 1 to 3 **PNEUMATIC ACCESSORIES** Standard Seal Repair Kit SLKT-234 1 Rear Inlet Seal Repair Kit **SLKT-316** 1 F/2 Fitting Push-in Straight G1/8 - 6mm O.D. Tube PLFT-038 1 to 2 Мν Fitting Push-in 90° Elbow G1/8 - 6mm O.D. Tube PLFT-042 1 to 2 **MOUNTING ACCESSORIES** Static Dynamic Loading Capacity[†] Imperial Metric Imperial Metric In-Line Jaw Mounting Kit ODPL-004 1 Maximum Tensile T 416 lbs. 1850 N 58 lbs. 260 N *Sensor and cable sold separately. Maximum Compressive C 520 lbs. 2315 N 58 lbs. 260 N See detailed option and accessory information at the end of this section. Maximum Moment Mx 71 in.-lbs. 770 in.-lbs. 87 Nm 8 Nm Maximum Moment My 350 Nm 3098 in.-lbs. 283 in.-lbs. 32 Nm Maximum Moment Mz 1682 in.-lbs. 190 Nm 283 in.-lbs. 32 Nm †Capacities are per set of jaws and are not simultaneous

DIRECTCONNECT

PARALLEL GRIPPER DPL-4040 TWO JAW LONG STROKE

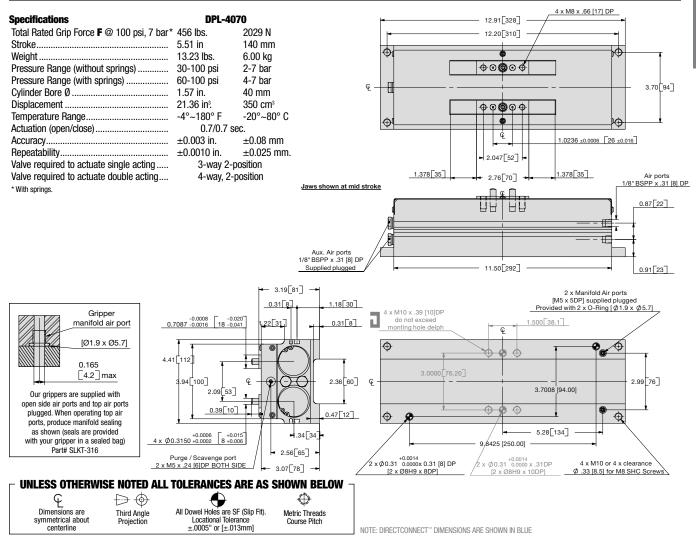


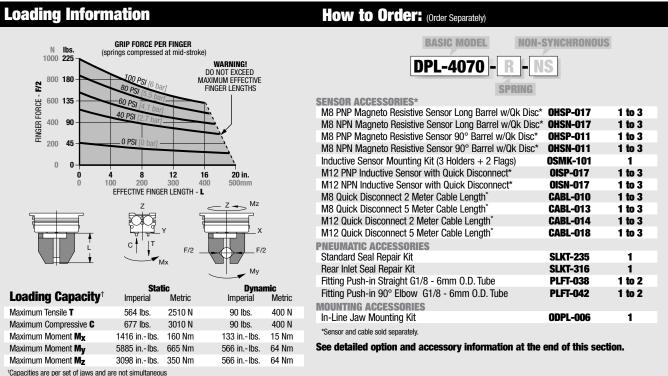


How to Order: (Order Separately) **Loading Information BASIC MODEL NON-SYNCHRONOUS** GRIP FORCE PER FINGER (springs compressed at mid-stroke) WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE **DPL-4040** F/2 SPRING FINGER LENGTHS 600 135 **SENSOR ACCESSORIES*** FINGER FORCE M8 PNP Magneto Resistive Sensor Long Barrel w/Qk Disc* OHSP-017 1 to 3 400 M8 NPN Magneto Resistive Sensor Long Barrel w/Qk Disc* **OHSN-017** 1 to 3 M8 PNP Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSP-011** 1 to 3 200 M8 NPN Magneto Resistive Sensor 90° Barrel w/Qk Disc* **OHSN-011** 1 to 3 Inductive Sensor Mounting Kit (3 Holders + 2 Flags) **OSMK-101** M12 PNP Inductive Sensor with Quick Disconnect* **OISP-017** 1 to 3 12 M12 NPN Inductive Sensor with Quick Disconnect* **OISN-017** 1 to 3 EFFECTIVE FINGER LENGTH - L M8 Quick Disconnect 2 Meter Cable Length* CABL-010 1 to 3 Mz CABL-013 M8 Quick Disconnect 5 Meter Cable Length' 1 to 3 M12 Quick Disconnect 2 Meter Cable Length* CABL-014 1 to 3 M12 Quick Disconnect 5 Meter Cable Length* CABL-018 1 to 3 **PNEUMATIC ACCESSORIES** F/2 Standard Seal Repair Kit **SLKT-235** 1 Rear Inlet Seal Repair Kit **SLKT-316** Мν Fitting Push-in Straight G1/8 - 6mm O.D. Tube PLFT-038 1 to 2 Static Dynamic Fitting Push-in 90° Elbow G1/8 - 6mm O.D. Tube PLFT-042 1 to 2 Loading Capacity[†] Imperial Metric Imperial Metric **MOUNTING ACCESSORIES** Maximum Tensile T 456 lbs. 2030 N 90 lbs. 400 N ODPI -OOS 1 In-Line Jaw Mounting Kit Maximum Compressive C 549 lbs. 2440 N 90 lbs. 400 N *Sensor and cable sold separately. Maximum Moment Mx 1195 in.-lbs. 135 Nm 124 in.-lbs. 14 Nm See detailed option and accessory information at the end of this section. Maximum Moment My 420 Nm 43 Nm 3717 in.-lbs. 381 in.-lbs. Maximum Moment Mz 1947 in.-lbs. 220 Nm 43 Nm 381 in.-lbs. †Capacities are per set of jaws and are not simultaneous



PARALLEL GRIPPER DPL-4070 TWO JAW LONG STROKE

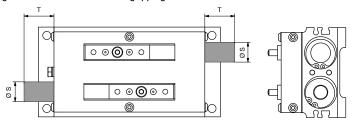




DPL Series Options & Accessories



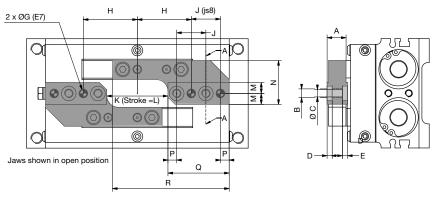
Optional Spring Assist (-R):The safety spring allows the gripper to retain the part should the air supply fail or allows the gripper to be used in single acting mode. The **-R** option is ideal for internal (ID) or external gripping (OD). The ID or OD will depend on the finger design. The fingers will face towards center of gripper for OD gripping or will face outward for ID gripping.



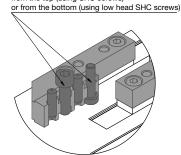
Use With	S	T
DPL-2520-R	0.65 [16.5]	0.98 [25]
DPL-2535-R	0.65 [16.5]	1.18 [30]
DPL-3230-R	0.98 [25]	0.76 [19.3]
DPL-3250-R	0.98 [25]	0.96 [24.3]
DPL-4040-R	1.10 [28]	1.69 [42.8]
DPL-4070-R	1.16 [29.5]	0.98 [24.8]

In-Line Jaw Adapter:

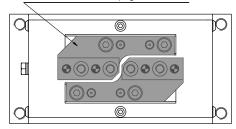
The In-Line Jaw Adapter allows for the simplification of the finger design. It provides for "in-line" alignment of the finger mounting holes. The kit includes 2 interfaces, screws, and dowel kit.



Fingers can be mounted on the acc from the top (using SHC screws)



Second direction for mounting the accessory When used with the -R option, it allows to secure for internal or external clamping

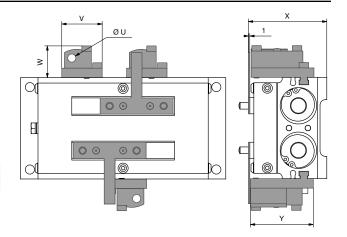


Order #	Use With	A	В	C	D	E	F	G	H	J	K	L	M	N	P	Q	R
ODPL-001	DPL-2520	0.51 [13]	M6	0.20[5]	0.14[3.5]	0.28[7]	M5	0.20[5]	1.46 [37]	0.79[20]	1.65[42]	1.57 [40]	0.30 [7.5]	1.18[30]	0.24[6]	1.65[42]	3.15[80]
ODPL-002	DPL-2535	0.51 [13]	M6	0.20[5]	0.14[3.5]	0.28[7]	M5	0.20[5]	2.05 [52]	0.79[20]	2.83[72]	2.76[70]	0.30[7.5]	1.18[30]	0.24[6]	1.65[42]	3.44[87.5]
ODPL-003	DPL-3230	0.59 [15]	M8	0.27 [6.8]	0.12[3]	0.39[10]	M6	0.24[6]	1.97 [50]	0.87[22]	2.44[62]	2.36[60]	0.39[10]	1.54[39]	0.31[8]	1.93 [49]	3.70 [94]
ODPL-004	DPL-3250	0.59 [15]	M8	0.27 [6.8]	0.12[3]	0.39[10]	M6	0.24[6]	2.76 [70]	0.87[22]	4.02[102]	3.94 [100]	0.39[10]	1.54[39]	0.31[8]	1.93 [49]	4.09[104]
ODPL-005	DPL-4040	0.83 [21]	M10	0.33 [8.5]	0.20[5]	0.47 [12]	M8	0.31 [8]	2.48[63]	1.02[26]	3.23[82]	3.15[80]	0.47 [12]	1.87 [47.5]	0.35[9]	2.24[57]	4.45[113]
ODPL-006	DPL-4070	0.83 [21]	M10	0.33 [8.5]	0.20[5]	0.47[12]	M8	0.31[8]	3.66 [93]	1.02[26]	5.59[142]	5.51 [140]	0.47 [12]	1.87 [47.5]	0.35[9]	2.24[57]	5.04[128]

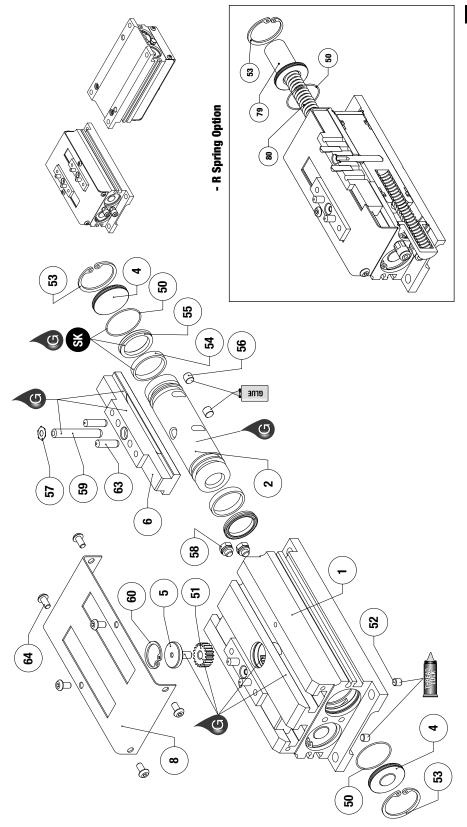
Inductive Sensors Holder:

Sense up to 3 jaw positions; open jaws, closed jaws, and part present. The kit includes 3 sensor holders and 2 flags. Sensors are not included.

Order #	Use With	U 001 [0]	V	W	X	Y
OSMK-099	DPL-2520	0.31 [8]	1.18 [30]	0.95 [24]	2.28 [58]	1.83 [46.5]
	DPL-2535	0.31 [8]	1.18 [30]	0.95 [24]	2.28 [58]	1.83 [46.5]
OSMK-100	DPL-3230	0.31 [8]	0.87 [22]	0.95 [24]	2.64 [67]	1.97 [50]
	DPL-3250	0.31 [8]	0.87 [22]	0.95 [24]	2.64 [67]	1.97 [50]
OSMK-101	DPL-4040	0.47 [12]	0.87 [22]	1.06 [27]	3.23 [82]	2.26 [57.5]
	DPL-4070	0.47 [12]	0.87 [22]	1.06 [27]	3.23 [82]	2.26 [57.5]







Item	Qty	Name
01	1	Body
02	2	Piston
04	4	Cap
05	1	Gear Cover
06	2	Jaw
80	1_	Shielded Case
50	4	Seal, Cap
<u>51</u>	1_	Synchronization Pinion
52	2	Set Screw-Manifold Port Plugs
53	4	Retainer Ring, Cap
54	4	Piston Ring Guidance
<u>55</u>	4	Piston U-Cup
56	4	Magnet
57	2	Drive Pin Retainer Ring
58	2	Manifold Port Plugs
59	2	Drive Pin
60	2	Center Retaining Ring
63	4	Jaw Dowel Pin
64	6	Shielded Case Screws
79	2	Spring Cap
80	2	Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Glue magnets #56 into the piston slots #2.
- 2) If top air ports are not used, plug the body #1 with screws #52 using glue.
- 3) Lubricate and install the U-Cup seals #55 and the guidance ring #54 onto the piston #2.
- 4) Lubricate and assemble the piston #2 into the body #1 using the adequate
- 5) Press dowel pins #63 into the jaws #6.
- 6) Lubricate and install the jaws #6 into the slots #1.
- 7) Press the drive pin #59 and the retaining ring #57 through the jaws #6 and the piston #2.
- 8) Lubricate and install the axis #5, the pinion #51, the retaining ring #60 into the body. Beware of the correctly place the jaws to get a synchronous motion.
- 9) Lubricate and install the seal #50 onto the
- 10) Install the cap #4 and the retaining ring #53 into the cap #1.
- 11) Install the shielded case #8.
- 12) Screw the plugs #58 into the body #1.

Assembly - Spring option

- 1) Lubricate and install the seal (#50) onto the cap.
- 2) Install the spring into the piston bore and into the cap bore.
- 3) Compress the spring till the cap reach its correct position on the body.
- 4) Install the retaining ring.







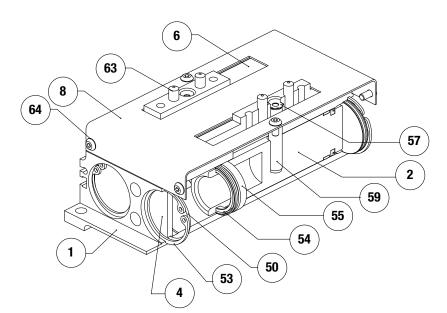








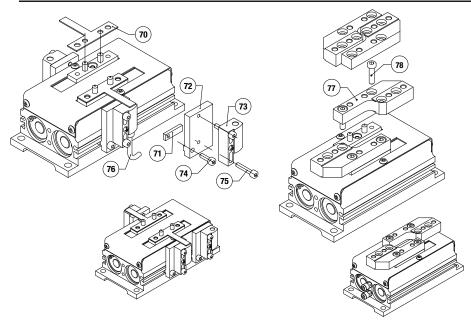




Hom	Ob.,	Name
цеш	Ųty	Name
01	1	Body
02	2	Piston
04	4	Cap
05	1	Axis
06	2	Jaw
80	1	Shielded Case
50	4	Seal, Cap
51	1	Synchronization Pinion
52	2	Set Screw-Manifold Port Plugs
53	4	Retainer Ring, Cap
54	4	Piston Ring Guidance
<u>55</u>	4	Piston U-Cup
56	4	Magnet
57	2	Drive Pin Retainer Ring
58	2	Stopper-Manifold Port Plugs
59	2	Drive Pin
60	2	Center Retaining Ring
63	4	Jaw Dowel Pin
64	6	Shielded Case Screws

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation - Inductive Sensors Holder Kit

- 1) Place the flags (#2) on the jaws as shown.
- 2) Install the sensor holder (#72) on the adapter (#73) using the screws (#75)
- 3) Tighten the sensor (not shown) into the sensor holder(#73).
- 4) Install the nut (#71) into the slot of the body and the adapter (#72) on the slot. Install the screw (#74) to fix the adapter on the nut.
- 5) Loosen the screw (#74) and slide the assembly until the light indicates.
- 6) Tighten the screw (#74).

Installation - In-Line Jaws

- Install the interface (#77) onto the jaws. When combined with the -R option and according to the mounting direction, the interface can be used for internal or external clamping.
- 2) Tighten the screw (#78) between the interface (#77) and the jaw.

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PRECIDESIGN NOTES

1.169

Parallel Gripper Miniature Series Double Wedge

• General purpose:

This style gripper is the most widely used in the industry. It is a rugged design and supplies very high grip force.

Small parts handling:

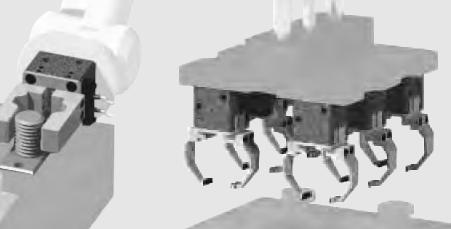
Compact size, high gripping force, and extended jaw design facilitates finger attachment for smaller parts.

• Robotic applications:

High grip force to weight ratio make these grippers very popular on small robots.

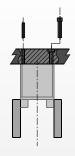
Miniature Size:

Allows banks of grippers to be mounted in close proximity for multiple part picking and placing.



Mounting Information:

Grippers can be mounted & operated in any orientation



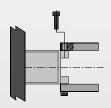
Body mounts with screws and locates with slip fit dowel pins for accuracy







Warning! Protect jaw mechanism from falling debris when mounted upside down



Fingers attach to jaws with screws and locate by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals

Valve Required to Operate

40-100 psi **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Metric

3-7 bar

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C

Imperial

Maintenance Specifications[†]

Expected Life

Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

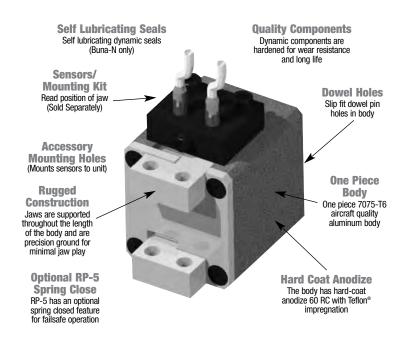
Application Restrictions

- Dirty or gritty environments
- Machining operations generating chips
- · Environments with loose particulate
- Applications where mechanism lubricant could cause contamination

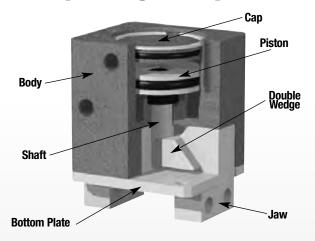
*Addition of lubrication will greatly increase service life

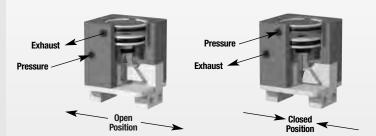
See Maintenance Section

Product Features



Operating Principle





- A double acting piston is connected by a shaft to a double sided wedge.
- The wedge slides in a slot located in each of the jaws converting vertical motion
 of the wedge into horizontal synchronous motion of the jaws.
- The large surface area of the wedge minimizes frictional wear.
- This gripper is suitable for internal or external gripping.

U.S. Patent # 5,125,708 Designed and manufactured in the USA

Style-RP Parallel Gripper

Size -5M

 Style:
 RP-5
 RP-5M

 Stroke:
 .16 in.
 4.1 mm

 Grip Force:
 35 lb
 156 N

 Weight:
 .18 lb
 .08 Kg



See **1.172** Page

Style-RP Parallel Gripper

Size -5M-FS Style: Stroke:

 Style:
 RP-5 Mtroke:
 16 in.
 4.1 mm

 Grip Force:*
 40 lb Mtrokeight:
 18 lb Mtrokeight:
 0.8 kg

 *Grip force with spring assist



See **1.172**

Style-RP Parallel Gripper

Size -10M

 Style:
 RP-10 Stroke:
 1/4 in.
 6.4 mm

 Grip Force:
 40 lb
 175 N

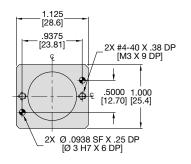
 Weight:
 .28 lb
 .13 Kg



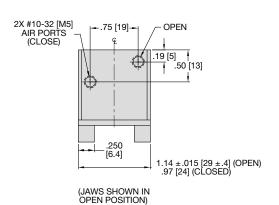
See 1.173

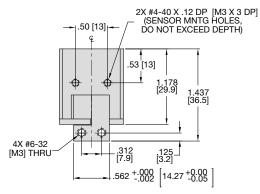
Note: Please refer to our new DPDS/DPDL Series grippers found on pages 1.134-1.157. The RP Series is still available for sale and the related information remains available on our website but we encourage you to consider the new DPDS/DPDL Series grippers found on pages 1.134-1.157 for new projects.



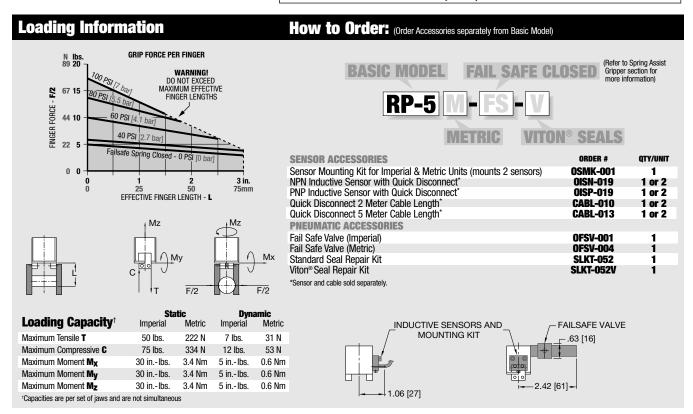


Specifications	RP-5	RP-5M
Total Rated Grip Force F @ 100 psi, 7 bar3	85 lb	156 N
Stroke	.16 in.	4.1 mm
Weight	0.18 lb	0.08 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.750 in.	19.1 mm
Displacement	0.042 in ³ .	0.7 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate	4-way, 2-p	osition

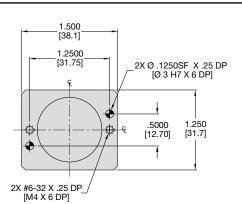




UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Projection $\pm 0.005^{\circ}$ or $\pm 0.005^{\circ}$ or $\pm 0.015^{\circ}$ Metric Threads Course Pitch $\pm 0.0005^{\circ}$ or $\pm 0.015^{\circ}$ Or \pm



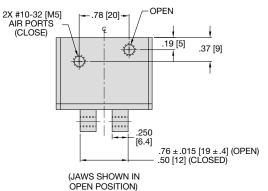


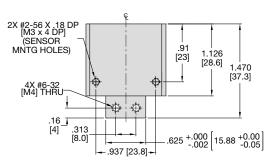


Specifications	RP-10	RP-10M
Total Rated Grip Force F @ 100 psi, 7 bar4	0 lb	178 N
Stroke	0.25 in.	6.4 mm
Weight	0.28 lb	0.13 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.00 in.	25.4 mm
Displacement	0.098 in ³ .	1.6 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate	4-way, 2-po	sition

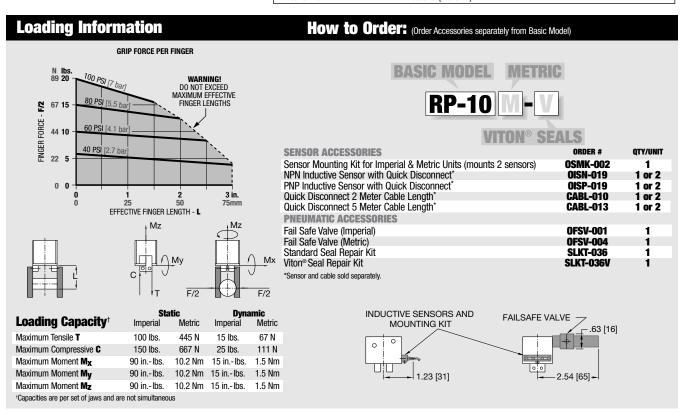
PARALLEL GRIPPER RP-10M

MINIATURE DOUBLE WEDGE SERIES

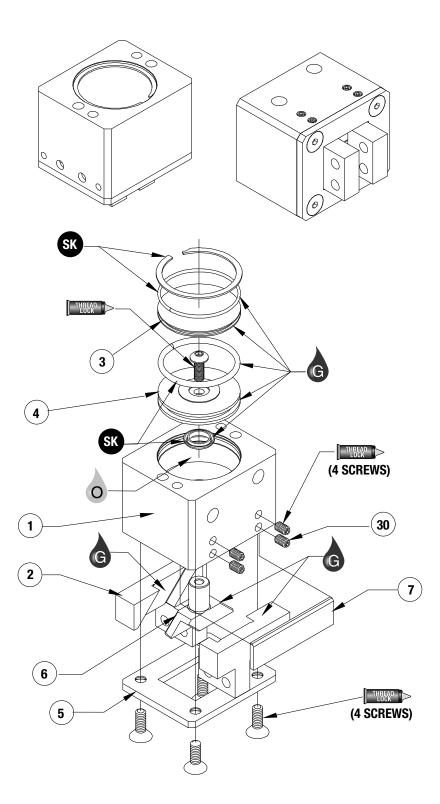




UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). Ç \bigoplus Imperial in. Metric [mm] Dimensions are $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Third Angle Metric Threads symmetrical about Locational Tolerance Course Pitch centerline ±.0005" or [±.013mm]







ltem	Qty	Name
01	1	Body
02	2	Jaw
03	1	Cap
04	1	Piston
05	1	Plate,Bottom
06	1	Shaft/Wedge
07*	1	Gib
30*	4	SSS,Cup Point
+ DD	400	1

* RP-10 Only

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedures

- 1) Lubricate and install seals.
- 2) Install piston into body.
 3) Place wedge, jaws, and gib plate into body.
- 4) Attach bottom plate to body.
- 5) Install cap and retaining ring.

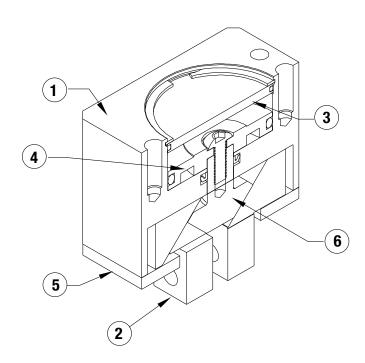
Gib Adjustment Procedure

- 1) Tighten set screws (#30) so that they just just touch the gib plate.
- 2) Cycle the gripper.3) Adjust screws so that there is no play in jaws.





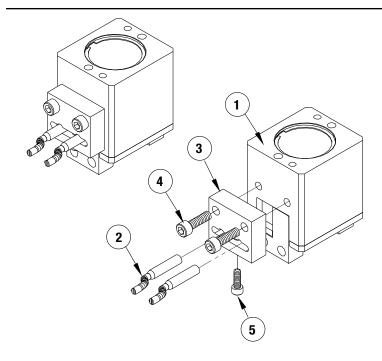
RP-5 & 10 Series Assembled View



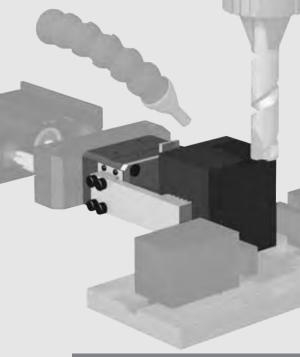
Item	Qty	Name
<u>01</u>	1	Body
02	2	Jaw
03	1	Cap
04	1	Piston
05	1	Plate, Bottom
06	1	Shaft/Wedge
07*	1	Gib
30*	4	SSS,Cup Point
* RP-	-10 0	nly

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Parallel Grippers-Double Wedge Series



Machining applications:

Sealed design repels chips and other particulate from internal drive mechanism.

General purpose:

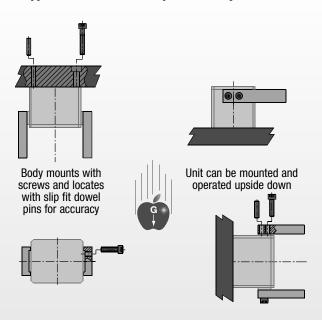
This style gripper is the most widely used in the industry. It is a rugged design and supplies very high grip forces for its size.

Part pressing:

Hardened steel bottom plate provides a solid surface for part pressing.

Mounting Information:

Grippers can be mounted & operated in any orientation



Fingers attach to jaws with screws and locate by keying or dowel pins

Technical Specifications:

Pneumatic Specifications Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar Cylinder Type **Double Acting** Internally Lubricated Buna-N Dynamic Seals Valve Required to Operate 4-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better Not Necessary* Air Lubrication Low Moisture Content (dry) Air Humidity

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C -30°~150° C -20°~300° F Viton® Seals (optional)

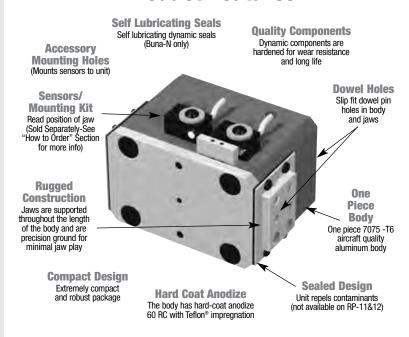
Maintenance Specifications 1

Expected Life

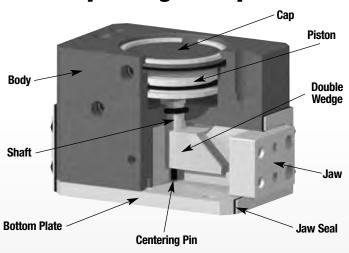
Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

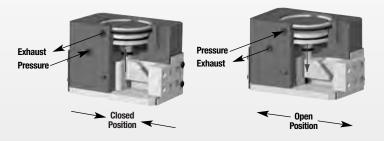
*Addition of lubrication will greatly increase service life †See Maintenance Section

Product Features



Operating Principle





- A double acting piston is connected by a shaft to a double sided wedge.
- The wedge slides in a slot located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.
- The large surface area of the wedge minimizes frictional wear.
- This gripper is suitable for internal or external gripping.

U.S. Patent # 5,125,708 Designed and manufactured in the USA

Style-RP Parallel Gripper

Size-11 M

 Style:
 RP-11 btroke:
 RP-11M c.25 in.
 6.4 mm

 Grip Force:
 40 lbs.
 178 N btrokes

 Weight:
 .25 lbs.
 .11 kg

See **1.178** Page **1.178**

Style-RP Parallel Gripper

Size-12M

 Style:
 RP-12
 RP-12M

 Stroke:
 0.38 in.
 9.5 mm

 Grip Force:
 40 lbs.
 178 N

 Weight:
 .56 lbs.
 .25 Kg

See 1.179

Style-RP Parallel Gripper

Size-15M



 Style:
 RP-15 Stroke:
 RP-15M Prism

 0.50 in.
 12.7 mm

 Grip Force:
 70 lbs.
 310 N

 Weight:
 1.25 lbs.
 .57 Kg

See **1.180** Page

Style-RP Parallel Gripper

Size-17M



 Style:
 RP-17
 RP-17M

 Stroke:
 0.75 in.
 19.1 mm

 Grip Force:
 220 lbs.
 979 N

 Weight:
 2.2 lbs.
 1.0 kg

See **1.181**

Style-RP Parallel Gripper

Size-18M



 Style:
 RP-18 Stroke:
 1.25 in.
 31.8 mm

 Grip Force:
 400 lbs.
 1.779 N

 Weight:
 7.7 lbs.
 3.5 Kg

See **1.182** Page **1.182**

Style-RP Parallel Gripper

Size-19M

 Style:
 RP-19
 RP-19M

 Stroke:
 2.00 in.
 50.8 mm

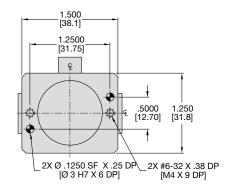
 Grip Force:
 600 lbs.
 2669 N

 Weight:
 21 lbs.
 9.5 Kg

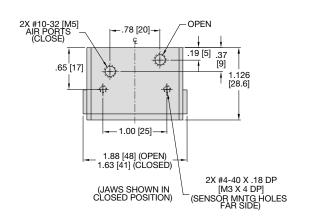
See **1.183**

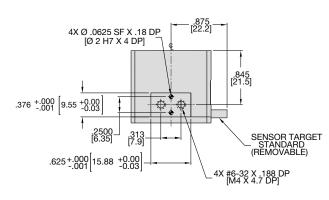
Note: Please refer to our new DPDS/DPDL Series grippers found on pages 1.134-1.157. The RP Series is still available for sale and the related information remains available on our website but we encourage you to consider the new DPDS/DPDL Series grippers found on pages 1.134-1.157 for new projects.



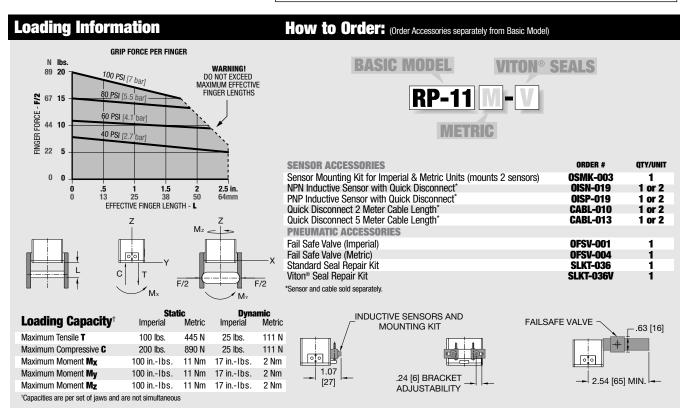


Specifications	RP-11	RP-11M
Total Rated Grip Force F @ 100 psi, 7 bar4	10 lbs.	178 N
Stroke	.25 in.	6.4 mm
Weight	0.26 lbs.	0.12 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.000 in.	25.4 mm
Displacement	0.098 in ³ .	1.6 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition



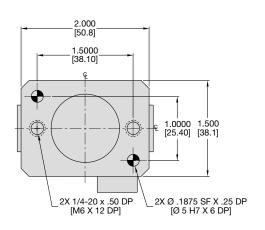


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Third Angle Projection $\pm 0.005^{\circ}$ or $[\pm .013mm]$ Metric Threads $\pm 0.005^{\circ}$ or $[\pm .013mm]$ $0.00 = \pm .015$ $0.000 = \pm .005$ $0.000 = \pm .005$ $0.000 = \pm .005$ $0.000 = \pm .005$ $0.000 = \pm .005$

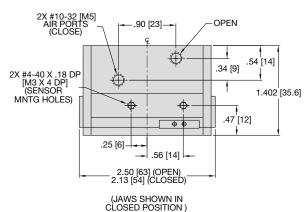


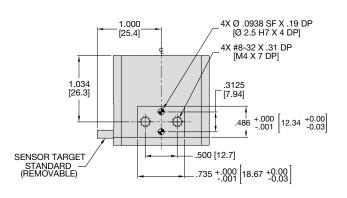


PARALLEL GRIPPER RP-12M DOUBLE WEDGE SERIES



Specifications	RP-12	RP-12M
Total Rated Grip Force F @ 100 psi, 7 bar4	0 lbs.	178 N
Stroke	.38 in.	9.5 mm
Weight	0.56 lbs.	0.25 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.000 in.	25.4 mm
Displacement	0.150 in ³ .	2.5 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-po	osition



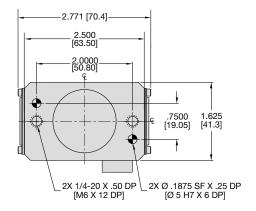


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] 0 Imperial in. Metric [mm] $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Dimensions are symmetrical about $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Third Angle Metric Threads Projection Course Pitch

Loading Information How to Order: (Order Accessories separately from Basic Model) WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE N lbs 89 20 GRIP FORCE PER FINGER 100 PSI [7 bar] **BASIC MODEL VITON® SEALS** FINGER LENGTHS **2** 67 15 **RP-12** FINGER FORCE 44 10 **METRIC** 22 5 0 0 **SENSOR ACCESSORIES** ORDER # QTY/UNIT 1 1.5 2 2.5 25 38 50 64 EFFECTIVE FINGER LENGTH - L 3 3.5 in. Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-003** 1 or 2 NPN Inductive Sensor with Quick Disconnect* **OISN-019 OISP-019** PNP Inductive Sensor with Quick Disconnect* 1 or 2 Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 CABL-013 Quick Disconnect 5 Meter Cable Length* 1 or 2 Mz = |-**PNEUMATIC ACCESSORIES** Fail Safe Valve (Imperial) **OFSV-001** 1 Fail Safe Valve (Metric) **OFSV-004 SLKT-040** Standard Seal Repair Kit F/2 SLKT-040V F/2 Viton® Seal Repair Kit *Sensor and cable sold separately. INDUCTIVE SENSORS AND FAILSAFE VALVE Static **Dynamic** Loading Capacity[†] Metric MOUNTING KIT Metric Imperial Imperial .63 [16] Maximum Tensile T 890 N 25 lbs. 111 N 200 lbs. Maximum Compressive C 400 lbs. 1779 N 25 lbs. 111 N 0 0 000 Maximum Moment Mx 150 in.-1bs. 17 Nm 25 in.-Ibs. 3 Nm 1.19 .24 [6] BRACKET Maximum Moment My 150 in.-lbs. 17 Nm 25 in.-1bs. 3 Nm 2.67 [68] MIN. [30] **ADJUSTABILITY** Maximum Moment Mz 150 in.-Ibs. 17 Nm 25 in.-Ibs. 3 Nm †Capacities are per set of jaws and are not simultaneous

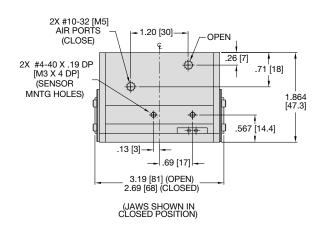
centerline

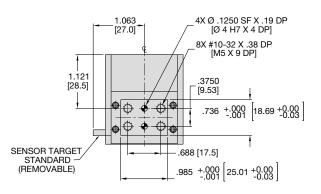




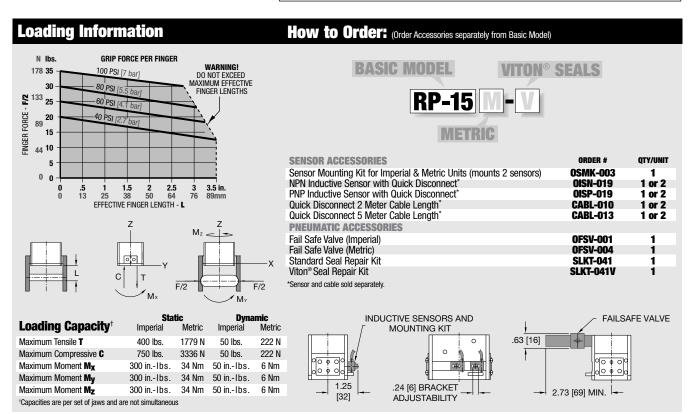
Specifications	RP-15	RP-15M
Total Rated Grip Force F @ 100 psi, 7 bar	70 lbs.	311 N
Stroke	.50 in.	12.7 mm
Weight	1.25 lbs.	0.57 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.25 in.	31.8 mm
Displacement	0.300 in ³ .	4.9 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-position	

O-- - - 161 - - 11 - --



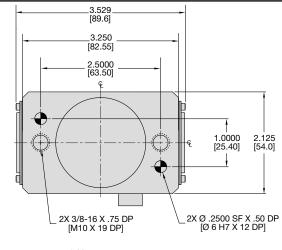


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW 0 Imperial in. $\Rightarrow \oplus$ Metric [mm] All Dowel Holes are SF (Slip Fit). Locational Tolerance $0.00 = \pm .01$ $0.000 = \pm .005$ Dimensions are Third Angle Metric Threads symmetrical about Projection Course Pitch centerline ±.0005" or [±.013mm] $0.0000 = \pm .0005$

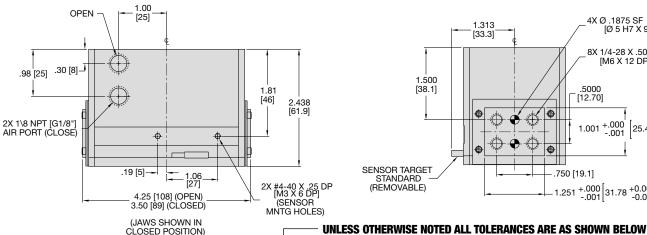


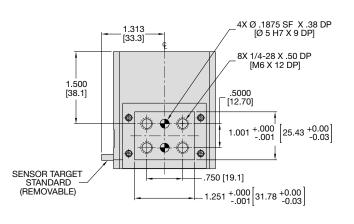
1.181

PARALLEL GRIPPER RP-17M DOUBLE WEDGE SERIES



Specifications	RP-17	RP-17M
Total Rated Grip Force F @ 100 psi, 7 bar	220 lbs.	979 N
Stroke	.75 in.	19.1 mm
Weight	2.2 lbs.	1.0 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.813 in.	46.1 mm
Displacement	1.400 in ³ .	22.9 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.18 sec.	0.18 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition





Ç Dimensions are symmetrical about

 $\triangleright \Phi$ Third Angle Projection All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

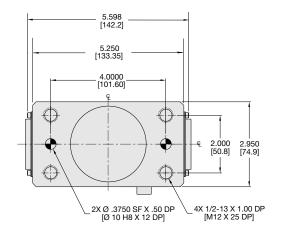
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Metric [mm]

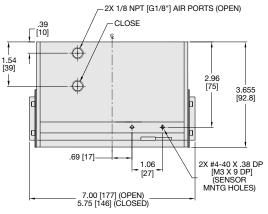
Loading Information How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER N lbs. 534 120 **BASIC MODEL** VITON® SEALS WARNING DO NOT EXCEED MAXIMUM EFFECTIVE 445 100 **3** 356 80 FINGER LENGTHS 267 60 60 PSI [4.1 bar] 40 PSI [2 **METRIC** 178 40 89 20 **SENSOR ACCESSORIES** ORDER # QTY/UNIT Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-072** 1 0 0 1 or 2 NPN Inductive Sensor with Quick Disconnect* **OISN-011** 2 3 4 5 50 76 10 EFFECTIVE FINGER LENGTH - **L** PNP Inductive Sensor with Quick Disconnect* Quick Disconnect 2 Meter Cable Length* OISP-011 102 1 or 2 CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length' CABL-013 1 or 2 **PNEUMATIC ACCESSORIES** OFSV-002 OFSV-005 Fail Safe Valve (Imperial) 1 Fail Safe Valve (Metric) 1 SLKT-042 Standard Seal Repair Kit SLKT-042V Viton® Seal Repair Kit *Sensor and cable sold separately. F/2 F/2 INDUCTIVE SENSORS AND FAILSAFE VALVE Static **Dynamic** MOUNTIING KIT .79 [20] Loading Capacity[†] Metric Imperial Metric Imperial Maximum Tensile T 3336 N 100 lbs. 445 N 750 lbs 0 Maximum Compressive C 1500 lbs. 6672 N 100 lbs. 445 N Maximum Moment Mx 750 in.-Ibs. 0000 85 Nm 125 in.-lbs. 14 Nm Maximum Moment My 750 in.-lbs. 85 Nm 125 in.-lbs. 14 Nm 1 62 .26 [7] BRACKĖT 3.63 [92] Maximum Moment Mz 750 in.-Ibs. 85 Nm 125 in.-lbs. 14 Nm **ADJUSTABILITY** †Capacities are per set of jaws and are not simultaneous

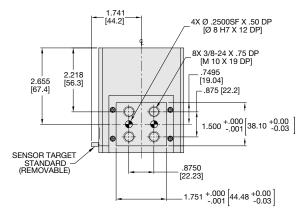
PARALLEL GRIPPER RP-18M DOUBLE WEDGE SERIES





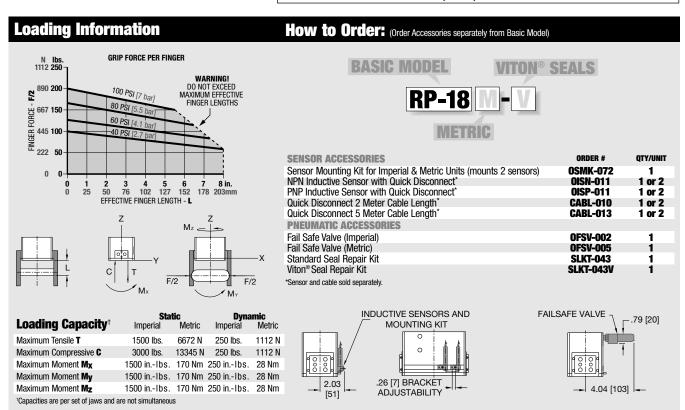
Specifications	RP-18	RP-18M
Total Rated Grip Force F @ 100 psi, 7 bar	400 lbs.	1779 N
Stroke	1.25 in.	31.8 mm
Weight	7.7 lbs.	3.5 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	2.500 in.	63.5 mm
Displacement	4.400 in ³ .	72.1 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.22 sec.	0.22 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-po	osition





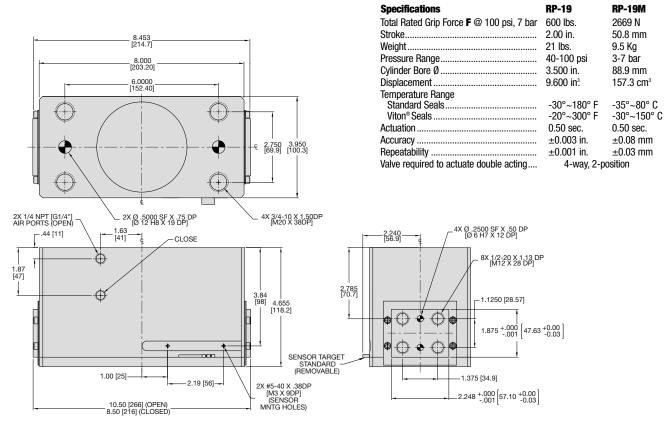
(JAWS SHOWN IN CLOSED POSITION)

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Third Angle Projection All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] All Dowel Holes are SF (Slip Fit). Metric Threads Course Pitch 0.000 = ±.005 0.000 = ±.005 0.000 = ±.005 0.000 = ±.0013

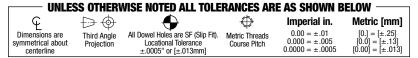


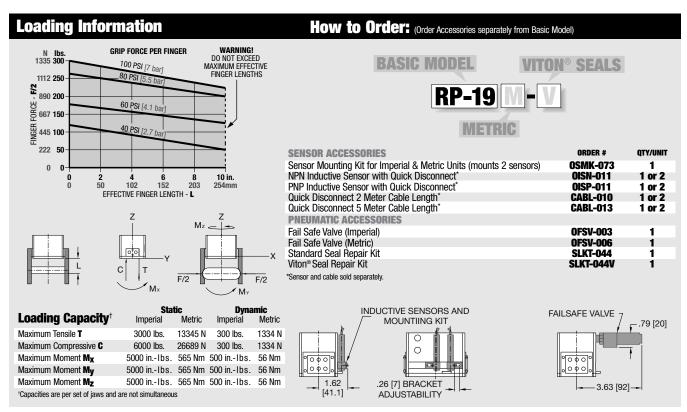


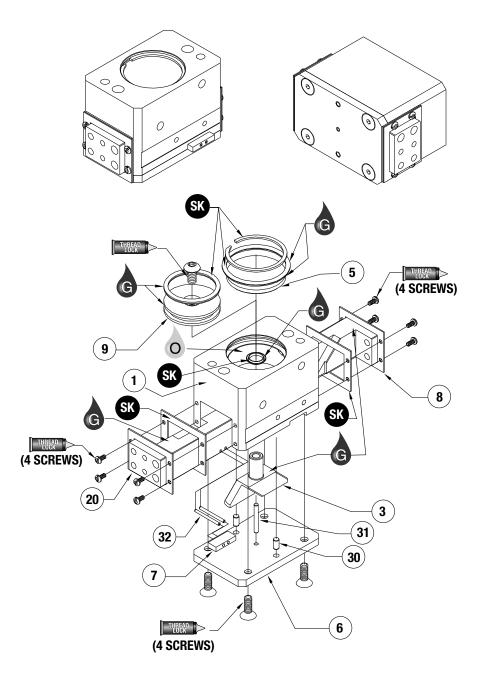
PARALLEL GRIPPER RP-19M DOUBLE WEDGE SERIES



(JAWS SHOWN IN CLOSED POSITION)







Item	Qty	Name
01	1	Body
03	1	Shaft/Wedge
05	1	Cap
06	1	Plate, Bottom
07	1	Target
80	2	Plate,Seal
09	1	Piston
20	2	Jaw,Target Ready
30	2	Dowel Pin
31	1	Dowel Pin
32	2	Roll Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals.
- 2) Install target on one jaw.3) Place wedge, shaft and jaws into body.

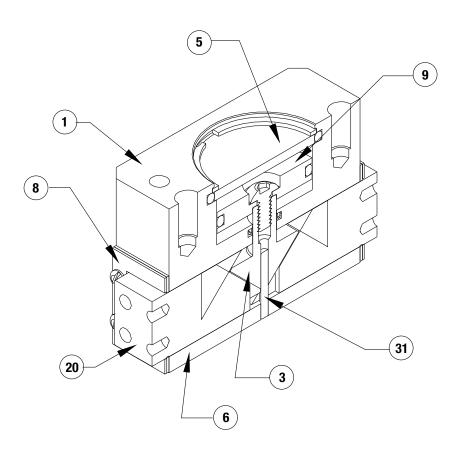
- 4) Install piston into body. 5) Install cap and retaining ring. 6) Attach bottom plate to body.





RP Double Wedge Series Assembled View

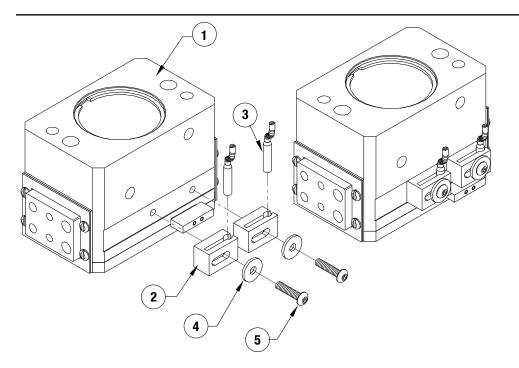




Item	Qty	Name
01	1	Body
03	1	Shaft/Wedge
05	1	Cap
06	1	Plate, Bottom
07	1	Target
08	2	Plate,Seal
09	1	Piston
20	2	Jaw,Target Ready
30	2	Dowel Pin
31	1	Dowel Pin
32	2	Roll Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation

- 1) Install sensors as shown.
- 2) Adjust for desired end of stroke detection.

Parallel Gripperso Jaw Precision Spring Series

· Compact and shielded gripper:

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Standard safety springs retain the components should the air supply fail, or during gripping, the spring provides additional gripforce.

• Multipurpose gripper:

The safety springs allow this gripper to be used to clamp on arbor or in bore without the need for any modifications. All the user has to do is to change the jaw position in the jaw holders.

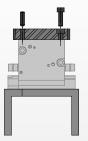
• Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism.



Grippers can be mounted & operated in any orientation

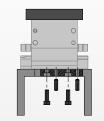
The gripper is protected from falling debris when it is mounted and operated upside down.



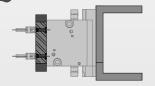
Gripper is located from the top with 2 dowel pins and assembled with 2 screws (by pulling).



Gripper is located on the side with 2 dowel pins and assembled with 2 through body screws.



Fingers are located on jaws with 2 dowel pins and assembled with 2 screws.



Gripper can be operated utilizing top manifold air ports.

Technical Specifications:

Pneumatic Specifications Imperial Metric 45-100 psi 3-7 bar Pressure Operating Range **Double Acting Spring Assist** Cylinder Type or Single Acting Spring Return **Dynamic Seals Internally Lubricated Buna-N** 4-way, 2-position for Double Acting Valve Required or 3-way, 2-position for Single Acting to Operate

Air Quality Requirements

Air Filtration 40 Micron or Better Air Lubrication Not Necessary* **Low Moisture Content (dry)** Air Humidity

Temperature Operating Range

Buna-N Seals (Standard) -30°~180° F -35°~80° C Viton® Seals (Optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

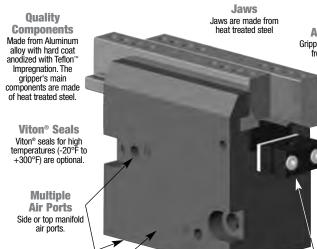
Expected Life Normal Application w/ Preventative Maintenance Field Repairable

5 million cycles 10+ million cycles* Yes

Seal Repair Kits Available Yes

*Addition of lubrication will greatly increase service life †See Maintenance Section





Gripper Attachment Gripper can be mounted from top or sides

> Jaw **Attachment** Each jaw allows iaw attachment for gripping on OD or ID

Cover Gripper body is shielded to repel chins and other particulate from internal drive mechanism.

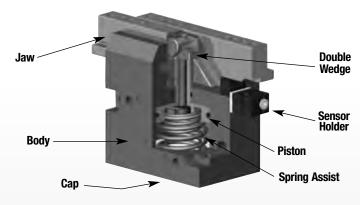
Standard springs allow the gripper **DIRECTCONNECT** to retain the component, should the **Mounting Patterns** air supply fail or to use the gripper in DIRECTCONNECT™ tapped single acting mode by clamping on & dowel mounting surface available on **DDH** version the shaft or the bore. [except -85 & 105]

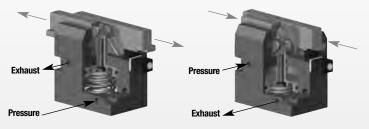
Spring Assist

Inductive Sensoring

Standard inductive sensor holders allow you to attach optional inductive sensor to sense up to two ends of stroke (non-adjustable)

Operating Principle





- Two safety springs apply pressure to a piston. One end of the piston is connected to a double wedge that has two opposing racks that slide in the jaw holder slot.
- It converts vertical motion of the piston into horizontal opposite synchronous motion of the 2 jaws.
- In order to benefit from spring power and from pneumatic control power, the pneumatic inlet must be applied to "S" for gripping and with "D" for release. An arrow etched onto each jaw holder indicates the gripping direction.
- Springs can be used to increase the grip force or to hold part in the event of air loss. It also allows the gripper to be used in single acting mode.

Style-DGC Parallel Gripper

Style-DGC Parallel Gripper

Style: Stroke:

Weight:

Size -45

Size -25

Style: G Stroke: 1.18 in. Grip Force: 108 lbs. 30 mm 481 N Weight: 1.32 lbs. 0.60 Kg



See 1.189

GC-25 20 mm

See 1.188

0.35 Kg

0.79 in.

0.77 lbs.

Grip Force: 106 lbs.

Style-DGC Parallel Gripper

Size -65

Style: GC-65 Stroke: Grip Force: Weight: 179 lbs. 796 N 2.87 lbs. 1.30 Kg



See 1.190 Page 1.190

Style-GC Parallel Gripper

Size -85

GC-85 1.97 in. 50 mm **Grip Force:** 333 lbs. **Weight:** 4.85 lbs. 1480 N 2.20 Kg



See 1.191

Style-GC Parallel Gripper

Size -105

Style: GC105 521 lbs. 2318 N Grip Force: Weight: 9.50 lbs. 4.31 Kg



See 1.192

PARALLEL GRIPPER DGC-25 TWO JAW PRECISION SPRING ASSIST



1.188



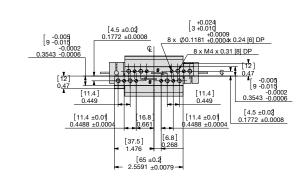
Total Rated Grip Force **F** @ 100 psi, 7 bar* 106 lbs. 474 N 0.787 in Stroke... 20 mm Weight 0.77 lbs. 0.35 kg Pressure Range 45-100 psi 3-7 bar Cylinder Bore Ø 1.34 in. 34 mm Displacement 0.98 in³. 16 cm³

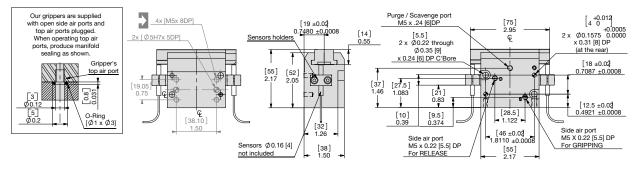
Temperature Range -35°~80° C Standard Seals -30°~180° F -30°~150° C Viton® Seals..... -20°~300° F 0.2 sec. 0.2 sec. ±0.0009 in. ±0.02 mm Accuracy..... Repeatability..... ±0.0004 in. ±0.01 mm.

Valve required to actuate single acting 3-way 2-position Valve required to actuate double acting.... 4-way, 2-position

* With springs.

Specifications





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

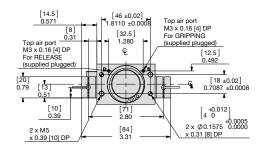
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Imperial in. Metric Threads Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm.0005$ Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

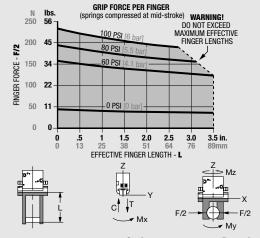
NOTE: To benefit from safety springs power, on open or on close, gripper must always be operated with "S" for GRIPPING and with "D" for RELEASE.

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "S")





How to Order: (Order Separately)



SENSOR ACCESSORIES	ORDER #	QTY/UNIT
4mm PNP Inductive Sensor with Qk Disconnect*	0ISP-014	1 or 2
4mm NPN Inductive Sensor with Qk Disconnect*	0ISN-014	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-319	1
Viton® Seal Repair Kit	SLKT-319V	1
*Sensor and cable sold separately.		

SIZE VITON® SEALS

BASIC MODEL

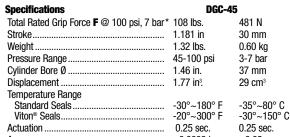
DGC - 25 -

Loading Capacity [†]	Sta [*] Imperial	tic Metric	Dyna Imperial	mic Metric
Maximum Tensile T	28 lbs.	125 N	6 lbs.	25 N
Maximum Compressive C	33 lbs.	145 N	7 lbs.	29 N
Maximum Moment M _X	18 inlbs.	2 Nm	4 inlbs.	0.5 Nm
Maximum Moment My	35 inlbs.	4 Nm	9 inlbs.	1 Nm
Maximum Moment Mz	53 inlbs.	6 Nm	13 inlbs.	1.5 Nm
†Capacities are per set of laws and a	re not simultaneo	us		



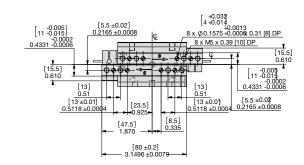
* With springs.

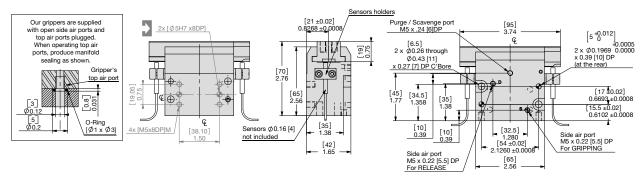
PARALLEL GRIPPER DGC-45 TWO JAW PRECISION SPRING ASSIST



Accuracy..... ±0.0009 in. ±0.02 mm Repeatability..... ±0.0004 in. ±0.01 mm. 3-way 2-position Valve required to actuate single acting Valve required to actuate double acting....

4-way, 2-position





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

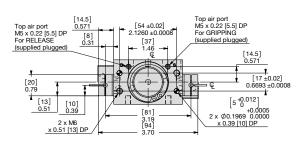
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm.0005$ Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

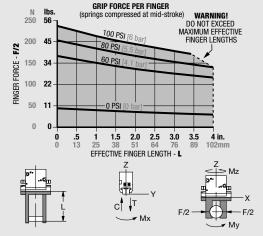
NOTE: To benefit from safety springs power, on open or on close, gripper must always be operated with "S" for GRIPPING and with for RELEASE.

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "S")



Loading Information

How to Order: (Order Separately)



	ci ∤ı	Их	F/2 My	F/2
Loading Capacity [†]	Sta t Imperial	tic Metric	Dyna Imperial	mic Metric
Maximum Tensile T	46 lbs.	205 N	9 lbs.	41 N
Maximum Compressive C	51 lbs.	225 N	10 lbs.	45 N
Maximum Moment M _X	27 inlbs.	3 Nm	7 inlbs.	0.75 Nm
Maximum Moment My	53 inlbs.	6 Nm	13 inlbs.	1.5 Nm
Maximum Moment M-	80 in - lhs	9 Nm	20 in ₌lhe	2 25 Nm

†Capacities are per set of jaws and are not simultaneous



SENSOR ACCESSORIES 4mm PNP Inductive Sensor with Qk Disconnect*	ORDER # OISP-014	QTY/UNIT 1 or 2
4mm NPN Inductive Sensor with Qk Disconnect*	OISN-014	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-321	1
Viton® Seal Repair Kit *Sensor and cable sold separately.	SLKT-321V	1

DIRECTCONNECT

PARALLEL GRIPPER DGC-65 TWO JAW PRECISION SPRING ASSIST



1.190



 Temperature Range
 -30°~180° F
 -35°~80° C

 Standard Seals
 -20°~300° F
 -30°~150° C

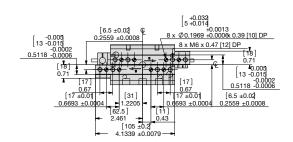
 Viton® Seals
 0.35 sec
 0.35 sec

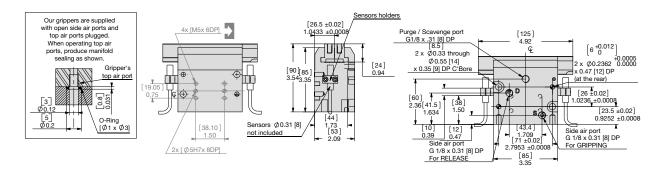
 Actuation
 ±0.009 in
 ±0.009 in

 Epeatability
 ±0.0004 in
 ±0.01 mm

 Valve required to actuate single acting
 3-way 2-position

3-way 2-position 4-way, 2-position





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW



Third Angle Projection

Valve required to actuate double acting....

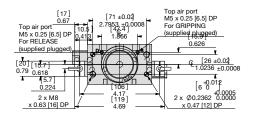
* With springs.

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch

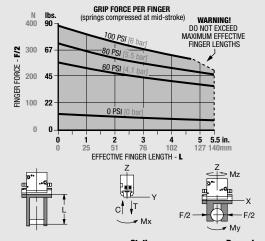
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ NOTE:
To benefit from safety springs power, on open or on close, gripper must always be operated with "S" for GRIPPING and with "D" for RELEASE.

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "S")



Loading Information

How to Order: (Order Separately)



SENSOR ACCESSORIES	ORDER #	QTY/UNIT
8mm PNP Inductive Sensor with Qk Disconnect*	0ISP-011	1 or 2
8mm NPN Inductive Sensor with Qk Disconnect*	OISN-011	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-323	1
Viton® Seal Repair Kit	SLKT-323V	1
*Conner and cable cold concretely		

SIZE VITON® SEALS

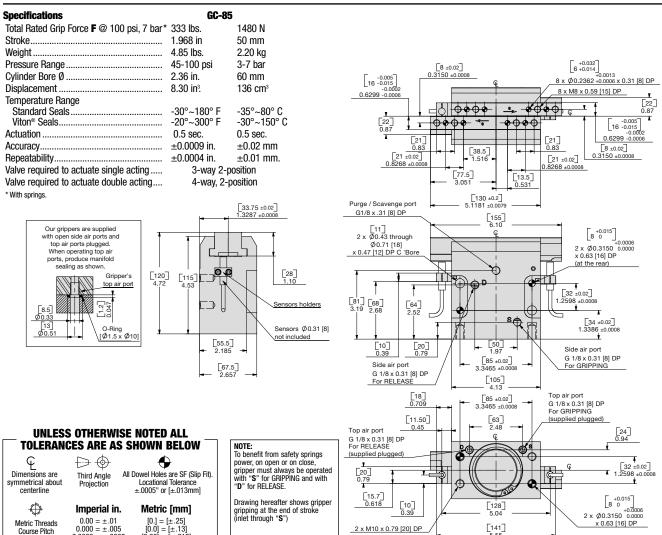
BASIC MODEL

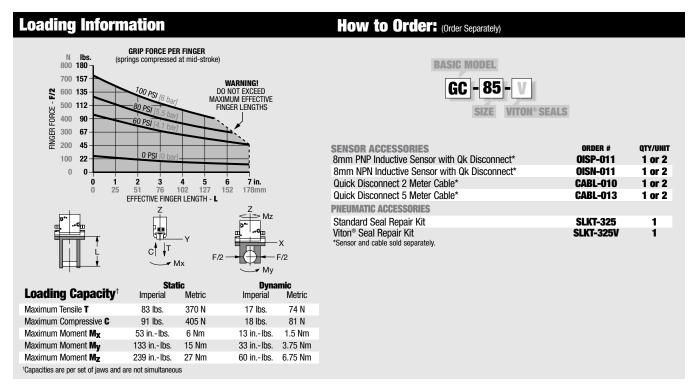
DGC - 65 -

Loading Capacity [†]	Stat Imperial	ic Metric	Dyna Imperial	mic Metric
Maximum Tensile T	61 lbs.	270 N	12 lbs.	54 N
Maximum Compressive C	69 lbs.	305 N	14 lbs.	61 N
Maximum Moment M _X	35 inlbs.	4 Nm	9 inIbs.	1 Nm
Maximum Moment My	89 inlbs.	10 Nm	22 inlbs.	2.5 Nm
Maximum Moment Mz	150 inlbs.	17 Nm	38 inlbs.	4.25 Nm
†Capacities are per set of jaws and are not simultaneous				

1.191

PARALLEL GRIPPER GC-85 TWO JAW PRECISION SPRING ASSIST





 $[0.00] = [\pm .013]$

 $0.0000 = \pm.0005$

PARALLEL GRIPPER GC-105 TWO JAW PRECISION SPRING ASSIST



8 +0.040 +0.018 +0.0016

8 x M10 x 0.71 [18] DP

Ø0.3150 +0.0007 x 0.31 [8] DP

[19] 0.75

[63 ±0.02] 2.4803 ±0.000

0.3937 0.0000 0.79 [20] DP

-0.005 21 -0.015

Specifications Total Rated Grip Force **F** @ 100 psi, 7 bar* 521 lbs. 2318 N Stroke... 2.362 in 60 mm 9.50 lbs. 4.31 kg 3-7 bar -0.005 21 -0.015 -0.000 Cylinder Bore Ø 2.99 in. 76 mm Displacement 15.93 in³. 261 cm³ 0.8268 -0.0008 Temperature Range -30°~180° F -35°~80° C Standard Seals... Viton® Seals... -20°~300° F -30°~150° C Actuation 0.7 sec. 0.7 sec. ±0.0009 in. Accuracy..... ±0.02 mm Repeatability..... ±0.0004 in. ±0.01 mm. Valve required to actuate single acting 3-way 2-position Valve required to actuate double acting.... 4-way, 2-position * With springs. Our grippers are supplied with open side air ports and top air ports plugged. When operating top air ports, produce manifold sealing as shown. Gripper's [145] 5.71 top air port Sensors holders [11.5] Ø0.45 Sensors Ø0.47 [12] [100] not included

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

(Ø1.6 x Ø13.1)

Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

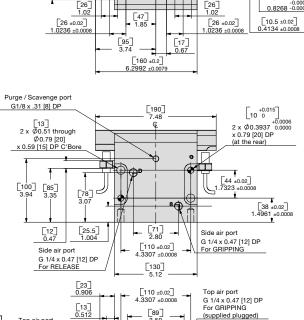
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm.0005$ Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

GRIP FORCE PER FINGER

[70.5] 2.776

NOTE: To benefit from safety springs power, on open or on close. gripper must always be operated with "S" for GRIPPING and with for RELEASE.

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "S")



0000

T

Loading Information

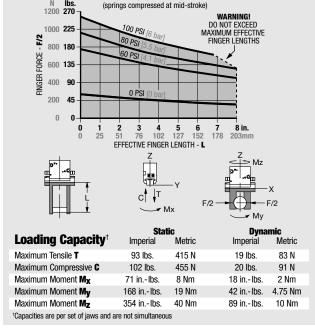
lhs.

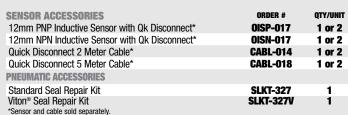
How to Order: (Order Separately)

2 x M12 x 0.79 [20] DP

Top air port

G 1/4 x 0.47 [12] DP For RELEASE (supplied plugged)





SIZE VITON® SEALS

[156] 6.14

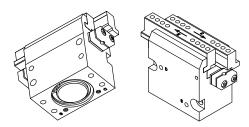
[176] 6.93

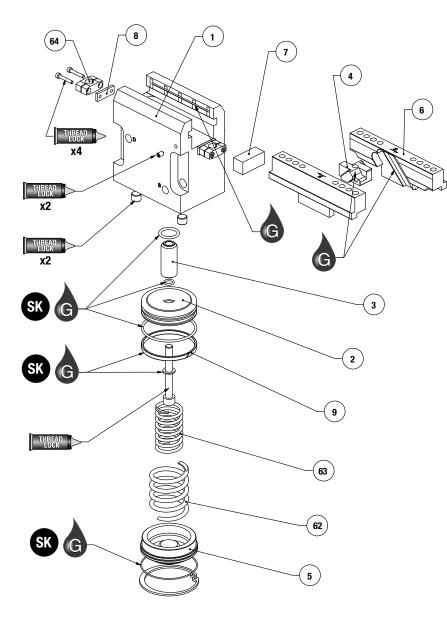
BASIC MODEL

GC - 105 -



DGC/GC Series Exploded View





Item	Qty	Name
01	1	Body
02	1	Piston
03	1	Piston Shaft
04	1	Double Wedge
05	1	Cap
06	2	Jaw Holder
07	1	Cover
80	2	Spacer
09	1	Piston Guidance Tape
62	1	Outer Spring
63	1	Inner Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals into cap (x1) and body (x1)
- 2) If rear inlets are used, clear them and plug the side inlets on the body (#1)
- 3) Lubricate the slot of jaws (#6), the double wedge (#4), and the slot of the body (#1).
- 4) Place the double wedge between the two jaws and then introduce the jaws in the slots of the body.

5) Assemble the piston:

DGC-25 & DGC-65 (not shown):
lubricate and install the seal onto the one piece piston (#3) Insert the piston into the body, locate it on the double wedge, place the seal ring under the screw cap and screw all the pieces together..

GC-85 (not shown): Insert the shaft (#3) into the body and center it in the double wedge. Lubricate and insert the seals on the piston (#2). Insert the piston into the body while centering on the shaft. Place the seal ring under the screw cap and screw all the pieces together.

GC-105: Insert the shaft (#3) into the body and center it in the double wedge. Lubricate and insert the seals and the guidance ring (#9) on the piston (#2). Insert the piston into the body while centering on the shaft. Place the seal ring under the screw cap and screw all the pieces together.

- 6) Make by hand the piston move into the body
- 7) Insert the two springs (#62 & 63) into the counterbore of the piston
- 8) Install the cap (#5) and fix it with the retaining ring.
- 9) Place and fix the wiper (#7) in the body.
- 10) Mount the sensor holder (#64) and the spacer (#8) on the body sides













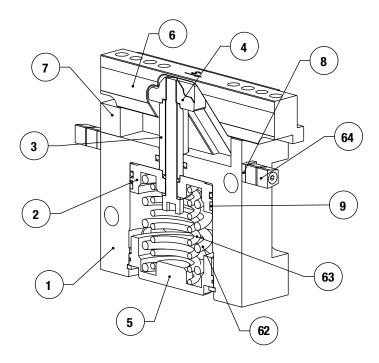




Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DGC/GC Series Assembled View





Item	Qty	Name
01	1	Body
02	1	Piston
03	1	Piston Shaft
04	1	Double Wedge
05	1	Cap
06	2	Jaw Holder
07	1	Cover
80	2	Spacer
09	1	Piston Guidance Tape
62	1	Outer Spring
63	1	Inner Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.













REG DESIGN NOTES GC SERIES 1.195

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Parallel Grippers-DPW DIRECTCONNECT[™] Wide Body Series



DIRECTONNECT

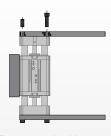
- DIRECTCONNECT™ Connectivity: DIRECTCONNECT™ Tapped and Dowel mounting on body.
- Large or Wide Parts:
 Wide body design provides secure gripping
 of large & wide parts.
- Multiple air port positions: Tapped air ports on top and front are standard.
- Manifold Air Porting:
 Top air ports can be manifold o-ring sealed.

- Inductive Sensor Flexibility:
- Mount either 3mm or 4mm Inductive sensors with the same bracket (3mm only on DPW-250).
- Magnetoresistive Sensing: Full range adjustable Magnetoresistive Sensors. Magnet supplied standard.
- Long Finger Applications: Jaw support thru the length of the body allows for long fingers to be attached to jaws.
- Thru Jaw Mounting: Offers a wider variety of mounting applications for jaws.
- Shaft Wiper Option: Rugged urethane shaft wipers seal the unit against harsh environments. Designed to be used in machine coolant and metal chip environment applications.
- Multiple Strokes: All gripper sizes are available in 2 different strokes.
- Non-synchronous motion: The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than its center.

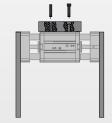
40-100 psi

Mounting Information:

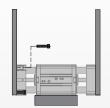
Grippers can be mounted & operated in any direction



Fingers attach with screws and locate on jaws with dowel pins



Body mounts on top with screws and locates with slip fit dowel pin holes for accuracy



Thru mounting on inside of jaws to allow for alternate finger mounting

Jaw design allows for simplified mounting of fingers



Symmetrical mounting pattern on jaws allows for multiple finger orientation

Technical Specifications:

Pneumatic Specifications

Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications

Expected Life

Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available 5 million cycles 10+ million cycles* Yes Yes

Metric

3-7 bar

Double Acting
Internally Lubricated Buna-N

4-way, 2-position

40 Micron or Better

Not Necessary* Low Moisture Content (dry)

-W Option Shaft Wiper Specifications

Wiper Material Temperature Rating (Wiper Only) Compatible Chemicals

90 Durometer Urethane -65°~275° F -54°~135° C water, coolant, petroleum oils,

silicone, lubricants, dilute acids & alkalis, hydraulic fluid, transmission fluid Non-Compatible Chemicals Ozone, ketones, strong acids,

Example Applications

brake fluid Grinding dust, machine chips & coolant, paper dust, washdown

Application Restrictions

Applications where mechanism lubricant could cause contamination (use -W Shaft Wiper Option in this case)

*Addition of lubrication will greatly increase service life

See **1.200**

Style: Stroke: 375M-1 1.00 in.



See 1.202

Style -DPW Parallel Gripper

Style: Stroke: Weight:

1.20 Kg

2.66 lbs.



Style -DPW Parallel Gripper

Size -500M

Style: 500M-1 38.1 mm Stroke: 1.50 in. Grip Force: 180 lbs. Weight: 3.27 lbs



See **1.206**

Style -DPW Parallel Gripper

Style: Stroke: 2.50 in. Grip Force: 180 lbs. Weight: 4.39 lbs.



Shaft Wiper Option

Product Features

Thru-Jaw Mounting C'bores on inside of jaws for thru mounting to increase range of applications

DIRECTCONNECT **Mounting Patterns** DIRECTCONNECT™ Tapped & Dowel mounting surface on top of body

Sealed Design (-W option) Urethane shaft wipers prevent against dirty environments (machining chips & coolant, grinding dust, paper mill environments, etc.)

Multiple Air Port Locations 2 standard airport location

(front & top)

Manifold **Air Ports** Top air ports can be O-Ring manifold sealed to eliminate air lines

Simplified Finger Mounting Large jaw

Dowel

Holes

Slip fit dowel

pin holes in

body and jaws

configuration allows for simplified finger mounting

End of Stroke **Cushions** Reduce shock of fully open

symmetrical.

multi-positional

mounting pattern for

simplified finger

design and increased

range of applications

Sensor

Mounting Slots

Standard mounting slots

for magneto resistive and

inductive sensors

(sensors sold separately)

and close strokes Square-Faced Jaws Allow for a

Magneto Resistive Sensors

An alternative option to inductive sensors (magnets supplied standard)

Combined 3mm and 4mm Inductive Sensor Mounting

Allows for either 3 or 4mm Inductive sensors (3mm only on DPW-250)

Optional Non-Synchronous Operation

Superior Jaw

Support

Each jaw is supported

by 2 shafts that extend the entire length of the

body and are guided

by 2 oil impregnated

bronze bushings per

shaft

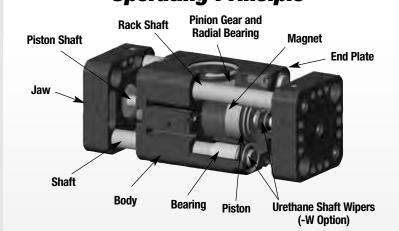
Quality Components

Hardened precision stainless steel shafting for wear resistance and long life

high temperature applications **Operating Principle**

High Temperature

Ontional Viton® seals are available for

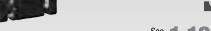






- Two shafts, one with a rack cut into it, are securely fastened to each of the jaws and ^ob supported through the length of the body.
- Two double acting opposed pistons provide power to the jaws.
- The rack shafts of each jaw slide in opposite directions of one another and are synchronized by a piston gear.
- · This gripper is suitable for internal or external gripping and can be mounted in any orientation.





Grip Force: 50 lbs. **Weight:** 0.662 lb.

0.662 lbs.

250M-1

19.1 mm

222 N

0.30 Kg

Style -DPW Parallel Gripper

Shown with -W Shaft Wiper Option

Style -DPW Parallel Gripper

Style: Stroke: 250M-2 **Size -250M-2** 1.25 in.

31.8 mm Grip Force: 50 lbs. Weight: 0.856 lb 222 N 0.39 Kg 0.856 lbs.

Size -250M-1

Shown with -W Shaft Wiper Option

Style -DPW Parallel Gripper

Size -375M-1 25.4 mm Grip Force: 100 lbs. Weight: 1.80 lbs. 0.81 Ka 1 80 lbs



Shown with -W Shaft Wiper Option

Size -375M-2 375M-2 2.00 in. 50.8 mm Grip Force: 100 lbs



Shown with -W Shaft Wiper Option



1.48 Kg



Shown with -W Shaft Wiper Option

Size -500M-2 63 5 mm 800 N 2.0 Kg



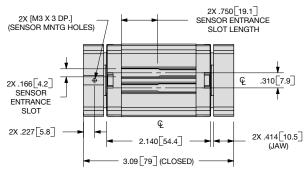
Shown with -W

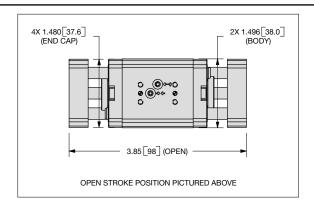
See 1.208

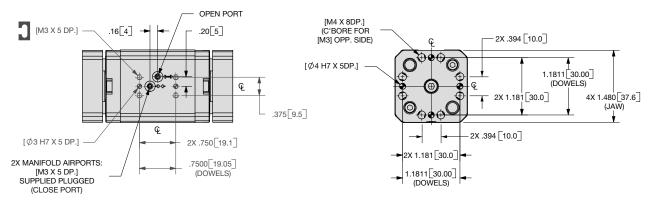
PARALLEL GRIPPERS DPW-250M-1 DIRECTCONNECT WIDE BODY SERIES

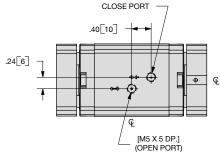


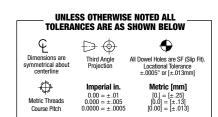












NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

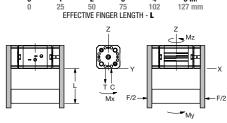
DPW-250M - 1 - NS - W - V NON-SYNCHRONOUS NS Non-Synchronous Operation Leave Blank for Synchronous (standar WIPERS W Shaft Wipers VITON SEALS V	NPN Magneto Resistive Sensor Short Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor Short Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* Quick Disconnect Cable (2 meters long)* Quick Disconnect Cable (5 meters long)* PNP Inductive Sensor 3mm (with Qk. Disc.)* NPN Inductive Sensor 3mm (with Qk. Disc.)* OISP-019 OISN-019	7 1 or 2 or 2
SAMPLE ORDER: DPW-250M-1-W-V Ex: DPW-250M Gripper, 19.1mm Stroke, Shaft Wipers, Viton Seals		



Total Rated Grip Force F @ 100 psi, 7 bar 50 lbs. 222 N 0.75 in. 19.1 mm 3-7 bar Cylinder Bore Ø 0.625 in. 15.9 mm 3.8 cm³ 0.30 Ka -35°~80° C -30°~150° C Temperature Range: Standard Seals -30°~180° F Viton® Seals -20°~300° F Actuation 0.12 sec. 0.12 sec. ±0.08 mm Accuracy ±0.003 in. ±0.03 mm Valve required to actuate 4-way, 2-position

DIRECT CONNECT WIDE BODY SERIES GRIP FORCE PER FINGER N lbs. 111 25 WARNING DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS 89 20 F/2 FINGER FORCE 67 15 45 10

PARALLEL GRIPPERS DPW-250M-1



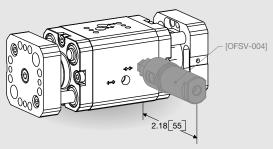
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	60 lbs. [267 N]	12 lbs. [53 N]
Maximum Compressive C	60 lbs. [267 N]	12 lbs. [53 N]
Maximum Moment M _X	120 in1bs. [14 Nm]	24 in1bs. [3 Nm]
Maximum Moment My	180 in1bs. [20 Nm]	36 in1bs. [4 Nm]
Maximum Moment Mz	120 in1bs. [14 Nm]	24 inIbs. [3 Nm]

†Capacities are per set of jaws and are not simultaneous

22 5

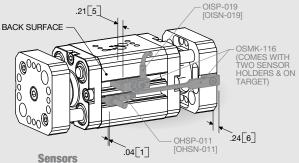
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Accessory Mounting Technical Data

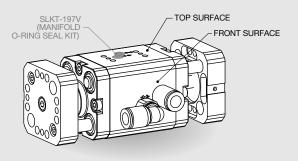


Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port

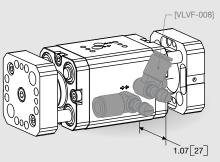


- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
 Available with 2M or 5M Quick Disconnect mating cable (order separately)



Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- · Front air ports are tapped for M5 fittings



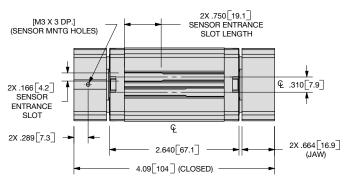
Flow Controls

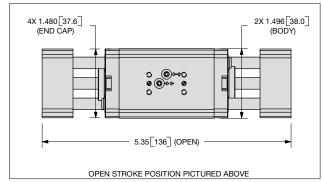
- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing

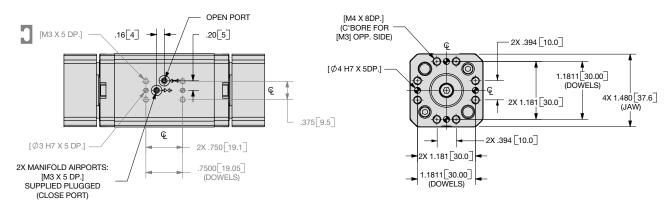
PARALLEL GRIPPERS DPW-250M-2 DIRECTCONNECT WIDE BODY SERIES

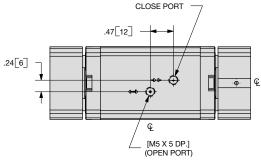












UNLESS OTHERWISE NOTED ALL

TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

Imperial in.

0.00 = ±.01
0.000 = ±.005
0.001 (±.013mm)

| Metric Threads
Course Pitch
| 0.000 = ±.005
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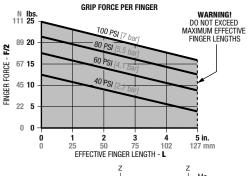
NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

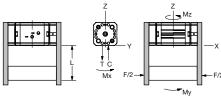
DPW-250M -	NON-SYNCHRONOUS Non-Synchronous Operation Leave Blank for Synchronous (standard)	PNP Magneto Resistive Sensor Short Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor Short Barrel (with Qk. Disc.)* PNP Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* PNP Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* Quick Disconnect Cable (2 meters long)* Quick Disconnect Cable (5 meters long)* PNP Inductive Sensor 3mm (with Qk. Disc.)* NPN Inductive Sensor 3mm (with Qk. Disc.)* Sensor Mounting Kit for 3mm Inductive Sensor PNEUMATIC ACCESSORIES Seal Repair Kit (Standard Buna-N) Seal Repair Kit (Viton®) Manifold Seal Kit (Viton®) Shaft Wiper Seal Kit Fail Safe Valve M5 Adjustable Flow Control *Sensor and cable sold separately	ORDER # OHSP-017 OHSP-017 OHSP-011 OHSP-011 CABL-010 CABL-013 OISP-019 OISN-019 OSMK-116 ORDER # SLKT-337 SLKT-337V SLKT-197V SLKT-197V SLKT-338 OFSV-004 VLVF-008	QTY/UNIT 1 or 2
	RDER: DPW-250M-2-W-V oper, 31.8mm Stroke, Shaft Wipers, Viton Seals			



Total Rated Grip Force F @ 100 psi, 7 bar 50 lbs. 222 N 1.25 in. 31.8 mm Pressure Range..... 3-7 bar 40-100 psi Cylinder Bore Ø 0.625 in. 15.9 mm 6.3 cm³ Weight...... 0.856 lbs. 0.39 Ka Temperature Range: Standard Seals -30°~180° F -35°~80° C Viton® Seals -20°~300° F -30°~150° C Actuation 0.14 sec. 0.14 sec. ±0.08 mm Accuracy ±0.003 in. ±0.03 mm Valve required to actuate 4-way, 2-position

PARALLEL GRIPPERS DPW-250M-2 DIRECT CONNECT WIDE BODY SERIES

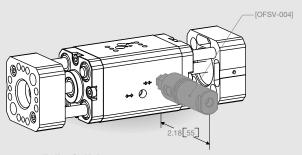




Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	60 lbs. [267 N]	12 lbs. [53 N]
Maximum Compressive C	60 lbs. [267 N]	12 lbs. [53 N]
Maximum Moment M _X	120 in1bs. [14 Nm]	24 in1bs. [3 Nm]
Maximum Moment My	180 in1bs. [20 Nm]	36 inIbs. [4 Nm]
Maximum Moment Mz	120 in1bs. [14 Nm]	24 inIbs. [3 Nm]

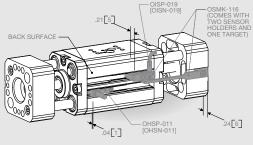
†Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



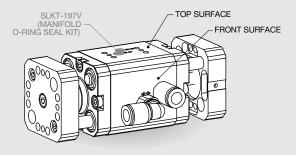
Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port



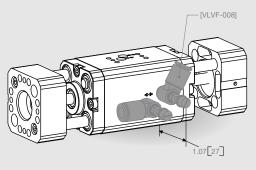
Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
 Available with 2M or 5M Quick Disconnect mating cable (order separately)



Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- · Front air ports are tapped for M5 fittings



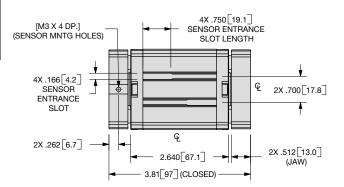
Flow Controls

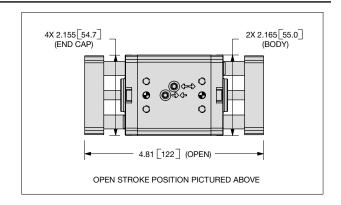
- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing

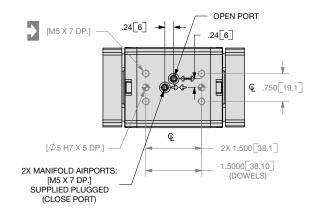
PARALLEL GRIPPERS DPW-375M-1 DIRECTCONNECT WIDE BODY SERIES

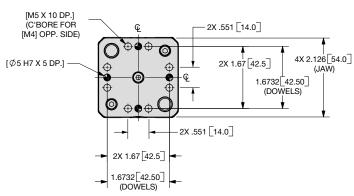


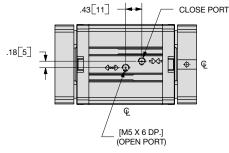


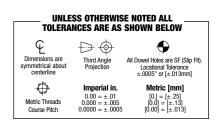




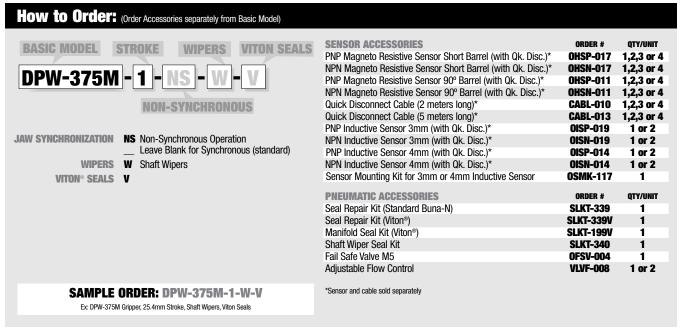








NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

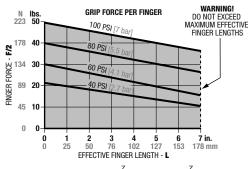


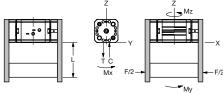
1.203



DPW-375M-1 Total Rated Grip Force **F** @ 100 psi, 7 bar 100 lbs. 445 N 25.4 mm Pressure Range..... 3-7 bar 40-100 psi Cylinder Bore Ø 0.938 in. 23.8 mm Displacement 0.690 in³. 11.3 cm³ 0.81 Ka -35°~80° C -30°~150° C Temperature Range: Standard Seals -30°~180° F Viton® Seals -20°~300° F Actuation 0.16 sec. 0.16 sec. ±0.08 mm Accuracy ±0.003 in. Repeatability..... ±0.001 in. ±0.03 mm Valve required to actuate 4-way, 2-position

PARALLEL GRIPPERS DPW-375M-1 DIRECT CONNECT WIDE BODY SERIES

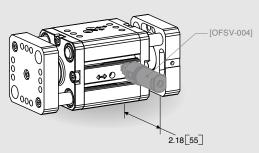




Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	120 lbs. [534 N]	24 lbs. [107 N]
Maximum Compressive C	120 lbs. [534 N]	24 lbs. [107 N]
Maximum Moment M _X	210 in1bs. [24 Nm]	42 in1bs. [5 Nm]
Maximum Moment My	300 in1bs. [34 Nm]	60 in1bs. [7 Nm]
Maximum Moment Mz	210 in1bs. [24 Nm]	42 in1bs. [5 Nm]

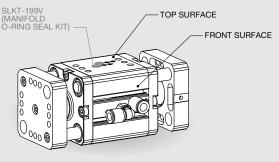
†Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



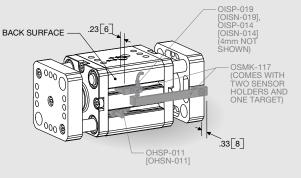
Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- · Mounts directly to gripper
- . M5 air port



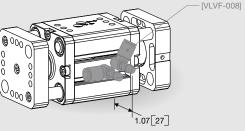
Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- · Front air ports are tapped for M5 fittings



Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- · Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
- Available with 2M or 5M Quick Disconnect mating cable

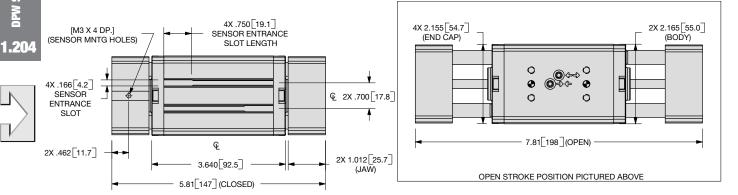


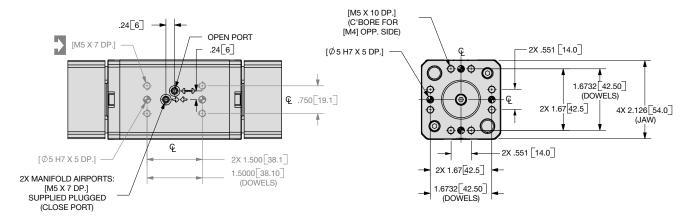
Flow Controls

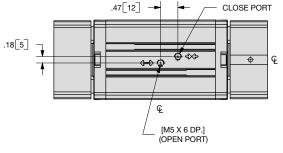
- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing

PARALLEL GRIPPERS DPW-375M-2 DIRECTCONNECT WIDE BODY SERIES









UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

q Dimensions are symmetrical about centerline

Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

Imperial in. 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

JAW SYNCHRONIZATION NS Non-Synch	WIPERS VITON SEALS S - W - V YNCHRONOUS Ironous Operation isk for Synchronous (standard)	NPN Magneto Resistive Sensor Short Barrel (with Qk. Disc.)* PNP Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* NPN Magneto Resistive Sensor 90° Barrel (with Qk. Disc.)* Quick Disconnect Cable (2 meters long)* Quick Disconnect Cable (5 meters long)* PNP Inductive Sensor 3mm (with Qk. Disc.)* NPN Inductive Sensor 3mm (with Qk. Disc.)* PNP Inductive Sensor 4mm (with Qk. Disc.)* NPN Inductive Sensor 4mm (with Qk. Disc.)* Sensor Mounting Kit for 3mm or 4mm Inductive Sensor PNEUMATIC ACCESSORIES Seal Repair Kit (Standard Buna-N) Seal Repair Kit (Viton*) Manifold Seal Kit (Viton*) Shaft Wiper Seal Kit Fail Safe Valve M5	ORDER # OHSP-017 OHSN-017 OHSN-011 DHSN-011 CABL-010 CABL-013 OISP-019 OISN-019 OISN-014 OISN-014 OSMK-117 ORDER # SLKT-339 SLKT-339 SLKT-99V SLKT-940 VLVF-008	QTY/UNIT 1,2,3 or 4 1,2,3 or 2 1 or 1 1 1 1 1 1 1 1 1 or 2
SAMPLE ORDER: DPV Ex: DPW-375 M Gripper, 50.8mm Strok		*Sensor and cable sold separately		

1.205



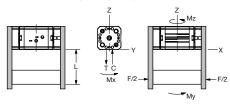
Total Rated Grip Force **F** @ 100 psi, 7 bar 100 lbs. 445 N 2.00 in. 50.8mm Pressure Range..... 3-7 bar 40-100 psi Cylinder Bore Ø 0.938 in. 23.8 mm 22.6 cm³ 1.20 Ka -35°~80° C Temperature Range: Standard Seals -30°~180° F Viton® Seals -20°~300° F -30°~150° C Actuation 0.20 sec. 0.20 sec. Accuracy ±0.003 in. ±0.08 mm

±0.03 mm

4-way, 2-position

WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE GRIP FORCE PER FINGER N lbs. 223 50 ₽ ¹⁷⁸ 40 FINGER LENGTHS 134 30-134 30-89 20-45 10 0 EFFECTIVE FINGER LENGTH - L

PARALLEL GRIPPERS DPW-375M-2 DIRECT CONNECT WIDE BODY SERIES

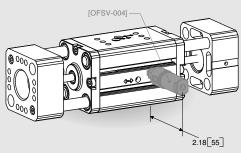


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	120 lbs. [534 N]	24 lbs. [107 N]
Maximum Compressive C	120 lbs. [534 N]	24 lbs. [107 N]
Maximum Moment M _X	210 in1bs. [24 Nm]	42 in1bs. [5 Nm]
Maximum Moment My	300 in1bs. [34 Nm]	60 in1bs. [7 Nm]
Maximum Moment Mz	210 in1bs. [24 Nm]	42 in1bs. [5 Nm]

†Capacities are per set of jaws and are not simultaneous

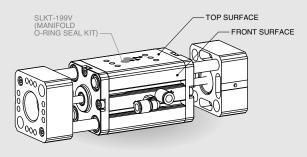
Accessory Mounting Technical Data

Valve required to actuate



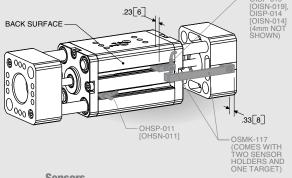
Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- · Mounts directly to gripper
- . M5 air port



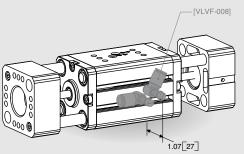
Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- · Front air ports are tapped for M5 fittings



Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- · Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
- Available with 2M or 5M Quick Disconnect mating cable



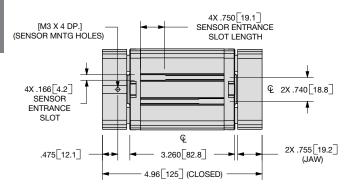
Flow Controls

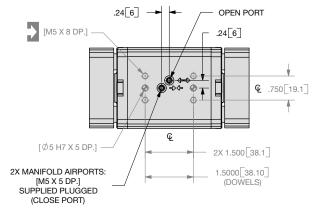
- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing

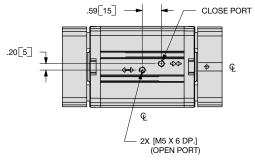
PARALLEL GRIPPERS DPW-500M-1 DIRECTCONNECT WIDE BODY SERIES

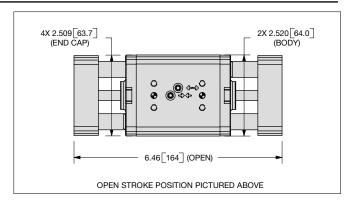


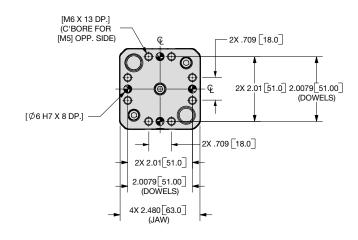


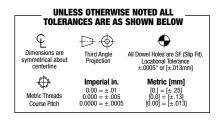




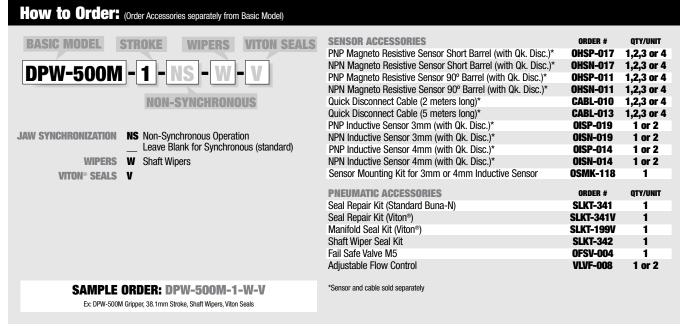








NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

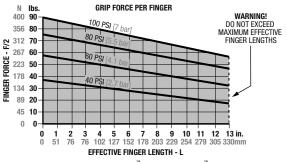


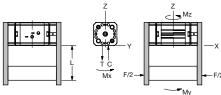
1.207



PARALLEL GRIPPERS DPW-500M-1 DIRECT CONNECT WIDE BODY SERIES

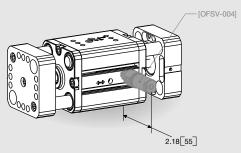
Specifications	DPW-500	M-1
Total Rated Grip Force F @ 100 psi, 7 bar	180 lbs.	800 N
Stroke	1.50 in.	38.1 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	1.841 in ³ .	30.2 cm ³
Weight	3.27 lbs.	1.48 Kg
Temperature Range: Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°∼300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-position	





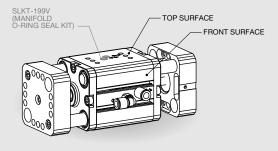
†Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



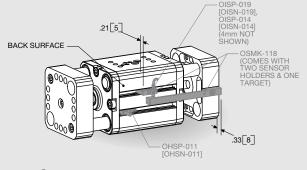
Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port



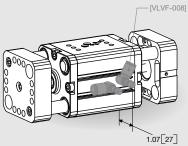
Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- Front air ports are tapped for M5 fittings



Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- · Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Flow Controls

- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing

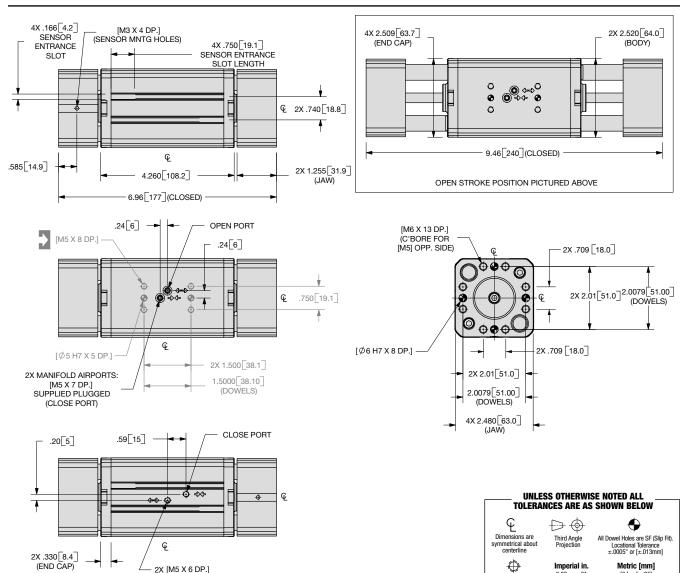
DIRECTCONNECT

PARALLEL GRIPPERS DPW-500M-2 DIRECTCONNECT WIDE BODY SERIES



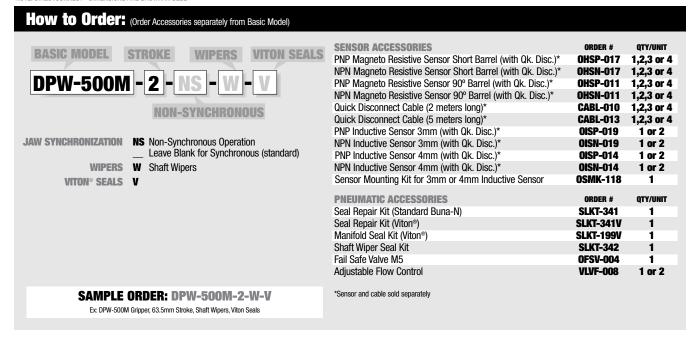
0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

Metric Threads Course Pitch



NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

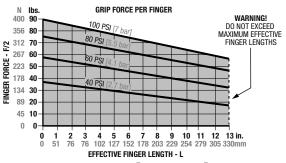
(OPEN PORT)

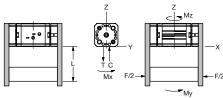




PARALLEL GRIPPERS DPW-500M-2 DIRECT CONNECT WIDE BODY SERIES

Specifications	DPW-500)M-2
Total Rated Grip Force F @ 100 psi, 7 bar	180 lbs.	800 N
Stroke	2.50 in.	63.5 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	3.068 in ³ .	50.3 cm ³
Weight	4.39 lbs.	2.0 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.28 sec.	0.28 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

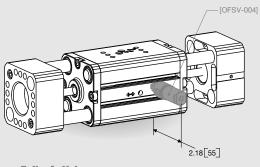




Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	600 lbs. [2668 N]	60 lbs. [267 N]
Maximum Compressive C	600 lbs. [2668 N]	60 lbs. [267 N]
Maximum Moment M _X	600 in1bs. [68 Nm]	60 inIbs. [7 Nm]
Maximum Moment My	900 in1bs. [102 Nm]	90 inIbs. [10 Nm]
Maximum Moment Mz	600 in1bs. [68 Nm]	60 inIbs. [7 Nm]

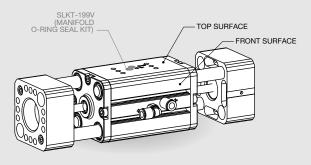
†Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



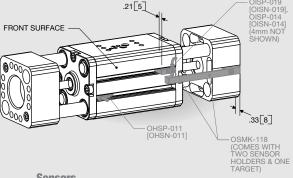
Failsafe Valves

- Used in applications where it is critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port



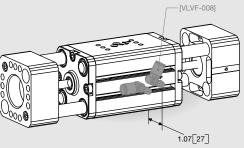
Multiple Air Port Locations

- 2 standard air port locations (top and front surface)
- Top manifold air ports are supplied plugged
- Seals in manifold kit are Viton®
- Front air ports are tapped for M5 fittings



Sensors

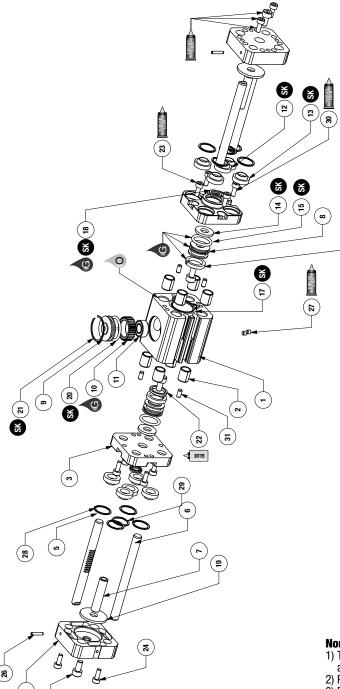
- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting Kits required
- Low profile underflush sensor version or 90° wire exit sensor version
- · Simple adjustment with slotted screw driver
- PNP and NPN inductive available
- Inductive sensor bracket mounts 3mm sensor
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Flow Controls

- Thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing





	Obs	Name
Item	Qty	Name
01	1	Body
02	8	Bushing, Oil Impregnated Bronze
03	2	End Cap
04	2	Jaw
05*	2 2 2	Guide Shaft, Rack
06*	2	Guide Shaft (Qty 4 for -NS)
07		Piston Rod
80	2	Piston
09	1	Cap, Gear
10*	1	Gear
11*	1	Bearing, Radial
12*	2	Piston Rod Wiper (Shaft Wiper
		"-W" option only)
13*	8	Shaft Wiper (Shaft Wiper "-W" option only)
14	2	Piston Bumper
15	2	Piston 0-ring
16	2	Teflon Ring
17*	2 2	Body O-ring
18	2	U-cup
19	2	Jaw Bumper
20	1	Gear Cap O-ring
21	1	Retaining Ring
22	1	Magnet
23	8	End Cap Mntg Screw
24	4	Guide Shaft Mntg Screw
25	4	Piston Shaft Mntg Screw
26*	2	Guide Shaft Alignment Dowel
27	2	Manifold Port Plug
28	8	Retainer Ring (Shaft Wiper "-W" Option only)
29	2	Retainer Ring (Shaft Wiper "-W" Option only)
30*	4	End Cap Mntg Screw
31	4	End Cap Dowel Pins
		•

*Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Quantity of #6 is 4 when ordering a Non-synchronous aripper.
- 3) Items #5, #10, #11, and #26 are for synchronous grippers only.
- 4) Items #12 and #13 are for -W option only.
- 5) Item #17 (Body O-ring) shown in body groove.
- 6) Item #23 Quantity is 6 for 375-1 and 375-2 only.
- 7) Item #30 is only used in 375-1 and 375-2.

Non-Synchronous Procedure:

- 1) Take DPW synchronous gripper and remove the retaining ring and gear cap.
- Remove gear from gripper.
- 3) Replace gear cap and retaining ring. The gripper is now non-synchronous

-W Option Assembly Procedure:

- 1) Take out guide shaft and piston rod mounting screws. 2) Remove jaws from guide shafts and piston rods.
- Take out end cap mounting screws and pull off end caps. Take out piston.
- 4) Slide out shafts and press wipers in pockets thru front side. Install retaining rings.
- 5) Replace shafts, pistons, and end caps.
- 6) Be sure to apply thread locker to mounting screws. The gripper now has shaft wipers.

Assembly Procedure:

- 1) Lubricate and install seals on piston.
- 2) Install pistons and shafts.
- 3) Mount end caps to enclose piston assembly.
- 4) Install tooling plates and shafts.
- 5) Place bearing, shaft, and gear into body and install cap and retaining ring for sync version.
- a) For disassembly, use magnet to pull gear out of body.
- b) Install 2 gear shafts with teeth facing syncing gear. Use dowel to align gear shafts in correct position.











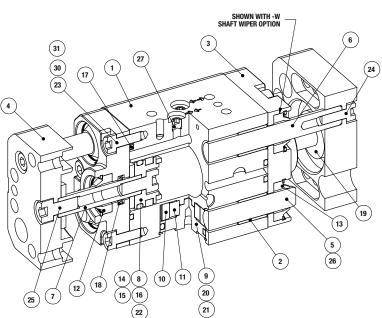
Teflon™ Based



Super Bonder



DPW SERIES ASSEMBLED VIEW

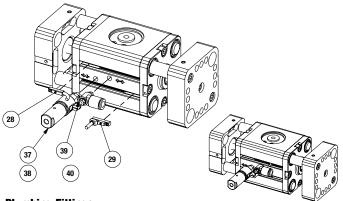


*Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Quantity of #6 is 4 when ordering a Non-synchronous gripper.
- 3) Items #5, #10, #11, and #26 are for synchronous grippers only.
- 4) Items #12 and #13 are for -W option only.
- 5) Item #17 (Body 0-ring) shown in body groove.
- 6) Item #23 Quantity is 6 for 375-1 and 375-2 only.
- 7) Item #30 is only used in 375-1 and 375-2.

	Item	Qty	Name
	01	1	Body
	02	8	Bushing, Oil Impregnated Bronze
	03	2	End Cap
)	04	2	Jaw
	05*	2	Guide Shaft, Rack
	06*	2	Guide Shaft (Qty 4 for NS)
	07	2	Piston Rod
	08	2	Piston
	09	1	Cap, Gear
	10*	1	Gear
	11*	1	Bearing, Radial
	12*	2	Piston Rod Wiper (Shaft Wiper "-W" option only)
	13*	8	Shaft Wiper (Shaft Wiper "-W" option only)
	14	2	Piston Bumper
	15	2	Piston 0-Ring
	16	2	Teflon Ring
	17*	2	Body 0-Ring
	18	2	U-cup
	19	2	Jaw Bumper
	20	1	Gear Cap O-ring
	21	1	Retaining ring
	22	1	Magnet
	23	8	End Cap Mntg Screw
	24	4	Guide Shaft Mntg Screw
	25	4	Piston Shaft Mntg Screw
	26*	2	Guide Shaft Alignment Dowel
	27	2	Manifold Port Plug
	28	8	Retainer Ring (Shaft Wiper "-W" Option only)
	29	2	Retainer Ring (Shaft Wiper "-W" Option only)
	30*	4	End Cap Mntg Screw
	31	4	End Cap Dowel Pins

Accessory Installation & Adjustment Instructions



Plumbing Fittings:

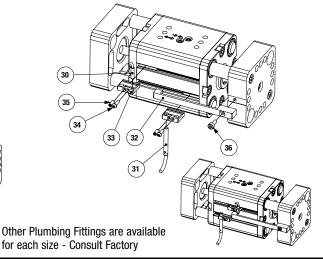
- 1) Flow Controls #39 or #40 can be inserted and used in any open or closed airport to help control the stroke actuation.
- 2) Fail-Safe Valve #37 or #38 can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Magneto-Resistive Sensors:

1) Insert sensors #28 or #29 into the opening at the end of the profile slot and lock the sensor into position with the integrated screw.

Inductive Sensors:

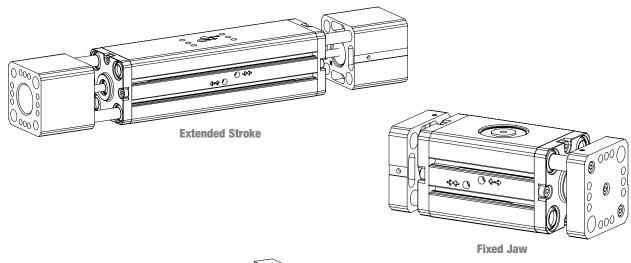
- Mount inductive sensor target (#32) to jaw using mounting screw (#36).
 Insert sensor bracket (#33) into slot of body.
 Insert sensor (#30 or #31) into appropriate 3mm or 4mm opening in bracket and adjust sensor depth so that sensor light indicates target (#32).
- 4) Tighten sensor locking screw (#34).
- 5) Position sensor bracket for desired stroke detection.
- 6) Tighten sensor bracket with set screw (#35) to lock stroke detection position.

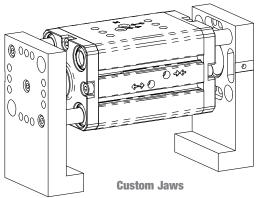


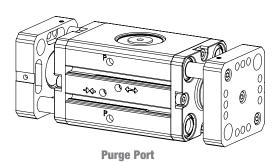
Disconnect
Diocominoct
Disconnect
ow - 1/4" OD
Smm OD

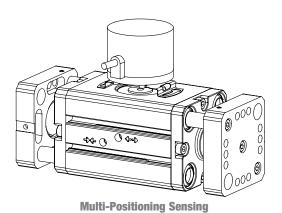
Smaller or Larger Bores Metallic Rod Scrapers Extended Strokes Alternate Materials and more...

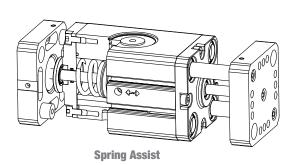
Drawings are for concept only. Contact Robohand Tech Support with project requirements.



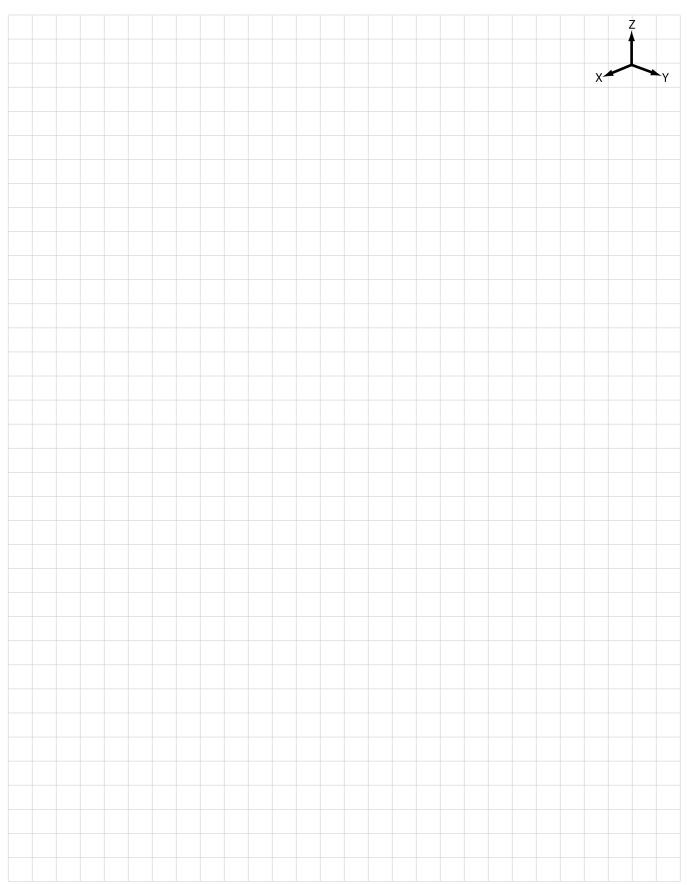




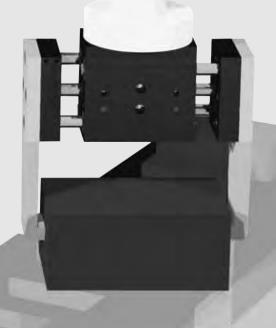


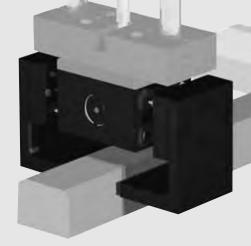


Please describe your application. Include a sketch or attach additional sheets if necessary.



Parallel Grippers-Wide Body Series





Machining applications:

Sealed design repels chips and other particulate from the internal drive mechanism.

Long gripper fingers:

Jaw support thru the length of the body allows for long fingers to be attached to the jaws.

Large or wide parts:

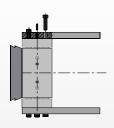
Wide body design provides secure gripping of large & wide parts.

• Non synchronous motion:

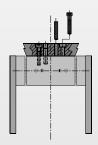
The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

Mounting Information:

Grippers can be mounted & operated in any orientation

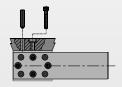


Fingers attach with screws and locate on jaws with dowel pins





Jaw design allows for simplified mounting of fingers



Body mounts on top or on side with screws and locates with slip fit dowel pin holes for accuracy

Technical Specifications:

Pneumatic Specifications Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar **Dual Double Acting** Cylinder Type Dynamic Seals Internally Lubricated Buna-N Valve Required 4-way, 2-position

Air Quality Requirements

40 Micron or Better Air Filtration Air Lubrication **Not Necessary* Low Moisture Content (dry)** Air Humidity

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C -30°~150° C -20°~300° F Viton® Seals (optional)

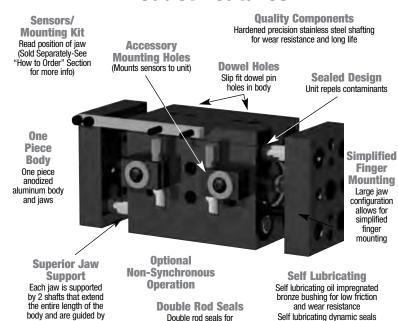
Maintenance Specifications[†]

Expected Life

Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

*Addition of lubrication will greatly increase service life †See Maintenance Section

Product Features

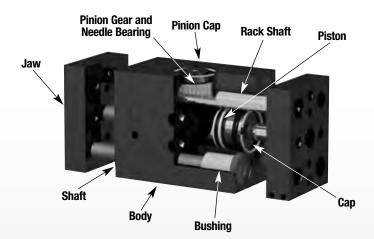


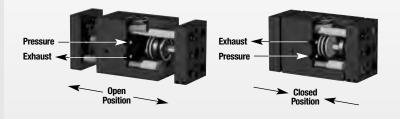
Operating Principle

longer life

2 bronze bushings

per shaft





- Two shafts, one with a rack cut into it, are securely fastened to each of the jaws and are supported through the length of the body.
- Two double acting opposed pistons provide power to the jaws.
- The rack shafts of each jaw slide in opposite directions of one another and are synchronized by a pinion gear.
- This gripper is suitable for internal or external gripping.

U.S. Patent # 5,163,729 Designed and manufactured in the USA

Style-RPW Parallel Gripper Size -625M-1 Stroke: Grip Force: 240 lb Weight: 6.5 lb 625M-1 50.8 mm 1068 N 2.95 Kg

Style-RPW Parallel Gripper

Size -625M-2 Stroke: 3.50 in. 625M-2 88.9 mm 1068 N weight: 7.8 lb 3.55 Kg



See **1.217** Page

See 1.216

Style-RPW Parallel Gripper

 Size
 -750M
 Stroke:
 4.50 in.
 114.3 mm

 Grip Force:
 470 lb
 2091 N

 Weight:
 14 lb
 6.36 Kg

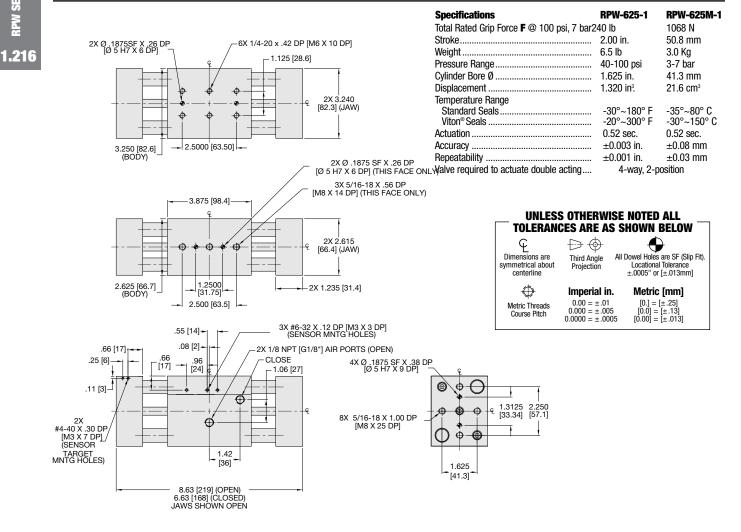


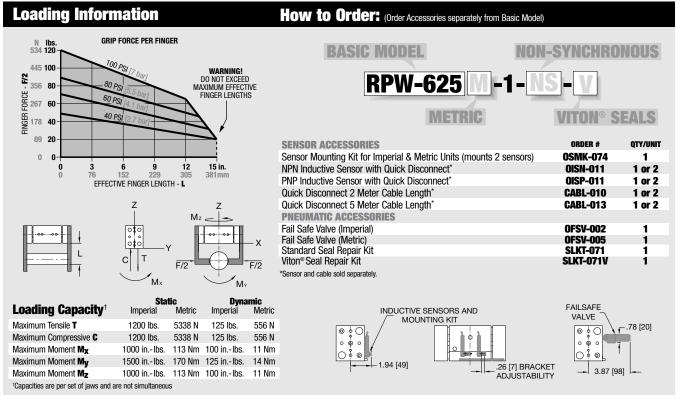
See **1.218** Page **1.218**

Note: Please refer to the New DPW series for sizes of RPW-250 through RPW-500-2 on pages 1.196 to 1.209. The RPW series information on these sizes is still available on our website and are available for sale. We encourage you to consider the new DPW design for new projects.

(Buna-N only)

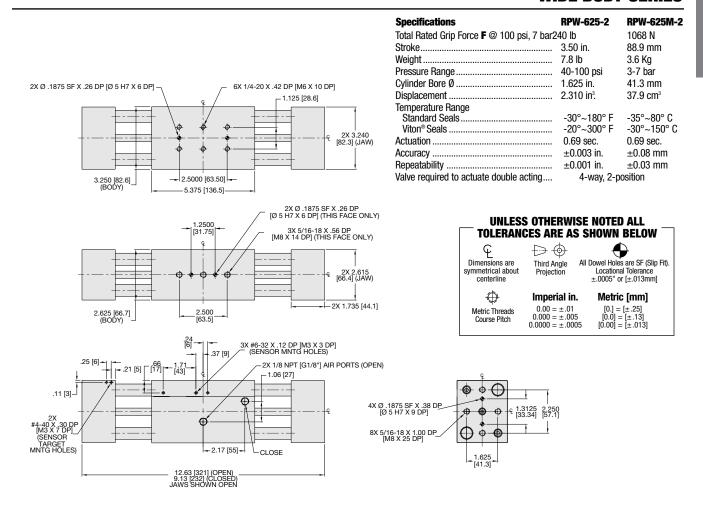


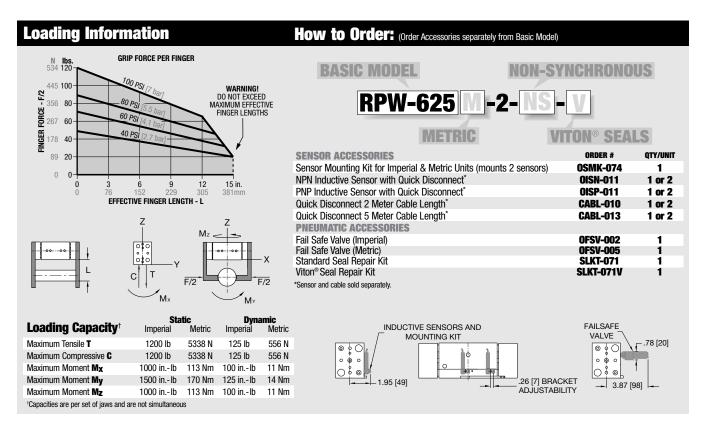


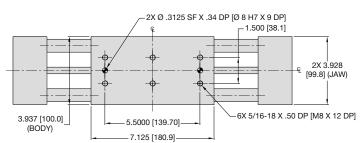




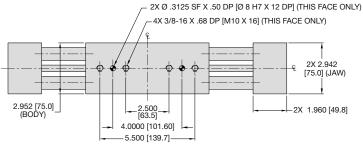
PARALLEL GRIPPER RPW-625M-2 WIDE BODY SERIES

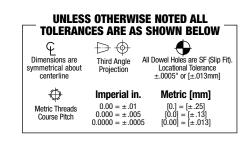


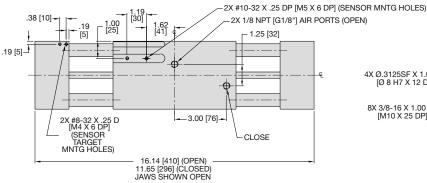




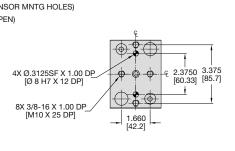
Specifications	RPW-750	RPW-750M
Total Rated Grip Force F @ 100 psi, 7 bar4	70 lb	2091 N
Stroke	4.50 in.	114.3 mm
Weight	14 lb	6.4 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	2.000 in.	50.8 mm
Displacement	14.200 in ³ .	232.7 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	1.00 sec.	1.00 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition





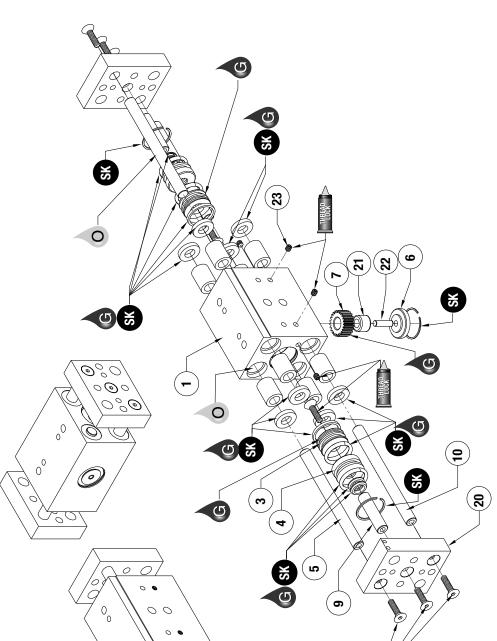


†Capacities are per set of jaws and are not simultaneous



Loading Information How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER N lbs 1113 250 **BASIC MODEL** NON-SYNCHRONOUS **≥** 890 200 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE **RPW-750** 80 PSI FORCE 668 150 FINGER LENGTHS 60 PSI FINGER **METRIC** VITON® SEALS **SENSOR ACCESSORIES** ORDER # QTY/UNIT Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-014** 1 NPN Inductive Sensor with Quick Disconnect* **OISN-011** 1 or 2 12 16 PNP Inductive Sensor with Quick Disconnect* **OISP-011** 1 or 2 **EFFECTIVE FINGER LENGTH - L** Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length* **CABL-013** 1 or 2 **PNEUMATIC ACCESSORIES** Fail Safe Valve (Imperial) **OFSV-002** 1 **OFSV-005** Fail Safe Valve (Metric) **SLKT-060** Standard Seal Repair Kit 1 SLKT-060V Viton® Seal Repair Kit Т F/2 F/2 *Sensor and cable sold separately. М× M INDUCTIVE SENSORS AND FAILSAFE Static **Dynamic** MOUNTING KIT VALVE Loading Capacity[†] Metric Metric Imperial Imperial -.88 [22] @ **\$** C @ **\$** O Maximum Tensile T 2500 lb 1112 N 11121 N 250 lb 0 0 Maximum Compressive C 2500 lb 11121 N 250 lb 1112 N 0 0 Maximum Moment Mx 2000 in.-lb 226 Nm 200 in.-lb 22 Nm 0 Maximum Moment My 3000 in.-lb 339 Nm 250 in.-lb 28 Nm 4.04 [103] .36 [9] BRACKET -2.20 [56] Maximum Moment Mz ADJÚSTABILITY 2000 in.-lb 226 Nm 200 in.-lb 22 Nm

RPW Series Exploded View



Item	Qty	Name
<u>01</u>	_1_	Body
03	2	Piston
04	2	Cap
05	2	Shaft
06	1	Gear Cover
07	1	Gear
09	2	Shaft, Piston
10	2	Shaft,Gear
20	2	Block, End W/ Target Holes
21	1	Bearing, Needle
22	1	Dowel Pin
23	1	Ball

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals.
- 2) Install pistons and shafts.*
- 3) Place piston caps and retaining rings into body
- 4) Install tooling plates and shafts
- 5) Place bearing, shaft, and gear** into body and install cap and retaining ring.for sync. version:
- a) For disassembly, use magnet to pull gear out of body.
- b) Install 2 rack shafts with teeth facing syncing gear.

Non-Synchronous Procedure

- 1) Take RPW synchronous gripper and remove the retainer ring and gear cover.
- 2) Slide out dowel pin and bearing.
- 3) Remove gear from gripper. (a magnet is often very helpful in removing the gear.)
- 4) Replace the dowel pin, gear cover, and retainer ring. The gripper is now non-synchronous.







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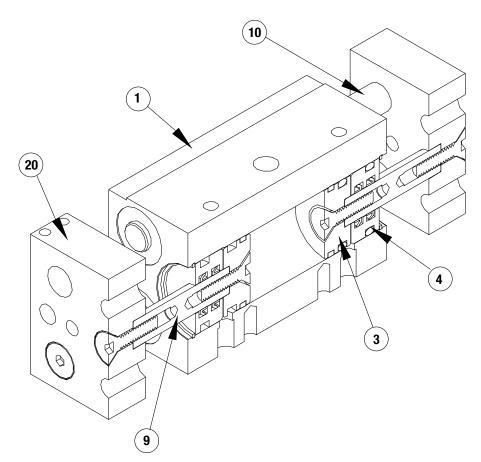








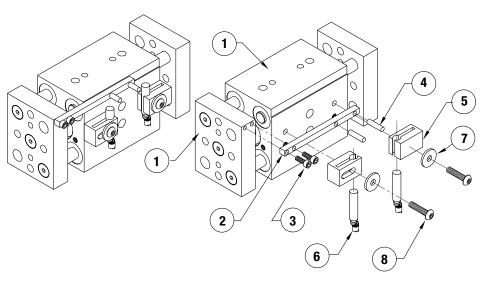




Item Qty		Name
01	1	Body
03	2	Piston
04	2	Cap
05	2	Shaft
06	1	Gear Cover
07	1	Gear
09	2	Shaft, Piston
10	2	Shaft,Gear
20	2	Block, End W/ Target Holes
21	1	Bearing, Needle
22	1	Dowel Pin
23	1	Ball

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Install target as shown, install sensors as shown, adjust for proper end of stroke sensing.















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PREGISDESIGN NOTES

1.221

Parallel Grippers -RPR Gladiator Series

- Large, heavy or wide parts:
 Wide body & long stroke design provide secure gripping of large heavy parts.
- Machining & foundry applications: Rod wipers repel chips and other particulate.
- Gripper Interchangeability:
 Bolt in replacement for PHD's GRR series gripper
- Multiple Sensing Options: Choose between inductive proximity sensors or a linear encoder.
- Maximum rigidity:
 Jaws are supported by 3 shafts, shafts are supported at 3 points.

• Long Finger Applications:

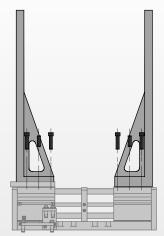
Rigid design and full body support of jaws allows for longer finger lengths.

Non-synchronous motion:

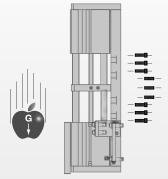
The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick and place at a point other than it's center.

Mounting Information:

Grippers can be mounted & operated in any orientation



Fingers mount on the bottom of the jaws with screws and dowel pins.



Body mounts with screws from behind and slip fit dowel pin holes for accuracy.

Technical Specifications:

Pressure Operating Range
Cylinder Type
Dynamic Seals
Valve Required to Operate

Imperial
40-100 psi
3-7 bar
Double Acting
Internally Lubricated Buna-N
4-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better
Air Lubrication Not Necessary*
Air Humidity Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications

Expected Life
Normal Application
w/ Preventative Maintenance
Field Repairable
Seal Repair Kits Available

Sean Repair Kits Available

5 million cycles
10+ million cycles*
Yes
Yes

*Addition of lubrication will greatly increase service life

Product Features

Stroke Available with 200mm

stroke. Consult factory

for different strokes

Rack & Pinion Synchronizer Rack and Pinion Synchronizer built inside the back

plate for protection against contaminants and harsh environment. Optional non-synchronized gripper available.

Rigid, Jaw bearing support Four, Flouropolymer composite bushings provide enhanced support to the jaws, protect against contaminants and corrosive environment

Gripper **Actuation Ports** Easy access to gripper open and close ports



Seals and Wipers Pressure energized seals

inside jaws offer minimum breakaway friction and enhanced cycle time. Other optional seals available for higher temperature and specific chemical compatibility

superior wear and corrosion resistsance

Superior Jaw Support Three, One piece, Case hardened, Precision ground linear guides provide higher stiffness and precision guide to the Jaws

Enhanced Piston Tube Ground, stainless steel piston tube for

against contaminants. **Optional - Jaw Position Analog sensors**

Optional - Rod Lock Optional Rod Lock valves available to lock jaws in position in case or air loss

Pented

Rod lock design integral inside the

jaw provide provide protection

Optional Analog sensors available to continuously detect jaw positions along the stroke

Simplified Finger Mounting

Optional - Gripper Open and Gripper

Close Inductive Sensors

Optional Inductive sensors available to detect gripper

open and close positions

Large jaw configuration to accept heavy loads and equipped with dowel holes for precision assembly with fingers. The iaws are supplied with coated steel inserts for superior clamping force and corrosion resistance.

Operating Principle

Back Plate with Rack & Pinion (Jaw Synchronizer)

Bearing and Shaft Protection

Four shaft wipers provide continuous protection

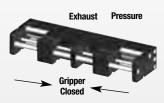
to the bearings inside the jaws

Gripper Open Port Gripper Close Port



Seals and O-Rings





(4 per Jaw)

- Two jaws are equipped with linear bearings and supported on three precision ground shafts.
- Each of the jaws are also engaged with stationary piston assembly inside them.
- Each of the piston assemblies receive pressurized air via any one of the two air tubes. Depending upon the gripper port used, the corresponding air tube will direct the pressurized air to open or close the jaws.
- The jaws are mechanically synchronized with two racks and a pinion located in the back plate.
- The gripper is also available without rack and pinion in non-synchronous configurtion.
- This gripper is available with inductive sensors to detect jaw open and jaw closed positions.
- This gripper is also available with anolog sensor to detect jaw positions any where along the gripper stroke.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation.

Style -RPR-63M Parallel Gripper

Size -63M-200

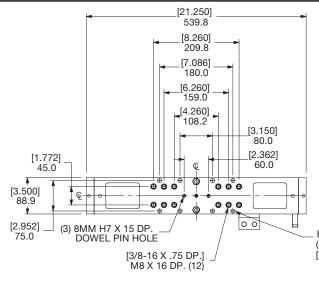
RPR-63 Stroke: 200 mm Grip Force: 800 lbs. Weight: 35 lbs. 3520 N 15.8 Kg



Note: Additional strokes availble upon request. Contact DE-STA-CO for more information.

PARALLEL GRIPPER RPR GLADIATOR SERIES





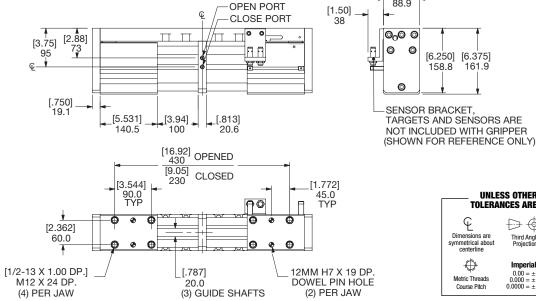
Specifications	KPK-63	KPK-63W
Total Rated Grip Force F @ 100 psi, 7 bar	800 lbs.	3520 N
Stroke	7.87 in.	200 mm
Weight	35 lbs.	15.8 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	2.48 in.	63 mm
Displacement	38.2 in ³ .	623 cm ³
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation Time	1.3 sec.	1.3 sec.
Accuracy	±0.005 in.	±0.13 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate double acting	4-way, 2-p	osition

DDD 62

FROM FARSIDE (8) C'BORE FOR [M10] 3/8 SHCS

(2) PER JAW

[3.500] 88.9



2X 1/8 BSPP AIR PORTS

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW					
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]			
Metric Threads Course Pitch	Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	Metric [mm] $ [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] $			

How to Order: (Order Accessories separately from Basic Moo
--

(4) PER JAW

BASIC MODEL	STROKE	VITON SE	ALS	ROD LOC	
RPR-63 M	- 200 -	NS - V	-S	- R2	
BASIC MODEL METRIC	RPR-63				
STROKE SYNCHRONIZATION	Leave	It factory for addi Blank for Synchro		,	
VITON® SEALS	Leave	emperature Viton®	Seals (
ROD LOCK	S Stainle	ss Steel	,		
	I-LS One Ro	od Lock (Left Side	1	,	
HARDWARE ROD LOCK R1	V High To Leave S Stainle Leave Leave -RS One Ro	One Rod Lock (Left Side)			

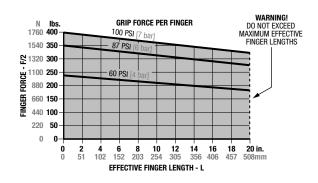
SAMPLE ORDER: RPR-63M-150-NS-V-S-R2 Ex: RPR-63M, Metric Gripper, 150 Stroke, Non Synchronized, Viton® Seals, Stainless Steel, 2 Rod Locks

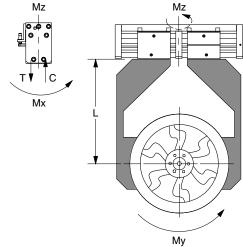
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
12 mm Sensor Mounting Kit (Mounts 2 Inductive sensors)	OSMK-131	1
12 mm Inductive NPN Sensor with Quick Disconnect	OISN-017	1 or 2
12 mm Inductive PNP Sensor with Quick Disconnect	OISP-017	1 or 2
Straight Quick Disconnect Cable (2M cable length)**	CABL-014	1 or 2
Straight Quick Disconnect Cable (5M cable length)**	CABL-018	1 or 2
Analog Sensor	0ISA-001	1
Analog Sensor cable with Quick Disconnect (5M cable length)	CABL-045	1
Analog sensor Mounting Kit	OSMK-132	1
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Fail Safe Valve 1/4 NPT (Imperial)	OFSV-003	1
Fail Safe Valve 1/4 BSPP (Metric)	OFSV-006	1
Plumbing Adapter 1/4 BSPP Male to 1/4 NPT Female	PLFT-024	1 or 2
Buna-N Seal Repair Kit	SLKT-452	1
Viton Seal Repair Kit	SLKT-453	1
**Sensor and cable sold separately		

PARALLEL GRIPPER RPR **GLADIATOR SERIES**

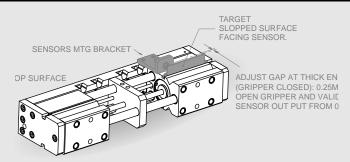
Loading Capacity:

Maximum Tensile T	3500 lbs. [15570 N]
Maximum Compressive C	3500 lbs. [15570 N]
Maximum Moment M _X	7500 inlbs. [825 Nm]
Maximum Moment My	9000 lbs. [990 N]
Maximum Moment Mz	7500 inlbs. [825 Nm]
Maximum Effective Finger Length L	20 in. [500mm]



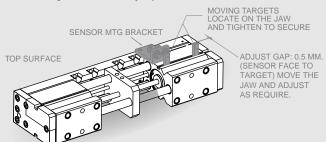


Accessory Mounting Technical Data





- · Used in applications where jaw position information is required along
- Sensor is mounted on a stationary bracket and the target is mounted on the moving jaw. The target has 'slopped' surface facing the sensor. Thus when the target moves with the Jaw, it creates varying air gap between the slopped surface and the sensor
- The sensor is supplied with 24 vdc and generates 0~10 vdc signal as a function of the air gap, as described earlier. Thus the sensor outputs 0~10 vdc signal as a function of jaw position



Inductive Sensor: Gripper Open/Close

- Used in applications where jaw open and closed positions must be detected as process requirements
- PNP and NPN inductive sensors are available
- The two inductive sensors are stationary and mounted with a bracket directly to the back plate
- . The target is mounted on the moving jaw
- The sensor cable has quick disconect connector at the sensor end and open pig tail wires at the otherend. Cable available in two lengths 2M & 5M
- Adjustments required after assembly:
- Air gap between sensor face and moving target to 0.5 mm and fine adjust as required. Tighten the lock nuts on the sensors to avoid loosensing under application.
- Location of the moving target on the jaw to suit stroke

Rod Lock (Fail Safe Valve)

GRIPER OPEN PORT

GRIPER CLOSE PORT-

· Used in applications where the part being gripped not be dropped if the air pressure is lost

ROD LOCK-RHS

- · Mounts directly to the jaw. (Must use Jaw with Rod lock option)
- Available options:

LHS Rod Lock

ROD LOCK-LHS (Air Port-G 1/8)

RHS Rod Lock

Two Rod locks. (As shown)

- . Holding force: 1400 N (318 Lbf) max per rod lok.
- Note: If holding forces are exeeded, slippage may occur.
- · Rod lock 'clamp time' when air loss:

250 ms..... ref

Will greatly depend upon flow coefficient of air exhaust line. (Line I.D., Length, Qty & Type of bends, other air circuit elements like valve, mufflers ..., and as apply)

Air port: G 1/8

Note: Must be connected to fully exhaused line when air pressure is lost

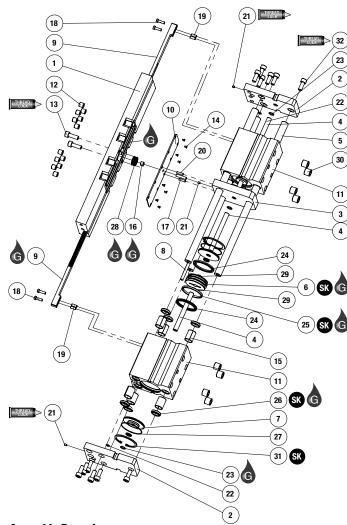
Air specifications:

Air Supply pressure: 10 bar (147 psig) max. Minimum release pressure: 3 bars (44.1 psig)

Air quality:

Filteration: 40 micron, min. Non Lubricated, dry air.





Assembly Procedure:

A. Standard - Synchronous Gripper

- Lubricate and install O-rings in the two end blocks and in the middle block. Install set screws (air plug, Item 21) into the two end blocks and the middle block.
- Assemble RHS and LHS Jaws E-Z locks, bushings, o-rings and piston assembly
- Assemble RHS jaw assembly to the three guide shafts. Assemble RHS end block to the guide shafts.
- Assemble the mid block and assemble RHS piston tubes and RHS cross tubes.
- 5) Assemble the LHS jaw to the three guide shafts. Install the piston tubes and the Cross tubes as described earlier. Install LHS end block and install it's fasteners, 'snug tight' to the three guide rods. Verify that the two jaws can traverse along the guide bars without any binding.
- 6) Install the cover to the middle block by locating it with the dowel pins above. Install the racks to the jaws by first locating with the dowel pins and then with fasteners. Lubricate the needle bearing, install it into the pinion and install this assembly to the middle dowel pin.
- 7) Lubricate the racks, the pinion and inside of the grooves of the back plate. Locate the back plate between the two end blocks and carefully engage it to the three dowel pin, protruding out of the middle block. Install the fasteners and snug tight to secure the back plate to the middle plate and to the end blocks. Install fastensers for the cover and tighten them.

Item	Qty	Name
01	1	Base Plate
21	2	End Block
03	1	Mid Block
04	4	Piston Tube
05	3	Guide Shaft
06	2	Piston
07	4	Cap
08	2	Cross Tube
09*	2	Rack
10	1	Cover
11*	2	Jaw
12	12	EZ-Lock Insert- Back Plate
13	2	Base Plate MTG Screws
14	8	Cover MTG Screws
15	12	Composite BushingS
16*	1	Needle Bearing
17*	1	Needle Bearing MTG Dowel
18	4	Rack MTG Screw
19*	4	Rack MTG Dowel
20	2	Cover MTG DoweL
21	3	Air Passage Plug - Set Screw
22	4	Cross Tube 0-Ring
23	4	Piston Tube O-Ring
24	4	U-Cup Piston
25	2	Wear Band
26	12	Shaft Wiper
27	4	Cap O-Ring
28*	1	Pinion
29	4	Piston Tube O-Ring- Inner
30	8	EZ-Lock Insert- Jaws
31*	4	Cap Retaining Ring
32	12	End Block MTG Screw

*Notes:

- Contact De-Sta-Co Sales Department for complete spare parts list with order number and process.
- Item # 31 will be different between Imperial and Metric grippers.
 All other features will remain same.
- Item numbers #9, #16, #17, # 19, and #28, are for Synchronous gripper only.
- 4) Item # 11 will be different for gripper with Rod lock options.
- 5) For High Temperature option, all O-rings will be of viton material.
- 6) For Corrosion resistant option, all fasteners will be stainless steel.

Note: Customer to plumb the rod lock valves to his safety circuit.

- 8) Assembly validation and torque the fastener
 - A) Torque all the fasteners to their specification.
 - B) Connect 40 psig air to the gripper ports. Cycle the gripper open/close and verify that the jaw motions are smooth, free of binding, noise and without air leak.
 - C) Increase air pressure to 100 psig. Cycle the gripper open/close and verify that the jaw motions are smooth, free of binding, noise and wituout air leak.

B. Standard - Non Synchronous Gripper

For Non-Synchronous gripper, DO NOT install items #9, #16, #17, #19 and #28.

C. Gripper with ROD LOCK option

Note: Gripper with Rod Lock option will use different item #11 and will use Rod lock valve.

- A) Assemble the jaws to the guide shafts with Rod Lock.
- B) All other steps, as above.









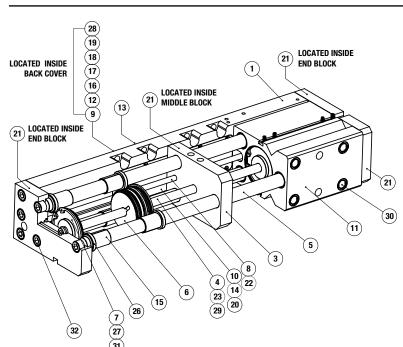


Based





RPR SERIES ASSEMBLED VIEW



Item	Qty	Name	
01	1	Base Plate	
21	2	End Block	
03	1	Mid Block	
04	4	Piston Tube	
05	3	Guide Shaft	
06	2	Piston	
07	4	Cap	
80	2	Cross Tube	
09*	2	Rack	
10	1	Cover	
11*	2	Jaw	
12	12	EZ-Lock Insert- Back Plate	
13	2	Base Plate MTG Screws	
14	8	Cover MTG Screws	
15	12	Composite BushingS	
16*	1	Needle Bearing	
17*	1	Needle Bearing MTG Dowel	
18	4	Rack MTG Screw	
19*	4	Rack MTG Dowel	
20	2	Cover MTG DoweL	
21	3	Air Passage Plug - Set Screw	
22	4	Cross Tube O-Ring	
23	4	Piston Tube 0-Ring	
24	4	U-Cup Piston	
25	2	Wear Band	
26	12	Shaft Wiper	
27	4	Cap O-Ring	
28*	1	Pinion	
29	4	Piston Tube O-Ring- Inner	
30*	8	EZ-Lock Insert- Jaws	
31	4	Cap Retaining Ring	
32	12	End Block MTG Screw	

*Notes:

- 1) Contact De-Sta-Co Sales Department for complete spare parts list with order number and prices.
- 2) For Synchronous gripper Items #9, #16, #17, #19 & #28 are installed in back plate.
- 3) For Metric gripper, item# 30 will be with metric threads. Other features remain same as in Imperial version.
- 4) For High Temperature option all O-rings will be of Viton material.
- 5) For Corrosion environment, all fasteners will be of stainless steel material.
- 6) For Rod-lock option item # 11 will be intrgrated with Rod-lock unit.

Note: Customer to provide and plumb their pneumatic safety circuitry to vent Rod-lock unit in case of air loss.

"B-Series" Industrial Parallel



BPW - WIDE BODY SERIES

The BPW Parallel Gripper feature a wide body design ideal for handling large and wide parts using long fingers. The jaws are supported through the full length of the body for high moment carrying capacity and are sealed against chips or particles, which makes it ideal for use in machining or foundry applications.

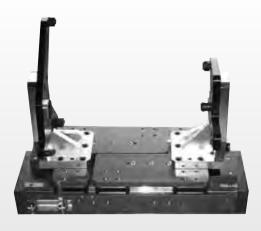
- For Large and Wide Parts
- High Grip Forces and Moment Loads
- Support for Long Fingers
- Non-synchronous Option
- Optional Spring Close (BPW-1600 only)



BRP - HEAVY DUTY SERIES

The BRP Parallel Gripper are heavy duty and rugged for reliable operation in real life industrial operations. Sealed jaws protect the internal mechanism from chips and coolant in machining applications. Hardened tool steel jaws and supports allow for long tooling fingers and high moments and forces.

- Rugged Design
- High Grip Forces and Moment Loads
- Support for Long Fingers
- Optional Spring Open or Close



BPG - LONG STROKE SERIES

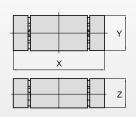
The BPG Parallel Gripper feature a long stroke and low profile and they are often used to handle different size parts with the same fingers. The jaws and supports are made of hardened tool steel and the body is made of lightweight, hard anodized aluminum.

- Accommodate Multiple Part Sizes with same Fingers
- Long Strokes
- Optional Spring Open or Close
- Low Profile Design

Grippers



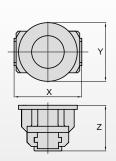




Model #	Stroke	Grip Force	Weight	X	Υ	Z
	6.3 in [160 mm]	970 lbs [3868 N]	88 lbs [40 kg]	17.9 in [454 mm]	7.1 in [180 mm]	5.9 in [150 mm]
	7.8 in [200 mm]	1920 lbs [8536 N]	154 lbs [70 kg]	27 in [694 mm]	8.0 in [203 mm]	6.9 in [174 mm]

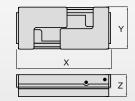






Model #	Stroke	Grip Force	Weight	X	Υ	Z
BRP-20	1.5 in [38 mm]	1618 lbs [7200 N]	40.3 lbs [18.3 kg]	8.19 in [208 mm]	7.87 in [200 mm]	6.16 in [157 mm]
BRP-21	1.5 in [38 mm]	3462 lbs [15400 N]	81.6 lbs [37 kg]	12.13 in [308 mm]	10.63 in [270 mm]	6.69 in [170 mm]
BRP-21-D	2.5 in [64 mm]	2001 lbs [8900 N]	81.6 lbs [37 kg]	12.13 in [308 mm]	10.63 in [270 mm]	6.69 in [170 mm]





For Applications Support or More Info

Contact Us at: cs-automation@destaco.com

or Call Us at: **1.888.DESTACO**

Model #	Stroke	Grip Force	Weight	X	Υ	Z
BPG-160	4.06 in [160 mm]	1787lbs [7950 N]	126 lbs [57 kg]	23.78 in [604 mm]	10.63 in [270 mm]	5.51 in [140 mm]

Parallel Grippers **3-Jaw Centerin**

Machining applications:

The 3 concentric jaws and excellent repeatability make it easier to accurately load and unload round parts.

• Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism. Viton® seals are standard.

· Compact, robust and powerful gripper

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Different strokes:

All gripper sizes are available in 2 stroke sizes.

For long fingers applications:

The large surface area of the jaws coupled with the encapsulated bottom case design allows for long finger designs.

Multipurpose gripper:

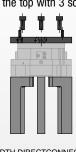
A wide range of options & accessories (extended stroke, safety springs for internal or external gripping, magneto resistive or inductive sensors, stripper plate) allow these grippers to be used in a wide number of applications.



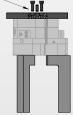
Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located using two dowel pins and assembled from the top with 3 screws.

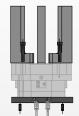


-DTH DIRECTCONNECT MOUNTING



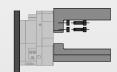
Body mounts with 4 screws and locates with 2 slip fit dowel pins for accuracy

The gripper can also be assembled from the bottom with 3 through body screws.



Gripper is protected from debris when operated upside down.

Gripper can be operated utilizing top manifold air ports.



Fingers are located on jaws with 2 dowel sleeves (provided) and assembled with 2 screws.

Technical Specifications:

Pneumatic Specifications

Pressure Operating Range without Springs

30-100 psi Cylinder Type

Double Acting or Double Acting Spring Assist or Single Acting Spring Return **Internally Lubricated Viton®**

Metric

2-7 bar

Imperial

Dynamic Seals Valve Required to Operate:

Double Acting 4-way, 2-position Single Acting (-C or -O Option) 3-way, 2-position

Air Quality Requirements

Air Filtration 40 Micron or Better Air Lubrication Not Necessary* Air Humidity **Low Moisture Content (dry)**

Temperature Operating Range

Buna-N Seals (Standard) -30°~180° F -35°~80° C -30°~150° C Viton® Seals (Optional) -20°~300° F

Maintenance Specifications[†]

Expected Life

Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

*Addition of lubrication will greatly increase service life

See Maintenance Section

0.32 in. 8 mm 130 lbs 579 N 0.6 lbs 0.25 Kg





Style -RTH/DTH Parallel Gripper

Size -1M

Grip Force: Weight:

RTH/DTH-1M RTH/DTH-1M-L Total Stroke: 0.16 in. 4 mm 200 lbs 889 N 0.6 lbs 0.25 Kg

Style -RTH/DTH Parallel Gripper



-2M RTH/DTH-2M RTH/DTH-2M-L 0.24 in. 6 mm 0.47 in. 12 mm Grip Force: 335 lbs 1490 N 220 lbs 979 N 1.2 lbs 0.53 Kg Weight: 1.2 lbs 0.53 Kg

Style -RTH/DTH Parallel Gripper



Standard Purge/

Scavenge Port

Used with a vacuum for clean

room environments or positive

pressure for harsh environments

-3M RTH/DTH-3M RTH/DTH-3M-L Total Stroke: 0.31 in. 8 mm 0.63 in. 16 mm Grip Force: 591 lbs 2627 N 384 lbs 1708 N 2.4 lbs 1.08 Kg 2.4 lbs 1.08 Kg Weiaht:

Style -RTH/DTH Parallel Gripper



Size

-4M RTH/DTH-4M RTH/DTH-4M-L Total Stroke: 0.39 in. 10 mm 0.79 in. 20 mm Grip Force: 1026 lbs 4562 N 667 lbs 667 N 4.3 lbs 1.95 Kg 4.3 lbs 1.95 Ka Weight:

Style -RTH/DTH Parallel Gripper



-5M RTH/DTH-5M RTH/DTH-5M-L Total Stroke: 0.51 in. 13 mm 1.02 in. 26 mm Grip Force: 1771 lbs 7877 N 1152 lbs 5124 N 8.6 lbs 3.9 Kg Weight: 8.6 lbs 3.9 Ka

See **1.240**

Style -RTH Parallel Gripper



-6M RTH-6M RTH-6M-L Total Stroke: 0.63 in. 16 mm 1.26 in. 32 mm 3099 lbs 13786 N 2017 lbs 8971 N Grip Force: 17.4 lbs 7.9 Kg 17.4 lbs 7.9 Kg Weight:

See **1.242**

Style -RTH Parallel Gripper



-7M RTH-7M RTH-M-L Total Stroke: 0.98 in. 25 mm 1.97 in. 50 mm Grip Force: 4967 lbs 22093 N 3222 lbs 14322 N Weight: 34.6 lbs 15.7 Kg 34.6 lbs 15.7 Kg

See **1.244**

Style -RTH Parallel Gripper



Size

-8M RTH-8M RTH-8M-L Total Stroke: 1.38 in. 35 mm 2.76 in. 70 mm 9971 lbs 44354 N 6450 lbs 28690 N Weight: 96.8 lbs 43.9 Kg 96.8 lbs 43.9 Kg

See **1.246**

Product Features Multiple Mounting Viton® Seals (-V) Option Optional Viton® seals for high temperatures (-20°F to +300°F / -30°~150° C) **Locations** Standard and Gripper can be mounted **Extended Stroke (-L)** from the top or bottom Each model of gripper is **Finger Locating** available in two stroke lengths Shielded **Sleeves** For precise finger Design mounting (standard) Gripper body is shielded to repel chips and other particulate from internal Jaw **Components** drive mechanism Hardened and precision ground steel for minimum Multiple jaw play with Sensing hard plating for wear resistance **Capabilities** and long life Up to 3 magneto resistive sensors (magnets built-in) or inductive Multiple sensors available **Air Ports** [except -1M, -2M, -3M] Side or top air ports (top ports

Operating Principle

DIRECTCONNECT

Mounting Patterns

DIRECTCONNECT™ tapped

& dowel mounting surface

available on DTH version

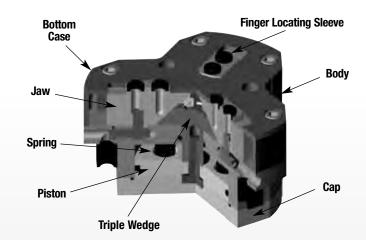
[except -6M, 7M, 8M]

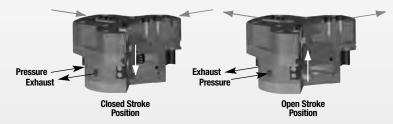
require O-ring)

Optional Spring Assist

Optional spring assist retains the component should the air supply fail, to assist the gripper for internal (-0) or external (-0) gripping, or

in single acting or spring assist mode

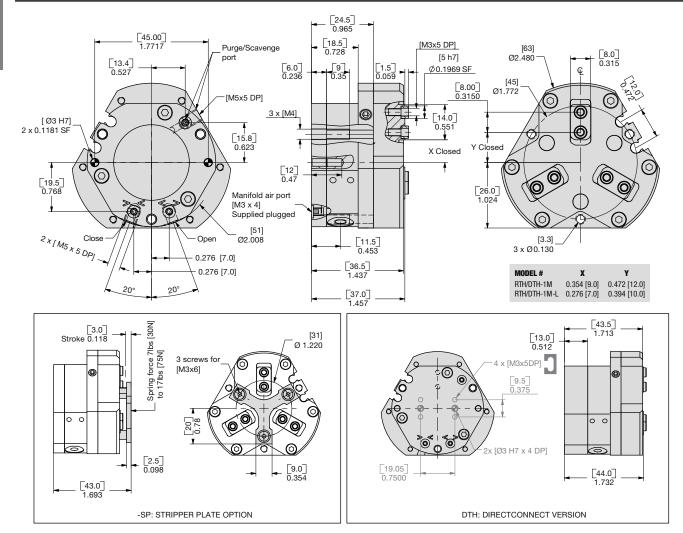


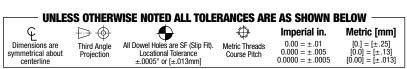


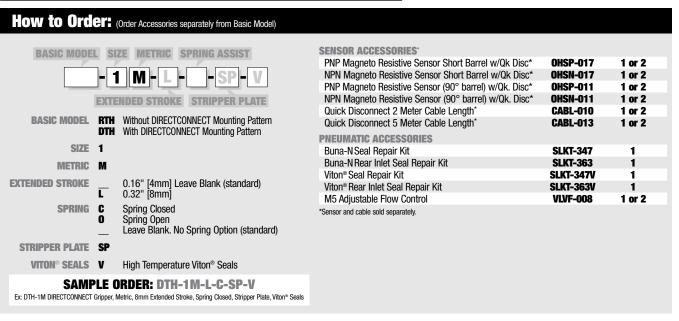
- A double acting piston is connected to a triple sided wedge.
- The triple wedge slides in a slot in each of the jaws converting the vertical motion of the wedge into a horizontal motion of the jaws.
- Each jaw moves within the slots. The design of the bottom case increases the rigidity and permits longer fingers. The large surface area of the guiding system permits higher moment loads.
- This gripper is suitable for internal or external gripping using single or double acting mode.

PARALLEL GRIPPER RTH/DTH-1M 3-JAW CENTERING SERIES





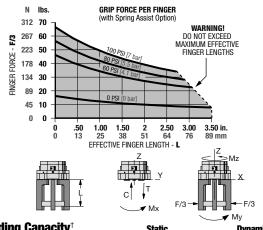






PARALLEL GRIPPER RTH/DTH-1M 3-JAW CENTERING SERIES

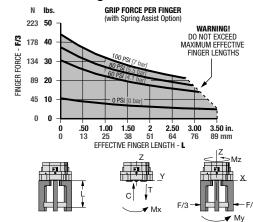
RTH/DTH-1M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	182 lbs. [810 N]	20 lbs. [89 N]
Maximum Compressive C	238 lbs. [1060 N]	20 lbs. [89 N]
Maximum Moment M _X	195 inlbs. [22 Nm]	18 inlbs. [2 Nm]
Maximum Moment My	248 inlbs. [28 Nm]	27 inlbs. [3 Nm]
Maximum Moment Mz	159 inlbs. [18 Nm]	27 inlbs. [3 Nm]

†Capacities are per set of jaws and are not simultaneous

RTH/DTH-1M-L Loading Information



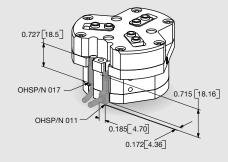
Static	Dynamic
164 lbs. [730 N]	13 lbs. [57 N]
216 lbs. [960 N]	13 lbs. [57 N]
177 inlbs. [20 Nm]	9 inlbs. [1 Nm]
204 inlbs. [23 Nm]	9 inIbs. [1 Nm]
133 inlbs. [15 Nm]	9 inlbs. [1 Nm]
	164 lbs. [730 N] 216 lbs. [960 N] 177 inlbs. [20 Nm] 204 inlbs. [23 Nm]

†Capacities are per set of jaws and are not simultaneous

153 lbs.	682 N
100 lbs.	443 N
200 lbs.	889 N
130 lbs.	579 N
0.16 in.	4 mm
0.32 in.	8 mm
0.6 lbs.	0.25 Kg
30-100 psi	2-7 Bar
60-100 psi	4-7 Bar
	0.32 in. 0.6 lbs.

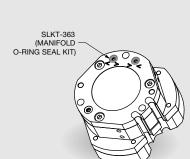
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	1.62 in.	32 mm
Displacement	0.40 in ³ .	6.5 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.06 sec.	/0.06 sec.
Accuracy	±0.002 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting		2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



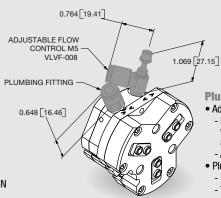
Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold 0-Ring seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-363V)



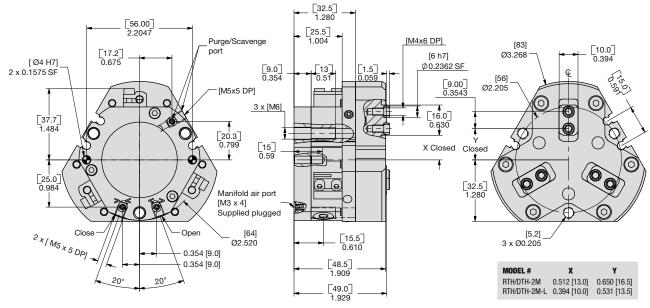
Plumbing Fittings

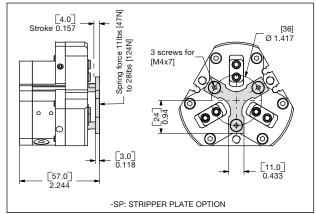
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

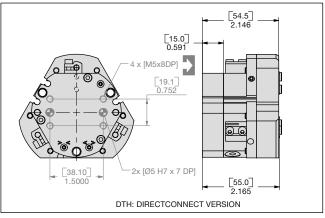
DIRECTCONNECT

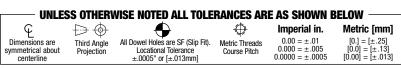
PARALLEL GRIPPER RTH/DTH-2M 3-JAW CENTERING SERIES

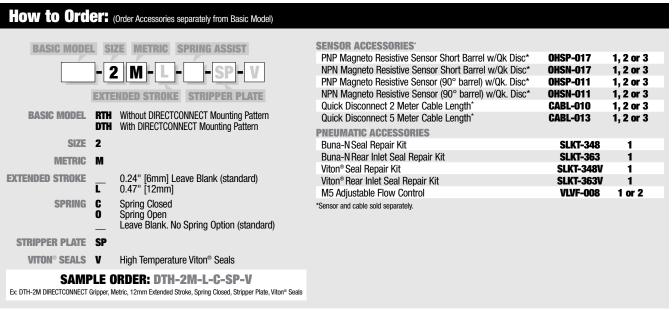






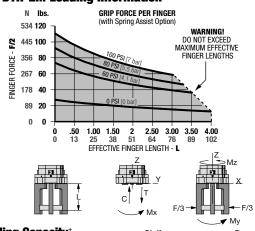






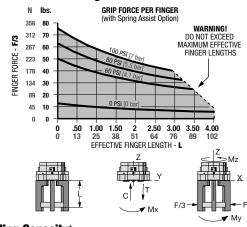
DIRECTONI

RTH/DTH-2M Loading Information



†Capacities are per set of jaws and are not simultaneous

RTH/DTH-2M-L Loading Information



PARALLEL GRIPPER RTH/DTH-2M

3-JAW CENTERING SERIES

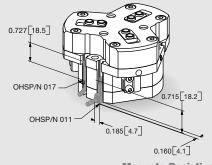
Loading Capacity	Static	Dynamic
Maximum Tensile T	243 lbs. [1080 N]	19 lbs. [84 N]
Maximum Compressive C	315 lbs. [1400 N]	19 lbs. [84 N]
Maximum Moment M _X	354 inlbs. [40 Nm]	27 inlbs. [3 Nm]
Maximum Moment My	460 inlbs. [52 Nm]	35 inlbs. [4 Nm]
Maximum Moment Mz	292 inlbs. [33 Nm]	35 inlbs. [4 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	278 lbs.	1238 N
Without Spring Assist -L	183 lbs.	812 N
With Spring Assist	335 lbs.	1490 N
With Spring Assist -L	220 lbs.	979 N
Total Stroke:		
Standard	0.24 in.	6 mm
Extended -L	0.47 in.	12 mm
Weight	1.2 lbs.	0.53 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring		4-7 Bar

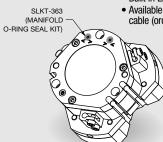
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø		43 mm
Displacement	1.05 in ³ .	17 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.07 sec	:./0.07 sec.
Accuracy	±0.002 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting		2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



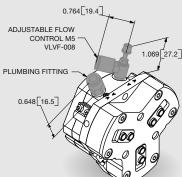
Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- . Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold O-Ring seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-363V)

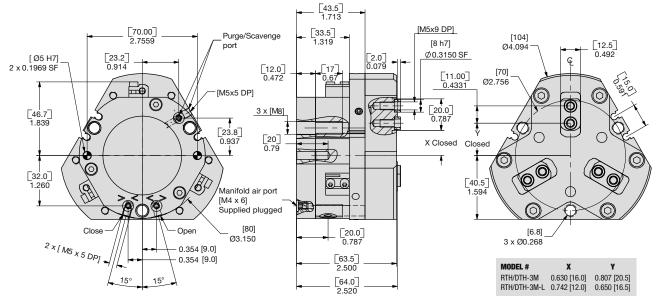


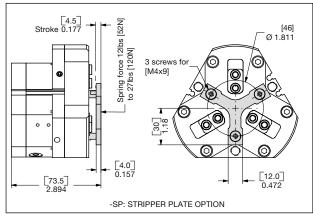
Plumbing Fittings Adjustable flow controls:

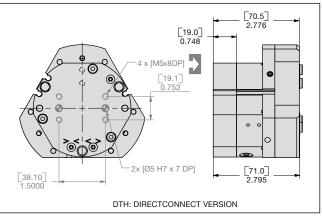
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

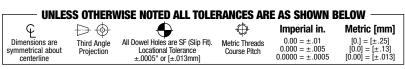
PARALLEL GRIPPER RTH/DTH-3M 3-JAW CENTERING SERIES







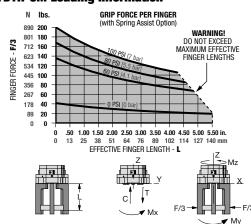




BASIC MODE	L SIZ	NDED STROKE STRIPPER PLATE	SENSOR ACCESSORIES* PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc* Quick Disconnect 2 Meter Cable Length*	OHSP-017 OHSN-017 OHSP-011 OHSN-011 CABL-010	1, 2 or 3 1, 2 or 3 1, 2 or 3 1, 2 or 3 1, 2 or 3
BASIC MODEL	RTH DTH	Without DIRECTCONNECT Mounting Pattern With DIRECTCONNECT Mounting Pattern	Quick Disconnect 5 Meter Cable Length* PNEUMATIC ACCESSORIES	CABL-013	1, 2 or 3
SIZE	3		Buna-N Seal Repair Kit	SLKT-349	1
METRIC	М		Buna-N Rear Inlet Seal Repair Kit	SLKT-364	1
EVERIDED CEDOVE		0.01 [One and I carre Disable (should and)	Viton® Seal Repair Kit	SLKT-349V	1
EXTENDED STROKE	_	0.31" [8mm] Leave Blank (standard) 0.63" [16mm]	Viton® Rear Inlet Seal Repair Kit	SLKT-364V	1
oppilio.	_	• •	M5 Adjustable Flow Control	VLVF-008	1 or 2
SPRING	C 0 —	Spring Closed Spring Open Leave Blank. No Spring Option (standard)	*Sensor and cable sold separately.		
STRIPPER PLATE	SP				
VITON® SEALS	V	High Temperature Viton® Seals			
		PRDER: DTH-3M-L-C-SP-V letric, 16mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals			

RH/OTH SERIES **1.237**

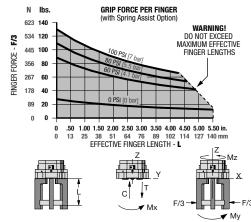
RTH/DTH-3M Loading Information



		<u> </u>
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	378 lbs. [1680 N]	68 lbs. [302 N]
Maximum Compressive C	490 lbs. [2180 N]	68 lbs. [302 N]
Maximum Moment M _X	637 inlbs. [72 Nm]	97 inlbs. [11 Nm]
Maximum Moment My	903 inlbs. [102 Nm]	142 inlbs. [16 Nm]
Maximum Moment Mz	584 inlbs. [66 Nm]	142 inlbs. [16 Nm]

†Capacities are per set of jaws and are not simultaneous

RTH/DTH-3M-L Loading Information



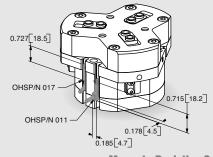
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	337 lbs. [1500 N]	44 lbs. [197 N]
Maximum Compressive C	436 lbs. [1940 N]	44 lbs. [197 N]
Maximum Moment M _X	566 inlbs. [64 Nm]	62 inlbs. [7 Nm]
Maximum Moment My	717 inlbs. [81 Nm]	80 inlbs. [9 Nm]
Maximum Moment Mz	469 inlbs. [53 Nm]	80 inlbs. [9 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	467 lbs.	2078 N
Without Spring Assist -L	303 lbs.	1349 N
With Spring Assist	591 lbs.	2627 N
With Spring Assist -L	384 lbs.	1708 N
Total Stroke:		
Standard	0.31 in.	8 mm
Extended -L	0.63 in.	16 mm
Weight	2.4 lbs.	1.08 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

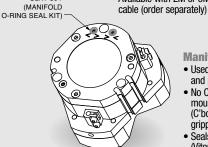
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø		55 mm
Displacement		37 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.08 sec./0.08 sec.	
Accuracy	±0.002 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting		

Accessory Mounting Technical Data



Magneto Resistive Sensors

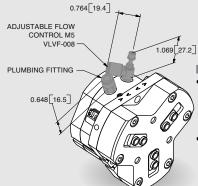
- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating



SLKT-364

Manifold O-Ring seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-364V)

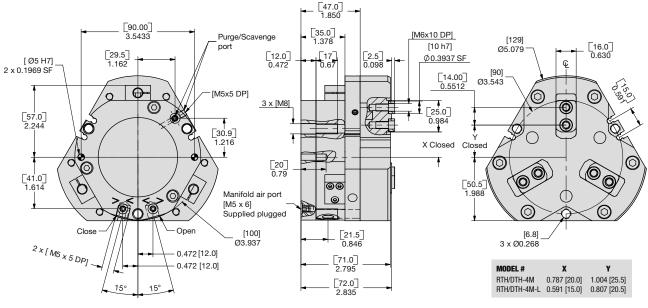


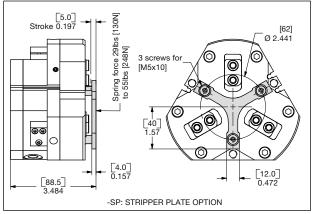
Plumbing Fittings

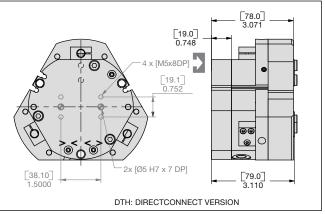
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

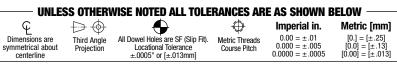
PARALLEL GRIPPER RTH/DTH-4M 3-JAW CENTERING SERIES





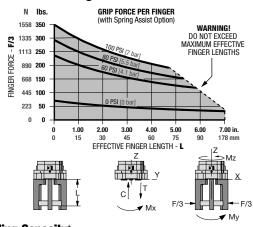






How to Ord	er:	(Order Accessories separately from Basic Model)			
BASIC MODEL SIZE	EXTE	M-L-SP-V ENDED STROKE STRIPPER PLATE Without DIRECTCONNECT Mounting Pattern With DIRECTCONNECT Mounting Pattern	8mm PNP Inductive Sensor w/Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc* Quick Disconnect 2 Meter Cable Length*	OISN-011 OISP-011 OHSP-017 OHSN-017 OHSP-011 DHSN-011 CABL-010 CABL-013	1, 2 or 3 1, 2 or 3
METRIC EXTENDED STROKE SPRING STRIPPER PLATE	M L C O - SP	0.39" [10mm] Leave Blank (standard) 0.79" [20mm] Spring Closed Spring Open Leave Blank. No Spring Option (standard)	PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit G 1/8" Adjustable Flow Control Adapter G 1/8 Male to 1/8 NPT Female *Sensor and cable sold separately.	SLKT-350 SLKT-365 SLKT-350V SLKT-365V VLVF-005 PLFT-025	1 1 1 1 1 or 2 1 or 2
	LE (High Temperature Viton® Seals DRDER: DTH-4M-L-G-SP-V letric, 20mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals			

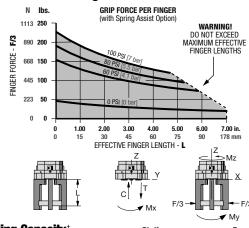
RTH/DTH-4M Loading Information



Loading Capacity [†]	Static	Dynamic	
Maximum Tensile T	474 lbs. [2110 N]	96 lbs. [425 N]	
Maximum Compressive C	627 lbs. [2790 N]	96 lbs. [425 N]	
Maximum Moment M _X	814 inlbs. [92 Nm]	142 inlbs. [16 Nm]	
Maximum Moment My	1133 inlbs. [182 Nm]	195 inlbs. [22 Nm]	
Maximum Moment Mz	734 inlbs. [84 Nm]	195 inlbs. [22 Nm]	

†Capacities are per set of jaws and are not simultaneous

RTH/DTH-4M-L Loading Information



PARALLEL GRIPPER RTH/DTH-4M

3-JAW CENTERING SERIES

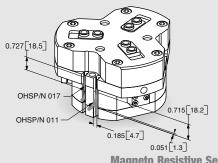
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	423 lbs. [1880 N]	62 lbs. [275 N]
Maximum Compressive C	560 lbs. [2490 N]	62 lbs. [275 N]
Maximum Moment M _X	726 inlbs. [82 Nm]	89 inlbs. [10 Nm]
Maximum Moment My	903 inlbs. [102 Nm]	115 inlbs. [13 Nm]
Maximum Moment Mz	593 inlbs. [67 Nm]	115 inlbs. [13 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications			
Total Rated Grip Force, F @ 100 psi [7 bar]:			
Without Spring Assist	819 lbs.	3644 N	
Without Spring Assist -L	532 lbs.	2366 N	
With Spring Assist	1026 lbs.	4562 N	
With Spring Assist -L	667 lbs.	2967 N	
Total Stroke:			
Standard	0.39 in.	10 mm	
Extended -L	0.79 in.	20 mm	
Weight	4.3 lbs.	1.95 Kg	
Pressure Range without Spring	30-100 psi	2-7 Bar	
Pressure Range with Spring	45-100 psi	3-7 Bar	

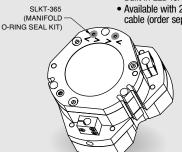
	Specifications (cont.)		
	Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
	Max. Pressure for Purge Port	30 psi	2.1 Bar
	Cylinder Bore Ø	2.85 in.	72 mm
	Displacement	4.90 in ³ .	80 cm ³
	Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)		0.1 sec./0.1 sec.	
	Accuracy	±0.0024 in.	±0.06 mm
	Repeatability	±0.0012 in.	±0.03 mm
	Valve required to actuate single acting		
	Valve required to actuate double acting	4-way, 2-position	

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



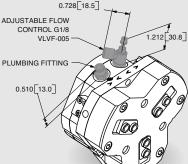
Manifold O-Ring seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)

Sensors holders

Inductive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- Simple adjustment of the target with screw driver · Available with 2M or 5M Quick Disconnect mating cable (order separately)



OISP-011 or

OISN-011

Plumbing Fittings

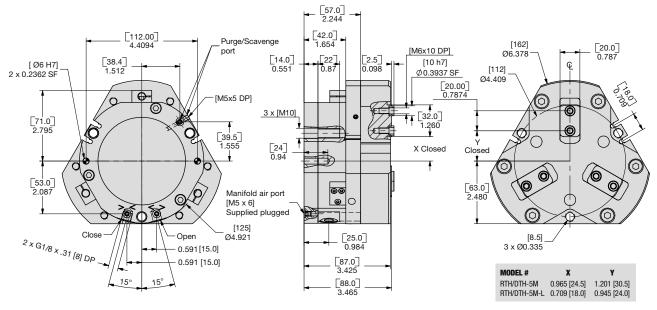
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubing
- Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

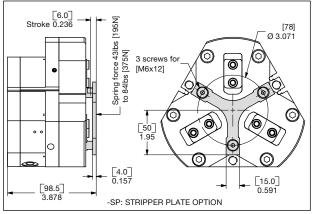


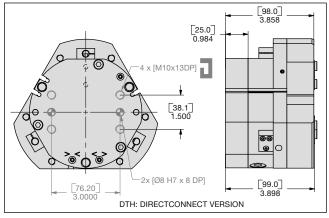
DIRECTCONNECT

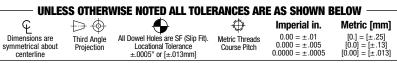
PARALLEL GRIPPER RTH/DTH-5M 3-JAW CENTERING SERIES









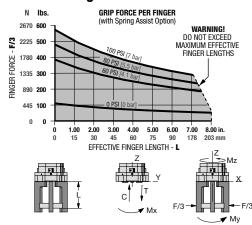


BASIC MODEL SIZE METRIC EXTENDED STROKE SPRING	EXTERTH DTH 5 M	Without DIRECTCONNECT Mounting Pattern With DIRECTCONNECT Mounting Pattern 0.51" [13mm] Leave Blank (standard) 1.02" [26mm] Spring Closed	SENSOR ACCESSORIES' 8mm NPN Inductive Sensor w/Quick Disconnect* 8mm PNP Inductive Sensor w/Quick Disconnect* PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc* NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc* Quick Disconnect 2 Meter Cable Length* Quick Disconnect 5 Meter Cable Length* PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Buna-N Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit	OISN-011 OISP-011 OHSP-017 OHSN-017 OHSP-011 OHSN-011 CABL-010 CABL-013 SLKT-351 SLKT-351 SLKT-365 SLKT-355V	1, 2 or 3 1, 2 or 3
STRIPPER PLATE	0 SP	Spring Open Leave Blank. No Spring Option (standard)	G 1/8" Adjustable Flow Control Adapter G 1/8 Male to 1/8 NPT Female *Sensor and cable sold separately.	VLVF-005 PLFT-025	1 or 2 1 or 2
VITON® SEALS	v	High Temperature Viton® Seals			

MECTON



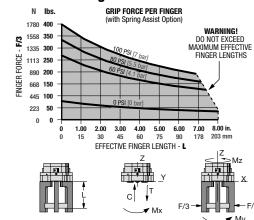
RTH/DTH-5M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	672 lbs. [2990 N]	152 lbs. [674 N]
Maximum Compressive C	895 lbs. [3980 N]	152 lbs. [674 N]
Maximum Moment M _X	1124 inlbs. [127 Nm]	221 inlbs. [25 Nm]
Maximum Moment My	1584 inlbs. [179 Nm]	310 inlbs. [35 Nm]
Maximum Moment Mz	1036 inlbs. [117 Nm]	310 inlbs. [35 Nm]

†Capacities are per set of jaws and are not simultaneous

RTH/DTH-5M-L Loading Information



PARALLEL GRIPPER RTH/DTH-5M

3-JAW CENTERING SERIES

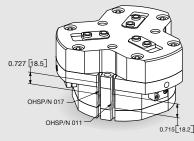
Loading Capacity [™]	Static	Dynamic
Maximum Tensile T	602 lbs. [2680 N]	97 lbs. [432 N]
Maximum Compressive C	803 lbs. [3570 N]	97 lbs. [432 N]
Maximum Moment M _X	1009 inlbs. [114 Nm]	142 inlbs. [16 Nm]
Maximum Moment My	1275 inlbs. [144 Nm]	177 inlbs. [20 Nm]
Maximum Moment Mz	832 inlbs. [94 Nm]	177 inlbs. [20 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications			
Total Rated Grip Force, F @ 100 psi [7 bar]:			
Without Spring Assist	1428 lbs.	6353 N	
Without Spring Assist -L	927 lbs.	4125 N	
With Spring Assist	1771 lbs.	7877 N	
With Spring Assist -L	1152 lbs.	5124 N	
Total Stroke:			
Standard	0.51 in.	13 mm	
Extended -L	1.02 in.	26 mm	
Weight	8.6 lbs.	3.9 Kg	
Pressure Range without Spring	30-100 psi	2-7 Bar	
Pressure Range with Spring	45-100 psi	3-7 Bar	

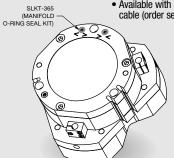
Specifications (cont.) Max. Vacuum for Scavenge Port..... 8 in. Ha 20 mm Hg Max. Pressure for Purge Port..... 2.1 Bar Cylinder Bore Ø..... 3.75 in. 95 mm Displacement 11.0 in³. 180 cm³ Temperature Range -20°~300° F -30°~150° C Actuation (open/close) 0.19 sec./0.19 sec. Accuracy ±0.0024 in. ±0.06 mm Repeatability ±0.0012 in. $\pm 0.03 \; \text{mm}$ Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting 4-way, 2-position

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold O-Ring seals

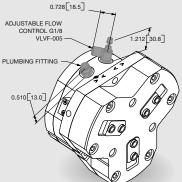
- · Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)

Inductive Sensors

OISP-011 or

- PNP and NPN Magneto Resistive available
- Sensors holders and targets are standard mounted
- Simple adjustment of the target with screw driver · Available with 2M or 5M Quick Disconnect mating

cable (order separately)



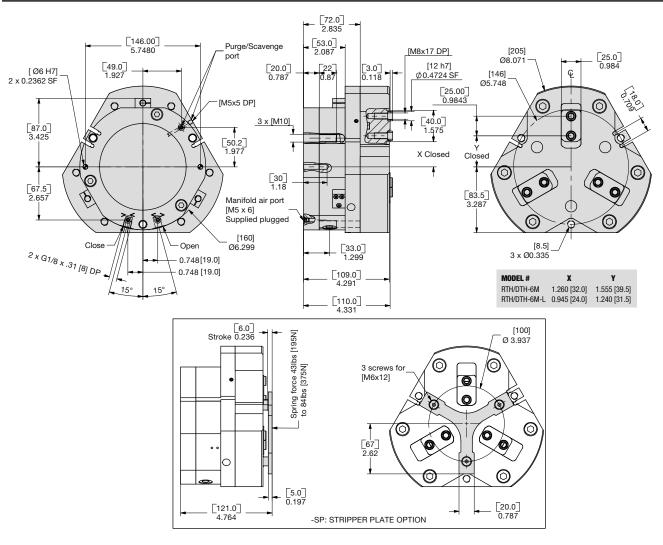
0.48[12]

Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RTH-6M 3-JAW CENTERING SERIES

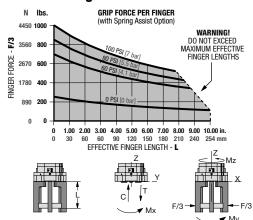




UNLE	SS OTHERV	VISE NOTED ALL TOLE	RANCES AR	E AS SHOWN E	BELOW -
Dimensions are symmetrical about	Third Angle	All Dowel Holes are SF (Slip Fit).	Metric Threads	Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$	Metric [mm] [0.] = [±.25] [0.0] = [±.13]
centerline	Projection	±.0005" or [±.013mm]	Course Pitch	$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$

SIZE 6 METRIC M EXTENDED STROKE O.63" [16mm] Leave Blank (standard) L 1.26" [32mm] SPRING C Spring Closed O Spring Open Leave Blank. No Spring Option (standard) STRIPPER PLATE V High Temperature Viton® Seals Quick Disconnect 2 Meter Cable Length* PNEUMATIC ACCESSORIES Buna-N Seal Repair Kit Viton® Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit Viton® Seal Repair Kit Viton® Rear Inlet Seal Repair Kit
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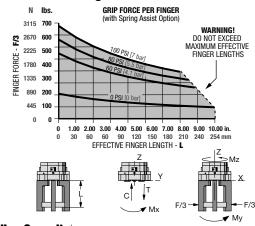
RTH/DTH-6M Loading Information



Static	Dynamic
971 lbs. [4320 N]	296 lbs. [1315 N]
1306 lbs. [5810 N]	296 lbs. [1315 N]
1522 inlbs. [172 Nm]	398 inlbs. [45 Nm]
2213 inlbs. [250 Nm]	575 inlbs. [65 Nm]
1452 inlbs. [164 Nm]	575 inlbs. [65 Nm]
	971 lbs. [4320 N] 1306 lbs. [5810 N] 1522 inlbs. [172 Nm] 2213 inlbs. [250 Nm]

†Capacities are per set of jaws and are not simultaneous

RTH/DTH-6M-L Loading Information



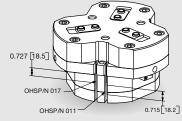
Loading Capacity	Static	Dynamic
Maximum Tensile T	868 lbs. [3860 N]	192 lbs. [852 N]
Maximum Compressive C	1165 lbs. [5180 N]	192 lbs. [852 N]
Maximum Moment M _X	1363 inlbs. [154 Nm]	257 inlbs. [29 Nm]
Maximum Moment My	1761 inlbs. [199 Nm]	327 inlbs. [37 Nm]
Maximum Moment Mz	1159 inlbs. [131 Nm]	327 inlbs. [37 Nm]

†Capacities are per set of jaws and are not simultaneous

opodinoutions		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	2294 lbs.	10202 N
Without Spring Assist -L	1490 lbs.	6629 N
With Spring Assist	3099 lbs.	13786 N
With Spring Assist -L	2017 lbs.	8971 N
Total Stroke:		
Standard	0.63 in.	16 mm
Extended -L	1.26 in.	32 mm
Weight	17.4 lbs.	7.89 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar

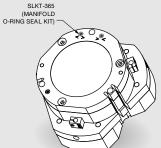
Specifications (cont.) Max. Vacuum for Scavenge Port..... 8 in. Ha 20 mm Hg 30 psi Max. Pressure for Purge Port..... 2.1 Bar Cylinder Bore Ø..... 120 mm 4.72 in. Displacement 22 in³. 355 cm³ Temperature Range -20°~300° F -30°~150° C Actuation (open/close) 0.36 sec./0.36 sec. ±0.08 mm Accuracy ±0.0032 in. Repeatability ±0.002 in. ±0.04 mm Valve required to actuate single acting..... 3-way, 2-position Valve required to actuate double acting 4-way, 2-position

Pressure Range with Spring...... 55-100 psi **Mounting Technical Data**



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold 0-Ring seals

4-7 Bar

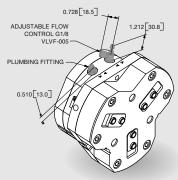
- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)

Inductive Sensors

OISP-011 or

- PNP and NPN Magneto Resistive available
- Sensors holders and targets are standard mounted
- Simple adjustment of the target with screw driver · Available with 2M or 5M Quick Disconnect mating

cable (order separately)



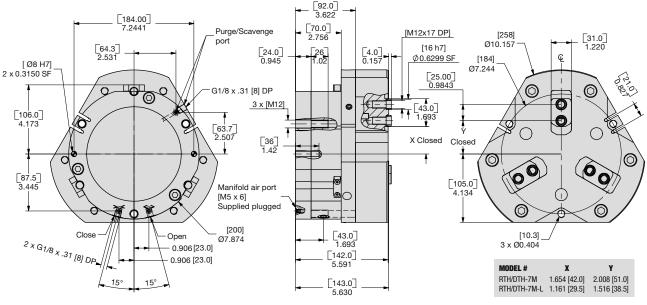
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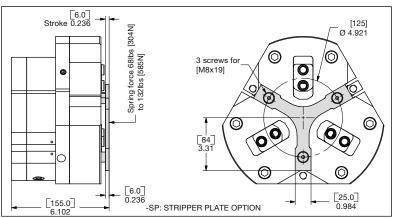
Plumbing Fittings

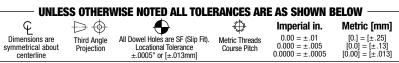
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
 - For side air port location
 - Top air port are plugged as standard

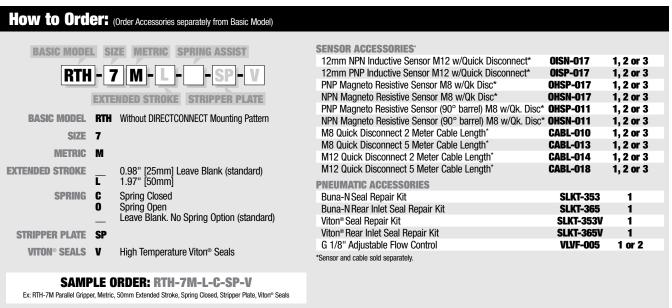
PARALLEL GRIPPER RTH-7M 3-JAW CENTERING SERIES







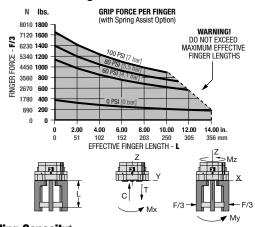






PARALLEL GRIPPER RTH-7M 3-JAW CENTERING SERIES

RTH/DTH-7M Loading Information

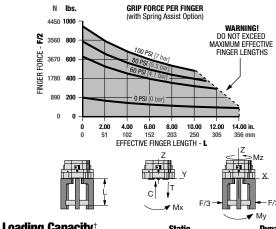


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	1214 lbs. [5400 N]	396 lbs. [1763 N]
Maximum Compressive C	1601 lbs. [7120 N]	396 lbs. [1763 N]
Maximum Moment M _X	1903 inlbs. [215 Nm]	531 inlbs. [60 Nm]
Maximum Moment My	2699 inlbs. [305 Nm]	761 inlbs. [86 Nm]
Maximum Moment Mz	1841 inlbs. [208 Nm]	761 inlbs. [86 Nm]

†Capacities are per set of jaws and are not simultaneous

Pressure Range with Spring...

RTH/DTH-7M-L Loading Information



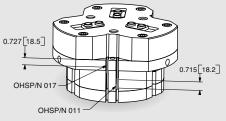
Loading Gapacity	Static	Dynamic
Maximum Tensile T	1054 lbs. [4690 N]	257 lbs. [1141 N]
Maximum Compressive C	1389 lbs. [6180 N]	257 lbs. [1141 N]
Maximum Moment M _X	1646 inlbs. [186 Nm]	345 inlbs. [39 Nm]
Maximum Moment My	2036 inlbs. [230 Nm]	425 inlbs. [48 Nm]
Maximum Moment Mz	1381 inlbs. [156 Nm]	425 inlbs. [48 Nm]
+0	aimultanaaua	

†Capacities are per set of jaws and are not simultaneous

Specifications			
Total Rated Grip Force, F @ 100 psi [7 bar]:			
Without Spring Assist	3859 lbs.	17165 N	
Without Spring Assist -L	2496 lbs.	11102 N	
With Spring Assist	4967 lbs.	22093 N	
With Spring Assist -L	3222 lbs.	14322 N	
Total Stroke:			
Standard	0.98 in.	25 mm	
Extended -L	1.97 in.	50 mm	
Weight	34.6 lbs.	15.7 Kg	
Pressure Range without Spring	30-100 psi	2-7 Bar	

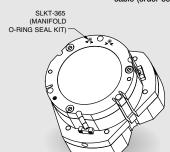
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	6.15 in.	156 mm
Displacement	37 in ³ .	940 cm ³
Temperature Range	-20°~300° F	
Actuation (open/close)		/0.85 sec.
Accuracy	±0.004 in.	±0.1 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate single acting		2-position
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold O-Ring seals

55-100 psi

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- · Seals in manifold kit are Buna-N (Viton® seal kit SLKT-365V)

OISP-017 or

Inductive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- Simple adjustment of the target with screw driver · Available with 2M or 5M Quick Disconnect mating cable (order separately)

Sensors holders are standard

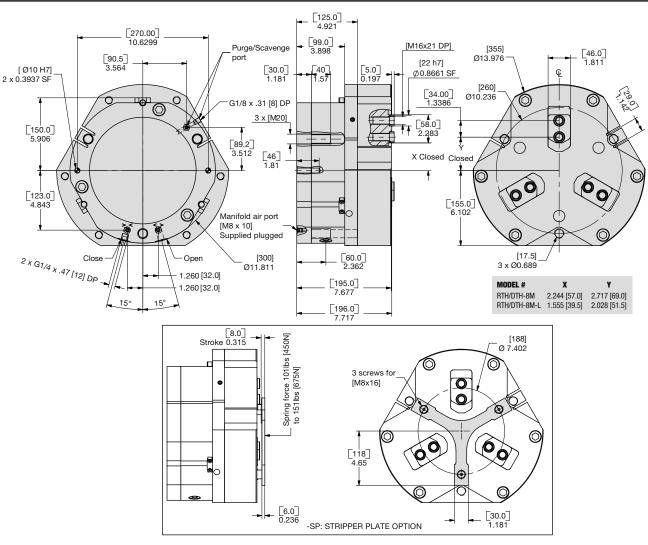
0.728[18.5] ADJUSTABLE FLOW 1.212 30.8 CONTROL G1/8 VLVF-005 PLUMBING FITTING 0.510 13.0

Plumbing Fittings

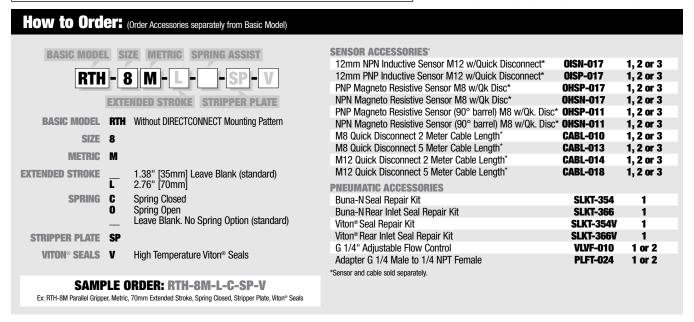
- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
- For side air port location
- Top air port are plugged as standard

PARALLEL GRIPPER RTH-8M 3-JAW CENTERING SERIES

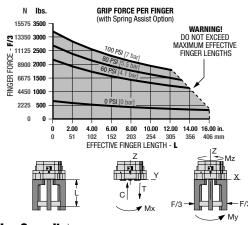




UNLES	SS OTHERV	VISE NOTED ALL TOLE	RANCES AR	E AS SHOWN E	BELOW
Q	$\Rightarrow \phi$	•	\bigoplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

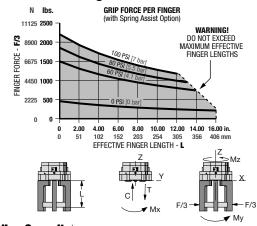


RTH/DTH-8M Loading Information



Loading Capacity [†]	Static	Dynamic		
Maximum Tensile T	1850 lbs. [8230 N]	614 lbs. [2733 N]		
Maximum Compressive C	2405 lbs. [10700 N]	614 lbs. [2733 N]		
Maximum Moment M _X	4027 inlbs. [455 Nm]	1159 inlbs. [131 Nm]		
Maximum Moment My	5116 inlbs. [578 Nm]	1478 inlbs. [167 Nm]		
Maximum Moment Mz	3204 inlbs. [362 Nm]	1478 inlbs. [167 Nm]		
†Capacities are per set of jaws and are not simultaneous				

RTH/DTH-8M-L Loading Information



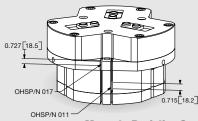
Loading Capacity	Static	Dynamic
Maximum Tensile T	1592 lbs. [7080 N]	398 lbs. [1772 N]
Maximum Compressive C	2070 lbs. [9210 N]	398 lbs. [1772 N]
Maximum Moment M _X	3461 inlbs. [391 Nm]	752 inlbs. [85 Nm]
Maximum Moment My	3788 inlbs. [428 Nm]	823 inlbs. [93 Nm]
Maximum Moment Mz	2372 inlbs. [268 Nm]	823 inlbs. [93 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications		
Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	7933 lbs.	35288 N
Without Spring Assist -L	5122 lbs.	22784 N
With Spring Assist	9971 lbs.	44354 N
With Spring Assist -L	6450 lbs.	28690 N
Total Stroke:		
Standard	1.38 in.	35 mm
Extended -L	2.76 in.	70 mm
Weight	96.8 lbs.	43.9 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

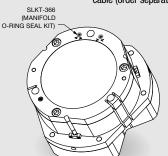
Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	8.86 in.	225 mm
Displacement	166 in ³ .	2720 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	1.7 sec./	
Accuracy	±0.004 in.	±0.01 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2	2-position

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- · Built in LED for ease of positioning and troubleshooting
- · Available with 2M or 5M Quick Disconnect mating cable (order separately)



Manifold O-Ring seals

- Used to seal top air ports and purge/scavenge port
- No C'bore holes in customer's mounting plate required (C'bore are machined in the gripper's body)
- · Seals in manifold kit are Buna-N (Viton® seal kit SLKT-366V)

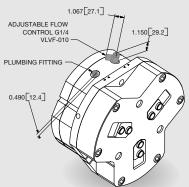
0 0

Inductive Sensors

are standard

OISN-017

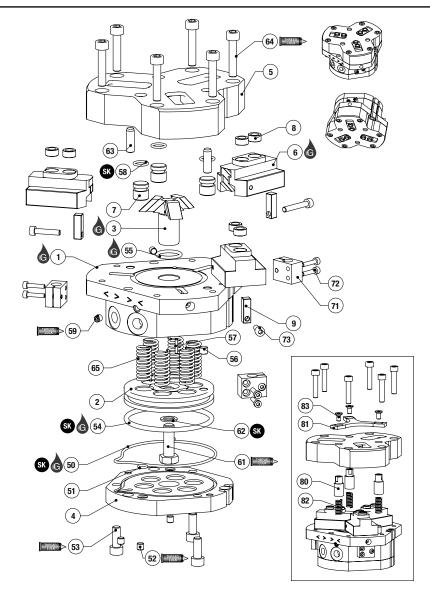
- PNP and NPN Magneto Resistive available
- · Sensors holders and targets are standard mounted
- Simple adjustment of the target with screw driver · Available with 2M or 5M Quick Disconnect mating cable (order separately)



Plumbing Fittings

- Adjustable flow controls:
- Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm OD tubing
- · Plumbing fittings:
- For side air port location
- Top air port are plugged as standard







NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



Assembly Procedure

- 1) Lubricate and install seals #55 into the body #1
- 2) Install #59 SS screws with thread locker into the body #1
- 3) Sub assemble the sensing nuts #9 into the jaws #6
- 4) Sub assemble the jaws #6 on either side of the triple wedge #3 with lubrication
- 5) Insert the jaws and triple wedge sub assembly into the body. To ensure a good positioning of the magnet, the dowel hole of the triple wedge (on tapped hole side) has to be positioned on the opposite side of the air ports (except size 1). For size 1, it has to be positioned between the sensor slots of the body.
- 6) Install seals #58 into the plugs #7
- 7) Insert the plugs #7 into the bottom case #5
- 8) Install bottom case #5 with pressed-in pins

- #63 onto the body and fasten with #64 screws with thread locker
- 9) Lubricate and install seals #54 into the piston #2
- 10) Mount magnet #56 to piston #2 with thread locker
- 11) For **-C** option, insert the spring #65 into the body counterbore holes
- 12) Insert the piston #2 with pressed-in pin #57 onto the triple wedge#3 and fasten with screw #61 and washer #62. Face mount the piston counterbore holes to

the body counterbore holes for **-C** option. Opposite mount for **-O** option.

For **-0** option, insert the spring #65 into the piston counterbore holes

- 14) Install #52 air ports plugs with thread locker onto the cap #4
- 15) Install seals #50 and #51 into the cap #4
- 16) Insert the cap into the body and locate it using cap dowel pin holes.

- 17) Fasten the cap with #53 screws with thread locker
- 18) Install the sensor holder #71 onto the body and fasten with screw #72
- 19) Insert screw #73 into the sensing nuts #9 from the body holes
- 20) Insert locating sleeves #8 into the jaws

-SP Assembly Procedure

- 1) Disassemble bottom case #5 unfastening #64
- 2) Sub assemble springs #82 into the stud #70
- 3) Insert the spring and stud sub assembly into the bottom case
- 4) Install bottom case #5 onto the body and fasten with #64 screws with thread locker
- 5) Install pressure plate #8 onto the studs and fasten with #83 screws







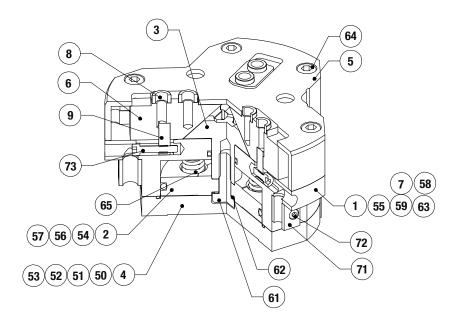








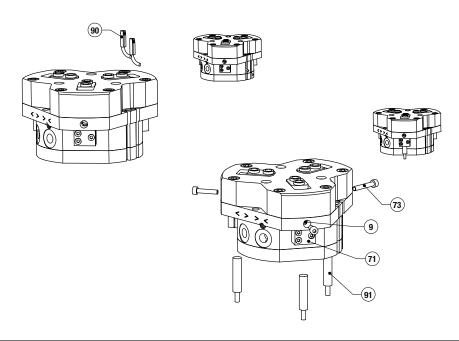




Hom	Otr	Name
Item	ЦLУ	Name
01	1	Body
02	1	Piston
03	1	Triple wedge
04	1	Cap
05	1	Bottom Case
06	3	Jaws
07	3	Plug
80	6	Locating sleeve
09	3	Sensing nut
50	1	Cap, 0-ring
<u>51</u>	3	Cap, 0-ring
52	3	Cap, SS screw
<u>53</u>	3	Cap, SHC screw
<u>54</u>	1	Piston, O-ring
55	1	Body, O-ring
56	1	Piston, Magnet
<u>57</u>	1	Piston, Pin
58	3	Plug, O-Ring
59	2	Body, SS screw
<u>61</u>		Triple wedge, HH screw
62	1	Triple wedge, Seal
63	2	Slide, Pin
64	6	Slide, SHC Screw
65	6	Spring
71	3	Sensor holder
72	6	Sensor holder, SHC screw
73	3	Sensing nut, SHC screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Magneto Resistive Sensor

- 1) Insert sensors #90 from either end of the profile slots
- 2) Set the sensor with the integrated screw

Inductive Sensor

- 1) Insert sensors #91 into the sensor holder #72
- 2) Tighten the sensor using the SHC screw onto the sensor holder #72
- 3) Insert the SHC screw #73 into the sensing nuts #9. The SHC screws are the targets to be adjusted in front of the sensor. Depending on the position to sense, use different length for the SHC screw #73 (shortest screw for open position, longest screw for close position). The sensing nut #9 has a thread insert that prevents the target from loosening. This may make the target harder to tighten into the nut.











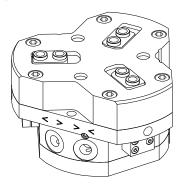


RTH/DTH SERIES SPECIALS

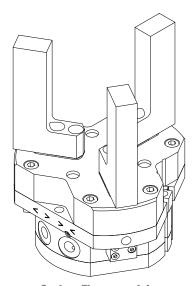


Fixed Jaws, Food-Grade Grease, Stroke Limiters, Custom Fingers and Jaws, Stainless Steel Components and more...

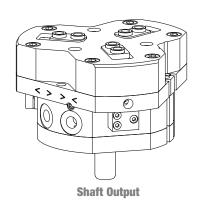
Drawings are for concept only. Contact Robohand Tech Support with project requirements.

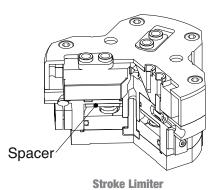


Fixed Jaws

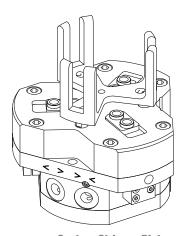


Custom Fingers and Jaws





Built-in Sensor with 2 Sensing Faces 2 or 3 Wire Technology

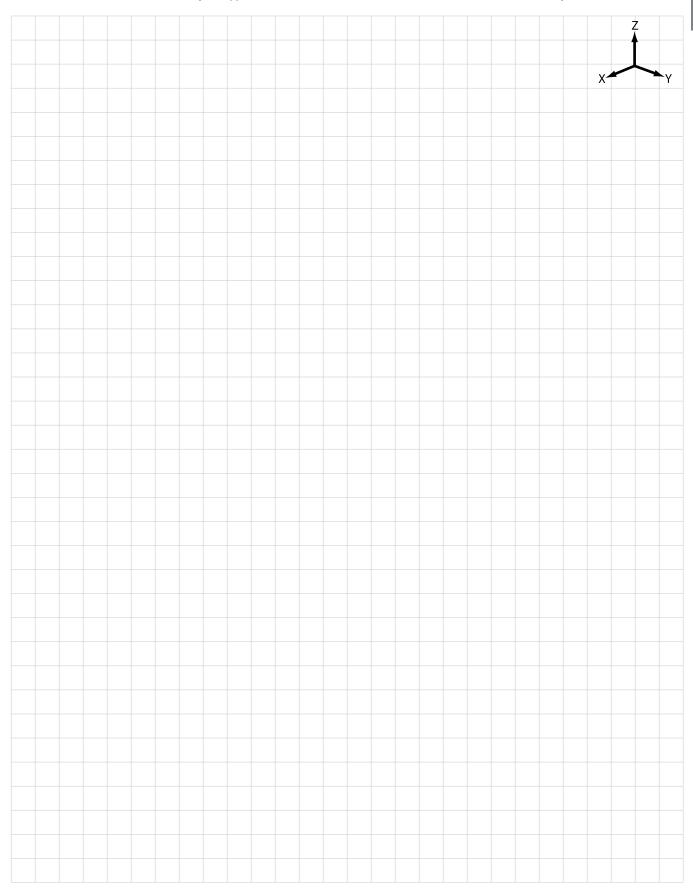


Custom Stripper Plate





Please describe your application. Include a sketch or attach additional sheets if necessary.



3P Parallel Gripper-3-Jaw Precision Series

Precision Gripper

The 3 concentric jaws and very good repeatability [0.02mm] allows loading and unloading accurate cylindrical parts.

Harsh Environments

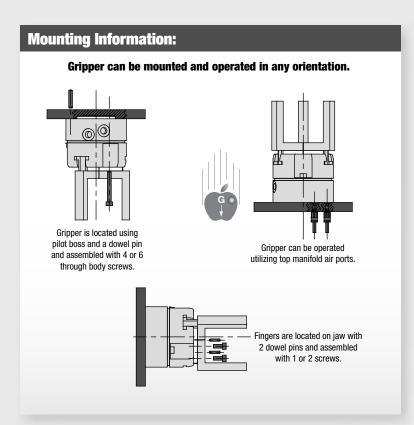
Shielded design (**-E**) repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.

Compact and Powerful

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, hydraulic power, safety springs for internal or external gripping, inductive sensors, tandem cylinder, Viton® seals, and protective boot) allow these grippers to be used in a number of applications.



Technical Specifications: Pneumatic Specifications Imperial Metric 30-100 psi Pressure Operating Range 2-7 bar **Double or double acting** Cylinder Type spring-assisted or single acting with spring **Dynamic Seals Buna-N** Valve Required to Operate: Double Acting 4-way, 2-position Single acting (Option RE or RI) 3-way. 2-position **Air Quality Requirements** Filtration **40 Micron or Better** Lubrification **Not Necessary* Temperature Operating Range** Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C **Application Restrictions Expected Life Normal Application** 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes *Addition of lubrication will greatly increase service life

Product Specifications

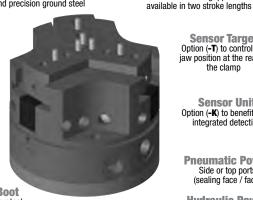
Quality Components

Body made from aluminum alloy with Teflon™ impregnated hardcoat anodize. Other essential parts of the gripper are made of hardened and precision ground steel

Versatile Finger Mounting 2 finger mounting surfaces on each jaw

Viton® Seals Optional Viton®

temperatures



Sensor Target Option (-T) to control the jaw position at the rear of the clamp

Standard and Extended Stroke (-C) Each model of gripper is

Sensor Unit

Option (-K) to benefit from integrated detection

Pneumatic Power Side or top ports (sealing face / face)

Hydraulic Power Option (-H) up to 20 bar max, (-H80) up to 80 bar max.

Tandem Cylinder

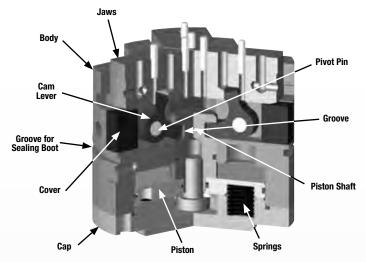
Protective Gripper Boot Optional Gripper Boot (**-E**) to protect the mechanism of the clamp are liquid and large external impurities.

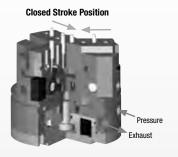
Spring Assist

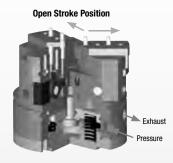
Spring assist retains the component should the air supply fail, to assist the gripper for internal (**-RE**) or external (**-RI**) gripping, or in single acting mode

Option (-M) doubles the grip force

Operating Principle







- A large double-acting piston is connected to the piston shaft at its end with a driving groove.
- Levers pivot in the body about an axis of articulation. Their two heads agree precisely on one side in the groove of the small piston, the other in a groove cut in each jaw holder.
- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

Style: 3P Precision Parallel Gripper



OUUSP	0003P=C
10 mm	16 mm
678 N	422 N
172 N	107 N
0.60 kg	0.60 kg
	10 mm 678 N 172 N

See Page 1.254 & 1.255

Style: 3P Precision Parallel Gripper



	8003P	8003P-C
Total Stroke:	13 mm	20 mm
Force at 6bar:1	1888 N	1219 N
Force w/o air:2	617 N	398 N
Weight:	0.97 kg	0.97 kg

See Page 1.256 & 1.257

Style: 3P Precision Parallel Gripper



	11003P	11003P-C
Total Stroke:	20 mm	30 mm
Force at 6bar:1	2967 N	1979 N
Force w/o air:2	941 N	628 N
Weight:	2.35 kg	2.35 kg

See Page 1.258 & 1.259

Style: 3P Precision Parallel Gripper



	14003P	14003P-C
Total Stroke:	26 mm	40 mm
Force at 6bar:1	6077 N	3930 N
Force w/o air:2	2248 N	1453 N
Weight:	4.70 kg	4.70 kg

See Page 1.260 & 1.261

Style: 3P Precision Parallel Gripper



	16503P	16503P-C
Total Stroke:	30 mm	50 mm
Force at 6bar:1	11190 N	6707 N
Force w/o air:2	3730 N	2235 N
Weight:	9.04 kg	9.04 kg

See Page 1.262 & 1.263

OPTIONS & ACCESSORIES

See Page 1.264 & 1.267

- 1. Force with spring and air at 6bar
- 2. Force with spring without air

PARALLEL GRIPPER 6003P PRECISION 3P GRIPPER SERIES



Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 678 N Grip Force $(F_{0+R})^2$, 0 bars, Springs Mid-Way, L=0 172 N Total Stoke 10 mm Weight 0.60 kg Pressure Range 2 -7 bar Pressure Range with Springs 3 -7 bar Ø Cylinder Bore 40 mm Displacement 12 cm3 Actuation (open / close) 0.07 s / 0.07 s Repeatability ± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW $\Rightarrow \Leftrightarrow$ Imperial in. Metric [mm]

Third Angle Projection

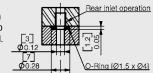
All Dowel Holes are SF (Slip Fit).

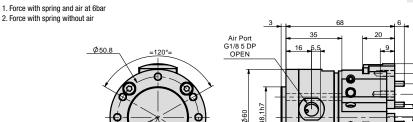
Acational Tolerance

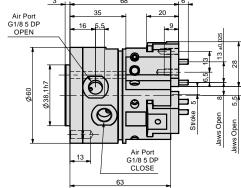
Metric Threads
Course Pitch ±.0005" or [±.013mm]

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

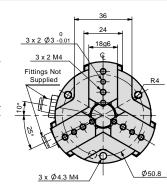






Dimensions are

symmetrical about



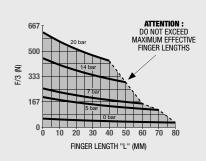
Loading Information:

M4 5 DP OPENING

(seals included)

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)

CLOSING (seals included)









Loading Capacity*	Statique	Dynamique
Maximum Tensile T	819 N	175 N
Maximum Compresive C	1556 N	175 N
Maximum Moment Mx	42 Nm	5 Nm
Maximum Moment My	49 Nm	6 Nm
Maximum Moment Mz	54 Nm	6 Nm

^{*} The Capacities are per set of jaws and are not simultaneous

How To Order:



POWER TYPE

TARGET FLAG

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

POWER TYPE	
P Pneumatic H Hydraulic (page 1.264) (One of two options is mandatory P or H)	
SPRINGS	
RE External Gripping RI Internal Gripping	
SENSOR UNIT	
• KT1 • KT2 • KX1 • K	X2
PROTECTIVE BOOT	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER63P	1
Fireproof KEVLAR Protective Boot, Red	E 3	E3R63P	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P	1 or 2
M8 Inductive Sensor PNP with M8 connector		0ISP-011-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 to 4
Cable (2 meters) with M8 screw right gold		CABL-010	1 to 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-156	1
Viton® Seal Repair Kit		SLKT-156V	1
Hydraulic Seal Repair Kit		SLKT-330	1



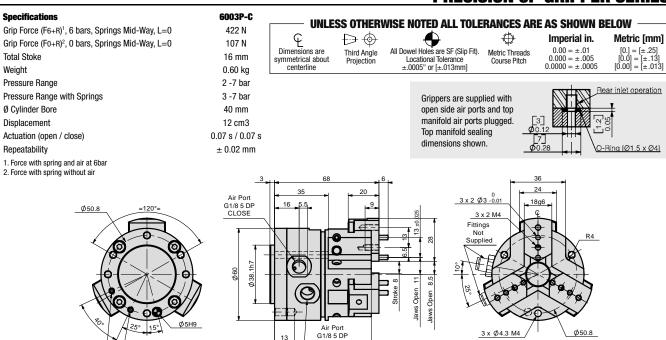
Air Port

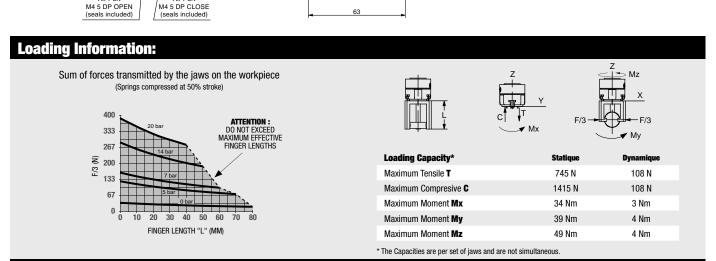
Air Port

PARALLEL GRIPPER 6003P-C **PRECISION 3P GRIPPER SERIES**

Ø50.8

3 x Ø 4.3 M4





OPEN

w To Order:					
BASE MODEL	SPRINGS SENS	OR UNIT EXTENDED STI	ROKE PROTECT	TIVE BOOT	
6003P -		- SD -	C -	V	M
POWER TYPE	TARGET FLAG	INDUCTIVE SENSOR MOU	NT VITON® SEA	ALS TANDI	EM CYLINDE
	PROTECTIVE BOOT ACCE	ESSORIES	Model Code	Order #	Qty/Unit
POWER TYPE P Pneumatic	PVC Protective Boot, Brown o	r Black	E	ER63P	1
P Pneumatic H Hydraulic (page 1.264) (One of two options is mandatory P or H)	Fireproof KEVLAR Protective E	Boot, Red	E3	E3R63P	1
SPRINGS	Inductive Sensor Kit (1 holder	: 1 flag)	SD	SD60-80P	1 or 2
RE External Gripping RI Internal Gripping	M8 Inductive Sensor PNP with		- -	0ISP-011-C	1 to 4
SENSOR UNIT	M8 Inductive Sensor NPN wit	h M8 connector		OISN-011-C	1 to 4
• KT1 • KT2 • KX1 • KX2 PROTECTIVE BOOT • E • E3	Cable (2 meters) with M8 screen	* *		CABL-010	1 to 4
	Standard Seal Repair Kit			SLKT-156	1
	Viton® Seal Repair Kit			SLKT-156V	1
Options and Accessories: See Page 1.264	Hydraulic Seal Repair Kit			SLKT-330	1

PARALLEL GRIPPER 8003P PRECISION 3P GRIPPER SERIES



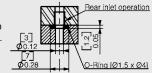
Specifications	8003P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	1888 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	617 N
Total Stoke	13 mm
Weight	0.97 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	60 mm
Displacement	35 cm3
Actuation (open / close)	0.08 s / 0.08 s
Repeatability	+ 0.02 mm

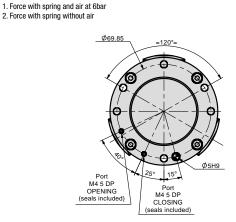
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

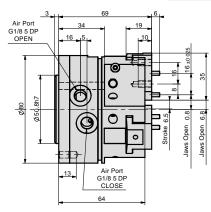
All Dowel Holes are SF (Slip Fit).
Locational Tolerance
Course Pitch ±.0005" or [±.013mm]

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.





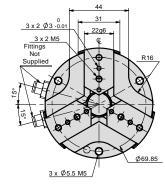


 $\Rightarrow \Leftrightarrow$

Third Angle Projection

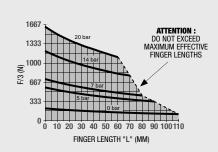
Dimensions are

symmetrical about



Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Loading Capacity*	Statique	Dynamique
Maximum Tensile T	1229 N	436 N
Maximum Compresive C	2075 N	436 N
Maximum Moment Mx	60 Nm	16 Nm
Maximum Moment My	68 Nm	19 Nm
Maximum Moment Mz	37 Nm	19 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

BASE MODEL SPRINGS SENSOR UNIT PROTECTIVE BOOT 8003P

POWER TYPE

TARGET FLAG

INDUCTIVE SENSOR MOUNT

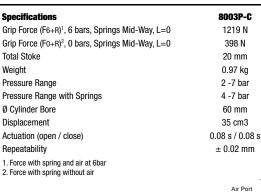
TANDEM CYLINDER

POWER TYPE
P Pneumatic H Hydraulic (page 1.264) (One of two options is mandatory P or H)
SPRINGS
RE External Gripping RI Internal Gripping
SENSOR UNIT
• KT1 • KT2 • KX1 • KX2
PROTECTIVE BOOT
• E • E3

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER83P	1
Fireproof KEVLAR Protective Boot, Red	E3	E3R83P	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-011-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		OISN-011-C	1 to 4
Cable (2 meters) with M8 screw right gold		CABL-010	1 to 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		S80	1
Viton® Seal Repair Kit		S80V	1
Hydraulic Seal Repair Kit		S80H	1



PARALLEL GRIPPER 8003P-C PRECISION 3P GRIPPER SERIES



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW 0 Imperial in.

Dimensions are symmetrical about

centerline

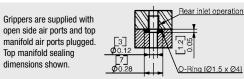
Third Angle Projection

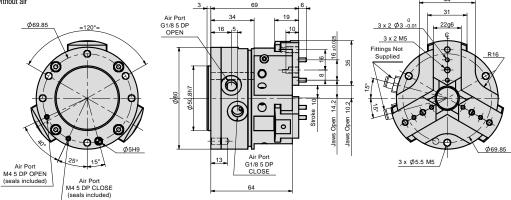
All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

Metric Threads Course Pitch

 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

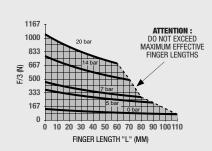
Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$





Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Qty/Unit

1

1

1 or 2

1 to 4

1 to 4

1 to 4

1

1

S80H

Loading Capacity*	Statique	Dynamique
Maximum Tensile T	1097 N	281 N
Maximum Compresive C	1853 N	281 N
Maximum Moment Mx	39 Nm	12 Nm
Maximum Moment My	44 Nm	13 Nm
Maximum Moment Mz	34 Nm	13 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

BASE MODEL SPRINGS SENSOR UNIT EXTENDED STROKE PROTECTIVE BOOT 8003P

POWER TYPE INDUCTIVE SENSOR MOUNT VITON® SEALS TANDEM CYLINDER TARGET FLAG

POWE	R TYPE		
P	Pneumatic		
Н	Hydraulic (page 1.264)	
(One of	two options is	mandatory P	or H)
SPRII	VGS		
RE	External G	ripping	
RI	Internal Gr	ipping	
SENS	OR UNIT		
• K	Γ1 • KT2	• KX1	• KX2
PROT	ECTIVE BOO	T	
• E	• E3		
_			

Options and Accessories: See Page 1.264

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #
PVC Protective Boot, Brown or Black	E	ER83P
Fireproof KEVLAR Protective Boot, Red	E3	E3R83P
SENSOR ACCESSORIES		
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD60-80P
M8 Inductive Sensor PNP with M8 connector		0ISP-011-C
M8 Inductive Sensor NPN with M8 connector		OISN-011-C
Cable (2 meters) with M8 screw right gold		CABL-010
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit		\$80
Viton® Seal Repair Kit		S80V

Hydraulic Seal Repair Kit

PARALLEL GRIPPER 11003P PRECISION 3P GRIPPER SERIES



Specifications	11003P
Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0	2967 N
Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0	941 N
Total Stoke	20 mm
Weight	2.35 kg
Pressure Range	2 -7 bar
Pressure Range with Springs	4 -7 bar
Ø Cylinder Bore	76 mm
Displacement	87 cm3
Actuation (open / close)	0.10 s / 0.10
Repeatability	± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Imperial in.

 $\rightarrow \oplus$

Dimensions are

symmetrical about centerline

Third Angle Projection

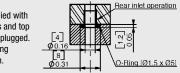
All Dowel Holes are SF (Slip Fit).
Locational Tolerance

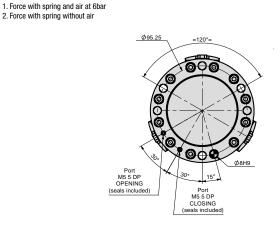
Metric Threads
Course Pitch ±.0005" or [±.013mm]

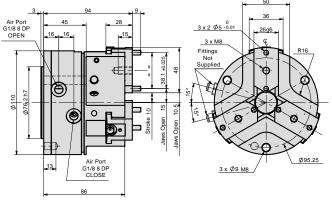
 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



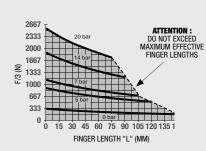




Loading Information:

2. Force with spring without air

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Capacités de chargement*	Statique	Dynamique
Traction maximale T	1560 N	695 N
Compression maximale C	2652 N	695 N
Moment maximum Mx	60 Nm	31 Nm
Moment maximum My	80 Nm	41 Nm
Moment maximum Mz	90 Nm	41 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:



POWER TYPE TARGET FLAG

INDUCTIVE SENSOR MOUNT

TANDEM CYLINDER

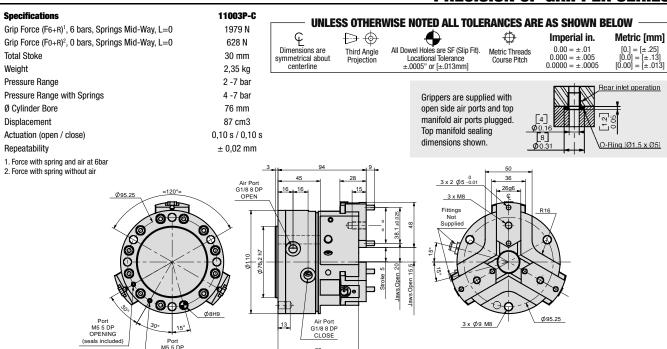
P H	Pneumatic
	Hydraulic (page 1.264) two options is mandatory P or H)
SPRIN	, , , , , , , , , , , , , , , , , , , ,
RE RI	External Gripping Internal Gripping
SENS	OR UNIT
• [(]	1 • KT2 • KX1 • KX2
PROT	ECTIVE BOOT
• E	• E3

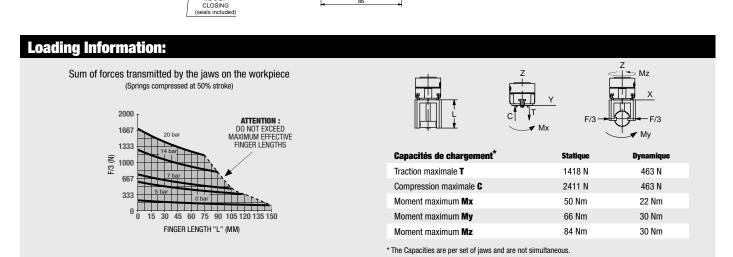
Options	and	Acce	essor	ies:
See	Pag	je 1.2	264	

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	ER113P	1
Fireproof KEVLAR Protective Boot, Red	E3	E3R113P	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	SD110P	1 or 2
M8 Inductive Sensor PNP with M8 connector		0ISP-011-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		0ISN-011-C	1 to 4
Cable (2 meters) with M8 screw right gold		CABL-010	1 to 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		S110	1
Viton® Seal Repair Kit		\$110V	1
Hydraulic Seal Repair Kit		S110H	1



PARALLEL GRIPPER 11003P-C PRECISION 3P GRIPPER SERIES





BASE MODEL	SPRINGS	SENSOR	UNIT EXTENDED	STROKE PROTE	CTIVE BOOT	
11003P -		T	+ SD	- C -	- v	- M
POWER TYPE	TARGET I	FLAG IN	IDUCTIVE SENSOR N	IOUNT VITON® S	SEALS TAND	EM CYLINDI
POWER TYPE	PROTECTIVE BO	OT ACCESSO	RIES	Model Code	Order #	Qty/Unit
P Pneumatic	PVC Protective Boo	t, Brown or Blac	k	E	ER113P	1
H Hydraulic (page 1.264) (One of two options is mandatory P or H)	Fireproof KEVLAR F	Protective Boot, F	Red	E3	E3R113P	1
SPRINGS	SENSOR ACCESS	SORIES				
RE External Gripping	Inductive Sensor K	it (1 holder, 1 fla	g)	SD	SD110P	1 or 2
RI Internal Gripping SENSOR UNIT	M8 Inductive Sense	or PNP with M8	connector		OISP-011-C	1 to 4
• KT1 • KT2 • KX1 • KX2	M8 Inductive Sense	or NPN with M8	connector		OISN-011-C	1 to 4
PROTECTIVE BOOT	Cable (2 meters) w	ith M8 screw rig	ht gold		CABL-010	1 to 4
• E • E3	PNEUMATIC AC	CESSORIES				
	Standard Seal Repai	ir Kit			S110	1
Options and Accessories:	Viton® Seal Repair K	iit			S110V	1
See Page 1.264	Hydraulic Seal Repa	ir Kit			S110H	1

PARALLEL GRIPPER 14003P PRECISION 3P GRIPPER SERIES



14003P Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 6077 N Grip Force $(F_{0+R})^2$, 0 bars, Springs Mid-Way, L=0 2248 N Total Stoke 26 mm Weight 4.70 kg Pressure Range 2 -7 bar Pressure Range with Springs 4.5 -7 bar Ø Cylinder Bore 105 mm Displacement 220 cm3 Actuation (open / close) 0.16 s / 0.16 s Repeatability ± 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

 $\Rightarrow \Leftrightarrow$ Third Angle Projection symmetrical about

Dimensions are

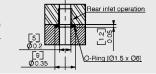
All Dowel Holes are SF (Slip Fit).

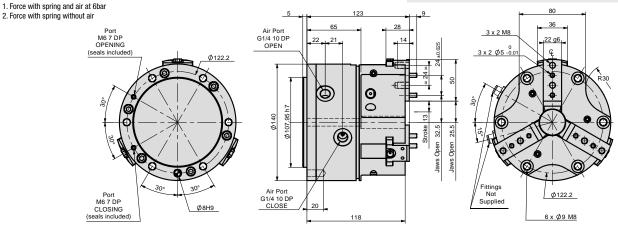
Acational Tolerance

Metric Threads
Course Pitch ±.0005" or [±.013mm]

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric [mm]

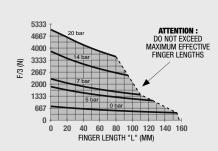
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.





Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Loading Capacity*	Statique	Dynamique
Maximum Tensile T	2390 N	850 N
Maximum Compresive C	2700 N	850 N
Maximum Moment Mx	85 Nm	25 Nm
Maximum Moment My	130 Nm	40 Nm
Maximum Moment Mz	100 Nm	40 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

BASE MODEL SPRINGS SENSOR UNIT PROTECTIVE BOOT 14003P

POWER TYPE TARGET FLAG **INDUCTIVE SENSOR MOUNT TANDEM CYLINDER**

POWER TYPE
P Pneumatic H Hydraulic (page 1.264) (One of two options is mandatory P or H)
SPRINGS
RE External Gripping RI Internal Gripping
SENSOR UNIT
• KT1 • KT2 • KX1 • KX2
PROTECTIVE BOOT
• E • E3

PVC Protective Boot, Brown or Black E KP-317 1 Fireproof KEVLAR Protective Boot, Red E3 KP-319 1 SENSOR ACCESSORIES Inductive Sensor Kit (1 holder, 1 flag) SD OSMK-114 1 or 2 M8 Inductive Sensor PNP with M8 connector OISP-017-C 1 to 4 M8 Inductive Sensor NPN with M8 connector OISN-017-C 1 to 4 Cable (2 meters) with M8 screw right gold CABL-014 1 to 4 PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit SLKT-333V 1 Hydraulic Seal Repair Kit SLKT-334 1	PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
SENSOR ACCESSORIES Inductive Sensor Kit (1 holder, 1 flag) M8 Inductive Sensor PNP with M8 connector M8 Inductive Sensor PNP with M8 connector M8 Inductive Sensor NPN with M8 connector Cable (2 meters) with M8 screw right gold PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit	PVC Protective Boot, Brown or Black	E	KP-317	1
M8 Inductive Sensor PNP with M8 connector OISP-017-C 1 to 4 M8 Inductive Sensor NPN with M8 connector OISN-017-C 1 to 4 Cable (2 meters) with M8 screw right gold CABL-014 1 to 4 PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit SLKT-333V 1	'	E3	KP-319	1
M8 Inductive Sensor NPN with M8 connector OISN-017-C 1 to 4 Cable (2 meters) with M8 screw right gold CABL-014 1 to 4 PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit SLKT-333V 1	Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-114	1 or 2
Cable (2 meters) with M8 screw right gold PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit SLKT-333V 1	M8 Inductive Sensor PNP with M8 connector		OISP-017-C	1 to 4
PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-333 1 Viton® Seal Repair Kit SLKT-333V 1	M8 Inductive Sensor NPN with M8 connector		OISN-017-C	1 to 4
Viton® Seal Repair Kit SLKT-333V 1	, ,		CABL-014	1 to 4
	Standard Seal Repair Kit		SLKT-333	1
Hydraulic Seal Repair Kit SLKT-334 1	Viton® Seal Repair Kit		SLKT-333V	1
	Hydraulic Seal Repair Kit		SLKT-334	1



Actuation (open / close)

Repeatability

PARALLEL GRIPPER 14003P-C PRECISION 3P GRIPPER SERIES

Imperial in.

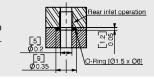
 $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

14003P-C **Specifications UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW** 3930 N Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 All Dowel Holes are SF (Slip Fit).
Locational Tolerance 0 Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 1453 N Dimensions are Third Angle Projection Metric Threads Course Pitch Total Stoke 40 mm symmetrical about 4.70 kg centerline ±.0005" or [±.013mm] Weight Pressure Range 2 -7 bar Pressure Range with Springs 4.5 -7 bar Ø Cylinder Bore 105 mm Displacement 220 cm3

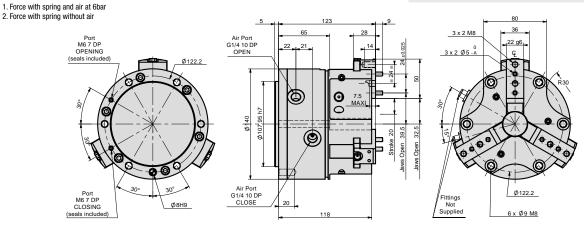
0.16 s / 0.16 s

± 0.02 mm

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

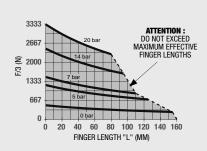


Metric [mm]



Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Dynamique
590 N
590 N
20 Nm
32 Nm
32 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:

BASE MODEL SPRINGS SENSOR UNIT EXTENDED STROKE PROTECTIVE BOOT 14003P

POWER TYPE INDUCTIVE SENSOR MOUNT VITON® SEALS TANDEM CYLINDER TARGET FLAG

POW	ER TYF	E		
P	Pneu	matic		
Н	Hydr	aulic (pa	age 1.264)	
(One o	two op	tions is m	andatory P	or H)
SPRI	IGS			
RE RI		nal Grip		
			pilig	
SENS	OR UN	Ш		
• K	u -	• KT2	• KX1	• KX2
PROT	ECTIV	E BOOT		
• E		• E3		
_				

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-317	1
Fireproof KEVLAR Protective Boot, Red	E3	KP-319	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-114	1 or 2
M8 Inductive Sensor PNP with M8 connector		0ISP-017-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		0ISN-017-C	1 to 4
Cable (2 meters) with M8 screw right gold		CABL-014	1 to 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-333	1
Viton® Seal Repair Kit		SLKT-333V	1
Hydraulic Seal Repair Kit		SLKT-334	1

PARALLEL GRIPPER 16503P PRECISION 3P GRIPPER SERIES



16503P Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 11190 N Grip Force $(F_{0+R})^2$, 0 bars, Springs Mid-Way, L=0 3730 N Total Stoke 30 mm Weight 9.04 kg Pressure Range 2 -7 bar Pressure Range with Springs 4.5 -7 bar Ø Cylinder Bore 120 mm Displacement 494 cm3 Actuation (open / close) 0.29 s / 0.29 s Repeatability \pm 0.02 mm

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

 $\Leftrightarrow \in$ Third Angle Projection

All Dowel Holes are SF (Slip Fit).

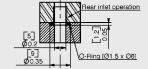
I ocational Tolerance

Course Pitch ±.0005" or [±.013mm]

Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

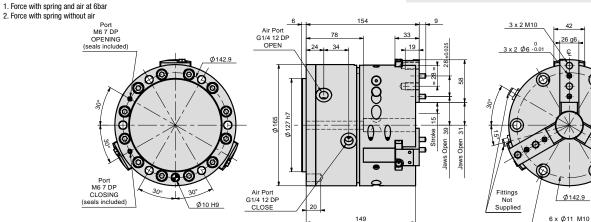
Metric [mm]

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



26 g6

Ø142.9

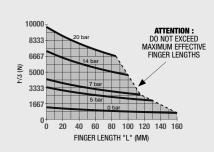


Dimensions are

symmetrical about

Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)









Loading Capacity*	Statique	Dynamique
Maximum Tensile T	2580 N	980 N
Maximum Compresive C	3200 N	980 N
Maximum Moment Mx	100 Nm	32 Nm
Maximum Moment My	150 Nm	50 Nm
Maximum Moment Mz	140 Nm	50 Nm

^{*} The Capacities are per set of jaws and are not simultaneous

How To Order:



POWER TYPE TARGET FLAG **INDUCTIVE SENSOR MOUNT TANDEM CYLINDER**

POWER TYPE
P Pneumatic H Hydraulic (page 1.264) (One of two options is mandatory P or H)
SPRINGS
RE External Gripping RI Internal Gripping
SENSOR UNIT
• KT1 • KT2 • KX1 • KX2
PROTECTIVE BOOT
• E • E3

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-320	1
Fireproof KEVLAR Protective Boot, Red	E 3	KP-322	1
SENSOR ACCESSORIES			
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-115	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-017-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		OISN-017-C	1 to 4
Cable (2 meters) with M8 screw right gold		CABL-014	1 to 4
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit		SLKT-335	1
Viton® Seal Repair Kit		SLKT-335V	1
Hydraulic Seal Repair Kit		SLKT-336	1



Ø Cylinder Bore

Actuation (open / close)

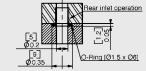
Displacement

Repeatability

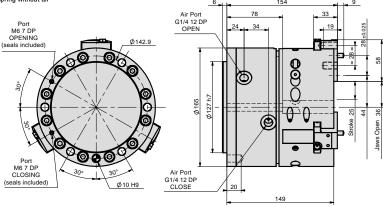
PARALLEL GRIPPER 16503P-C PRECISION 3P GRIPPER SERIES

16503P-C **Specifications UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW** Grip Force (F6+R)1, 6 bars, Springs Mid-Way, L=0 6707 N All Dowel Holes are SF (Slip Fit). 0 Imperial in. Metric [mm] Grip Force (F0+R)2, 0 bars, Springs Mid-Way, L=0 2235 N $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Dimensions are Third Angle Projection Metric Threads Course Pitch 50 mm Total Stoke symmetrical about Locational Tolerance Weight 9.04 kg centerline ±.0005" or [±.013mm] Pressure Range 2 -7 bar Pressure Range with Springs 4.5 -7 bar

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



1. Force with spring and air at 6bar 2. Force with spring without air

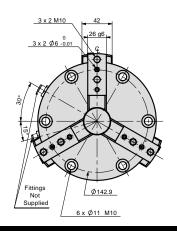


120 mm

494 cm3

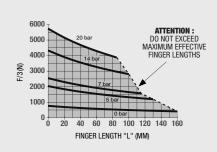
0.29 s / 0.29 s

 \pm 0.02 mm

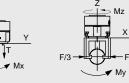


Loading Information:

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)







Loading Capacity*	Statique	Dynamique
Maximum Tensile T	2250 N	810 N
Maximum Compresive C	2800 N	810 N
Maximum Moment Mx	90 Nm	28 Nm
Maximum Moment My	140 Nm	40 Nm
Maximum Moment Mz	130 Nm	40 Nm

^{*} The Capacities are per set of jaws and are not simultaneous.

How To Order:



POWER TYPE INDUCTIVE SENSOR MOUNT VITON® SEALS TANDEM CYLINDER TARGET FLAG

POW	ER TYPE
P	Pneumatic
Н	Hydraulic (page 1.264)
(One o	two options is mandatory P or H)
SPRI	IGS
RE RI	External Gripping Internal Gripping
SENS	OR UNIT
• K	Γ1 • KT2 • KX1 • KX2
PROT	ECTIVE BOOT
• E	• E3
-	

RE RI		rnal Grip nal Gripp		
SENS	OR UI	TIV		
• K1	M	• KT2	• KX1	• KX2
PROT	ECTIV	E BOOT		
• E		• E3		
			_	
Opti	ons	and	Acces	sories:

See Page 1.264

PROTECTIVE BOOT ACCESSORIES	Model Code	Order #	Qty/Unit
PVC Protective Boot, Brown or Black	E	KP-320	1
Fireproof KEVLAR Protective Boot, Red SENSOR ACCESSORIES	E3	KP-322	1
Inductive Sensor Kit (1 holder, 1 flag)	SD	OSMK-115	1 or 2
M8 Inductive Sensor PNP with M8 connector		OISP-017-C	1 to 4
M8 Inductive Sensor NPN with M8 connector		OISN-017-C	1 to 4
Cable (2 meters) with M8 screw right gold PNEUMATIC ACCESSORIES		CABL-014	1 to 4
Standard Seal Repair Kit		SLKT-335	1
Viton® Seal Repair Kit		SLKT-335V	1
Hydraulic Seal Repair Kit		SLKT-336	1

SUPPLY: (P) Pneumatic (H) (H80) Hydraulic

As standard, the clamp is supplied with air to a pressure of 7 bar. The clamp is fitted with Viton 0-ring seals for high temperatures.

On request (contact us) the gripper can be supplied with hydraulic fluid. The clamp is fitted with seals Viton Quad-Ring.

- Choice (H) allows a hydraulic power to a pressure of 20 bar max. In this case the overall dimensions do not change. For better security the gripper must be fixed on their support before being fired. **CAUTION: Hydraulic cycle times are longer.**
- Choice (**H80**) allows a hydraulic power to a pressure of 80 bar max. In this case the total height of the gripper is increased (contact us).

The hydraulic power is incompatible with the option tandem (M).

Option (RE) or (RI): Spring Assist

The internal springs of the gripper ensures failsafe operation by retaining the component during pressure loss, to increase the gripforce, or allows the usage of the gripper in single acting operation.

Option (RE) for external gripping. Option (RI) for internal gripping.

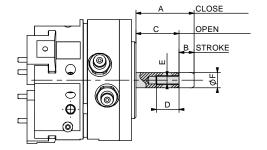
The (RE) is incompatible with the option (RI).

Option (T): Sensor Rod

Option (T) is a steel rod which comes out on the rear side of the gripper. The rod is fixed with the piston and has the same stroke movement. The open end of the rod allows for mounting a cam which allows to control the position of the jaws by using inductive sensors, micro switches, etc

WARNING: when screwing on cam rod, make sure the sensor rod does not rotate to prevent twisting of the springs of options (RE) or (RI).

Option (T) is incompatible with option (K).



Model	A	В	C	D	E	F
6003P & 6003P-C	35	5	30	15	M6	10
8003P & 8003P-C	35	6.5	28.5	15	M6	10
11003P & 11003P-C	35	10	25	15	M6	15
14003P & 14003P-C	55	13	42	20	M8	15
16503P & 16503P-C	53	23	30	20	M8	15

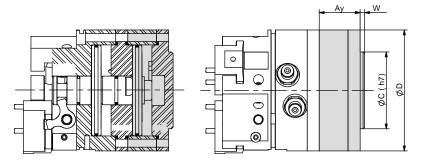
Option (M): Tandem Cylinder

The (**M**) is a cylinder light-alloy that fits behind the bottom plate. This actuator's integral action allows to double the gripforce by using the same pressure.

The combination of tandem option tandem (**M**) and Option (**RE**) or (**RI**) can double the clamping forces of the spring assist option. For cycle times of the tandem option, apply a factor of 3 to the actuation time.

The (M) is incompatible with the option (H).

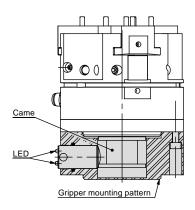
Model	Ау	ØC	ØD	W	Weight (kg)
6003P & 6003P-C	28.5	38.1	60	3	0.200
8003P & 8003P-C	27	50.8	80	3	0.300
11003P & 11003P-C	34	76.2	110	3	0.750
14003P & 14003P-C	49	107.95	140	5	2.100
16503P & 16503P-C	65	127	165	6	3.600

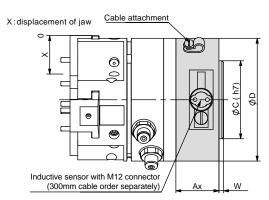


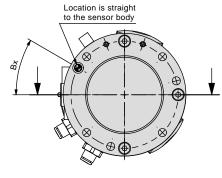
Option (KT1), (KX1), (KT2), (KX2): Sensor Unit

The (**K**) is a lightweight alloy housing that fits on the back of the gripper. An integrated shaft follows the movement of the piston to provide information to the sensor attached to the side of the unit. It can control two positions of the grippers jaws. 2 types of inductive sensors (**KT, KX**) and 2 detection zones (**1, 2**) are possible to allow for the combination of 2 to 4 possible positions (**KT1, KX1, KT2, KX2**). For **KT, KX** sensor specifications.









Model #	Ax	Вх	ØC	ØD	w	Weight (kg)	No. of Sensing Postions (please specify when ordering)	Information area from the open grip position (green LED) X (mm)	Area information relative to the closed grip position (yellow LED) X (mm)
6003P	23	30°	38.1	60	3	0.180	1	0 - 1 +0,5	4 ⁺⁰ _{-0,5} to 5
00031	20	30	30.1	00	J	0.100	2	0 - 2 +0,5	3 ⁺⁰ _{-0,5} to 5
6003P-C	23	30°	38.1	60	3	0.180	1	0 - 1.6 +0,8	7 ⁺⁰ to 8
UUUSF-U	23	30	30.1	00	3	0.100	2	0 - 3.2 $^{+0,8}_{-0}$	4.8 ⁺⁰ _{-0,8} to 8
8003P	28	30°	50.8	80	3	0.400	1	0 - 1 +0,5	5.5 ⁺⁰ _{-0,5} to 6,5
OUUSF	20	30	30.0	00	3	0.400	2	0 - 2 +0,5	4.5 ⁺⁰ _{-0,5} to 6,5
8003P-C	28	30°	50.8	80	3	0.400	1	0 - 1.5 +0,8	8.5 ⁺⁰ _{-0,8} to 10
0003P-G	20	30	50.6	00	3	0.400	2	0 - 3.1 +0,8	6.9 ⁺⁰ _{-0,8} to 10
11003P	36	30°	76.2	110	3	0.900	1	0 - 1 +0,5	9 ⁺⁰ _{-0,5} to 10
11003F	30	30	70.2	110	3	0.900	2	0 - 3 +0,5	7 ⁺⁰ _{-0,5} to 10
10003P-C	36	30°	76.2	110	3	0.900	1	0 - 1.5 $^{+0,8}_{-0}$	13.5 ⁺⁰ _{-0,8} to 15
10003P-G	30	30	70.2	110	3	0.900	2	0 - 4.5 +0,8	10.5 ⁺⁰ _{-0,8} to 15
14003P	45.5	165°	107.95	140	5	1.670	1	0 - 2 +0,5	11 ⁺⁰ _{-0,5} to 13
14003F	45.5	100	107.95	140	3	1.070	2	0 - 4 +0,5	9 ⁺⁰ _{-0,5} to 13
14003P-C	45.5	165°	107.95	140	5	1.670	1	0 - 3 +0,8	17 ⁺⁰ _{-0,8} to 20
140037-6	45.5	100	107.95	140	5	1.670	2	0 - 6.2 $^{+0,8}_{-0}$	13.8 ⁺⁰ _{-0,8} to 20
16503P	65.5	165°	127	165	6	2.670	1	0 - 2 +0,5	13 ⁺⁰ _{-0,5} to 15
10003P	00.0	100	121	100	O	2.070	2	0 - 4 +0,5	11 ⁺⁰ _{-0,5} to 15
10500B 0	CE E	1050	107	105		0.070	1	0 - 3.3 +0.8	21.7 ⁺⁰ _{-0,8} to 25
16503P-C	65.5	165°	127	165	6	2.670	2	0 - 7 +0,8	18 ⁺⁰ _{-0,8} to 25



Option (V): Viton® Seals

Gripper with Viton® seals allows for use in high temperature environments [-30 ° C or 150 ° C].

Accessory (E): Protective Boot

The accessory (**E**) is a protective boot that fits over the gripper. It protects the mechanism and thus improves the life of the gripper in hostile environments. The accessory (**E**) causes a different location of the fingers on the jaws as compared to the standard installation. Before attaching the boot, perform the following steps:

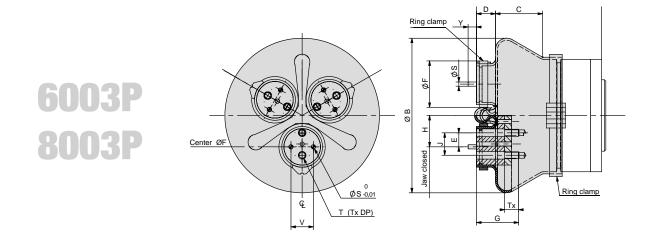
- 1. Mount gripper to machine.
- 2. Slip boot over gripper and secure in place.
- 3. Attached fingers to jaws using finger adapter.

Depending on the environment 2 types of envelopes are available:

- (E) Envelope of black or brown PVC for environmental grinding with emery presence.
- (E3) red envelope containing KEVLAR fireproof silicone environment for hot chips and weld spatter.

The accessory (E) is incompatible with the accessory (SD)

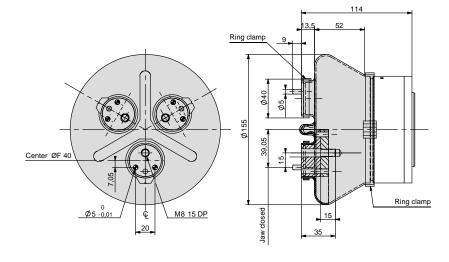
Model Code	Order #	Model	A	В	C	D	E	F	G	Н	J	K	S	T	TX	V	Y
E	ER62P	6003P &	88	98	35	13.5	8	29	29	17.5	13		3	M4	9	13	6
E3	E3R62P	6003P-C	00	30	33	13.3	Ü	29	29	17.3	13	_	3	IVI 4	9	13	
E	ER82P	8003P &	89	110	34	13.5	10	33	30	22.3	16		3	M5	10	16	6
E 3	E3R82P	8003P-C	89	110	10 34	13.3	10	33	30 22.	22.3	10	_	J	IVIJ	10	10	U
E	ER112P	11003P &							Co	e drawi	na						
E3	E3R112P	11003P-C							36	e urawi	iiy						
E	KP-311	14003P &	140	185	50	18	12	55	34	19.5	24	18	5	M8	14		8
E3	KP-313	14003P-C	143	100	50	10	12	55	34	19.5	24	10	5	IVIO	14	_	0
E	KP-314	16503P &	170	220	70	16	14	67	37	24	28	23	6	M10	10		8
E 3	KP-316	16503P-C	172	220	70	10	14	07	3/	19	20	23	0	M10	19	_	0



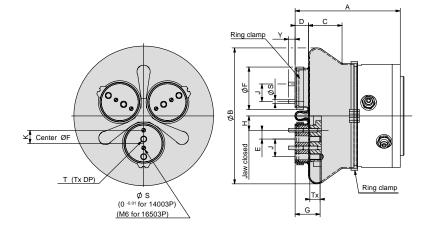


OPTIONS AND ACCESSORIES PRECSION 3P GRIPPER SERIES





14003P 16503P



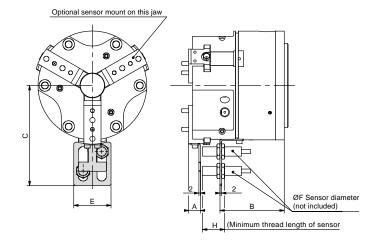
Accessory (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (**SD**) includes: 1 sensor bracket, 1 flag and screws. **Sensors are not provided.**

NOTES:

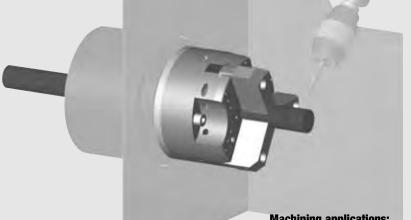
To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (**SD**).



Order #	Model	A	В	C	E	F	H
SD60-80P	6003P & 6003P-C	20	35	67	32	8	35
SD60-80P	8003P & 8003P-C	19	34	77	32	8	35
SD110P	11003P & 11003P-C	19.5	45	97	32	8	35
OSMK-114	14003P & 14003P-C	15	83	129	48	12	28.5
OSMK-115	16503P & 16503P-C	29	96	147	48	12	33

Through Hole Parallel Gripper PPC Series



Through Hole Gripper:

Designed for unique applications where a component ejector is needed after un-gripping the part or to blow air for cleaning the part center. The through hole design allows for the mounting of sensors to detect part presence, and for feeding parts to machining centers.

Machining applications:

The 3 concentric jaws and the excellent repeatability make it easier to accurately load and unload round parts.

Compact, robust and powerful gripper:

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism.

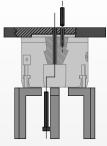
Multipurpose gripper:

A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, inductive sensors, Viton® seals) allow these grippers to be used in a number of applications.

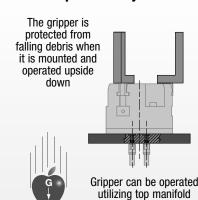
30-100 psi

Mounting Information:

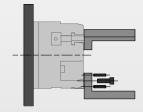
Grippers can be mounted and operated in any direction



Gripper is located using pilot boss and a dowel pin and assembled with 3 through body screws



air ports



Fingers are located on jaws with 2 dowel pins and assembled with 1 screw

Technical Specifications:

Pneum	atic	Speci	fications
_	_		_

Pressure Operating Range without springs Pressure Operating Range with springs Cylinder Type

Dynamic Seals Valve Required to Operate **Double Acting** Single Acting

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

Imperial Metric

2-7 bar

45-100 psi 3-7 bar

Double Acting or Double Acting Spring Assist or Single Acting Spring Return **Internally Lubricated Buna-N**

> 4-way, 2-position 3-way, 2-position

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C -20°~300° F Viton® Seals (optional) -30°~150° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance

Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

^{*}Addition of lubrication will greatly increase service life †See Maintenance Section

Product Features

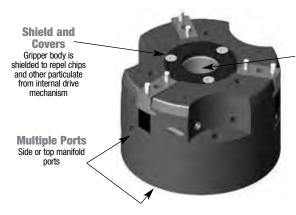
Viton® Seals Optional for high temperature applications

Quality Components

Made from Aluminum alloy, hard coat anodized with Teflon® Impregnation.The gripper's main components are made of heat treated steel

Standard Stroke and Extended Stroke

Each model of gripper is available in 2 stroke lengths



Through Hole Design

The standard hole diameter can be customized with optional sleeves

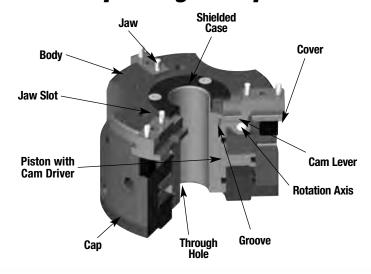
Inductive Sensing

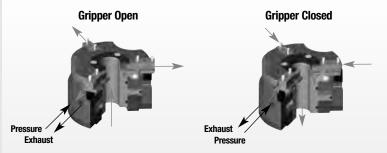
Inductive sensor kits available. Capable of sensing 4 positions

Safety Springs

Optional Springs for internal gripping (-RI) or external gripping (-RE) in single acting mode or spring assist

Operating Principle





- A double acting piston with a through hole drives the three cams.
- The piston's motion makes the cam lever rotate and moves the jaws.
- The three cams synchronize the jaw motion.
- Optional springs can be used to increase the grip force or to hold part in the event of loss of air.
- This gripper is suitable for internal or external gripping.

Style-PPC-12 & PPC-12-C



 Style:
 PPC-12

 Total Stroke:
 0.394 in.
 10 mm

 Grip Force:
 331 lb
 1474 N

 Weight:
 2.2 lb
 1.00 Kg

 Style:
 PPC-12-C

 Total Stroke:
 0.630 in.
 16 mm

 Grip Force:
 201 lb
 896 N

 Weight:
 2.4 lb
 1.10 Kg

See **1.270-1.271**

Style-PPC-25 & PPC-25-C



 Style:
 PPC-25

 Total Stroke:
 0.512 in.
 13 mm

 Grip Force:
 589 lb
 2620 N

 Weight:
 4.9 lb
 2.20 Kg

 Style:
 PPC-25-C

 Total Stroke:
 0.787 in.
 20 mm

 Grip Force:
 369 lb
 1642 N

 Weight:
 5.1 lb
 2.30 Kg

See **1.272-1.273**

Style-PPC-34 & PPC-34-C



 Style:
 PPC-34

 Total Stroke:
 0.787 in.
 20 mm

 Grip Force:
 974 lb
 4332 N

 Weight:
 11.2 lb
 5.10 Kg

 Style:
 PPC-34-C

 Total Stroke:
 1.181 in.
 30 mm

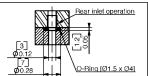
 Grip Force:
 638 lb
 2838 N

 Weight:
 11.7 lb
 5.3 Kg

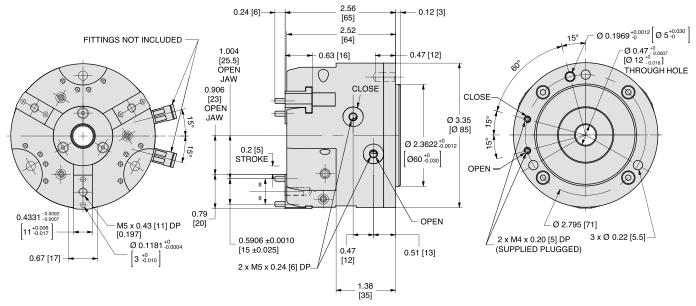
See **1.274-1.275**



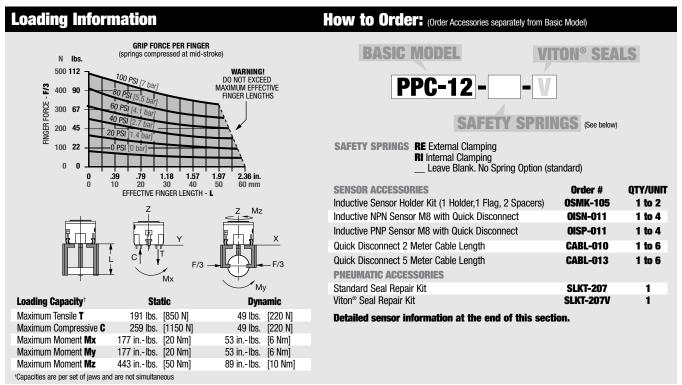
Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Specifications	PPC-1	2
Total Rated Grip Force @ 100 psi, 7 bar	331 lbs.*	1474 N*
Total Stroke	0.394 in.	10 mm
Weight	2.2 lbs.	1.0 Kg
Pressure Range without Springs		2-7 bar
Pressure Range with Springs	45-100 psi	3-7 bar
Cylinder Bore Ø	2.48 in.	63 mm
Displacement	1.40 in ³ .	23 cm ³
Temperature Range		
Standard Seals		-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	0.03 sec.	0.03 sec.
Repeatability	±0.0008 in.	±0.02 mm
*with Option RE or RI		



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Third Angle Projection Third Angle Projection All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] Metric Threads Course Pitch O.000 = ±.015 O.000 = ±.015 O.000 = ±.005 O.000 = ±.005 O.000 = ±.015 O.000 = ±.015



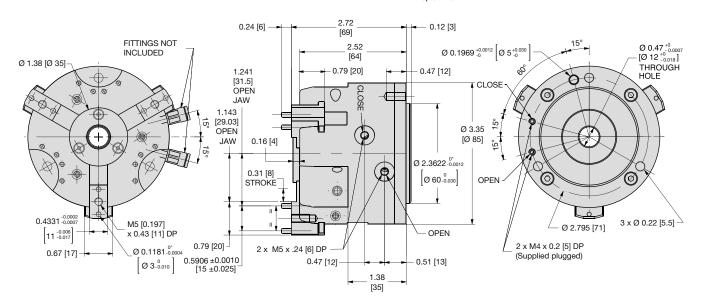


Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

Specifications Total Rated Grip Force @ 100 psi, 7 bar...... 896 N* Total Stroke 0.630 in. 16 mm 1.1 Kg Pressure Range without Springs..... 30-100 psi 2-7 bar Pressure Range with Springs..... 45-100 psi 3-7 bar Cylinder Bore Ø 2.48 in. 63 mm Displacement 1.40 in³. 23 cm³ Temperature Range Standard Seals..... -35°~80° C -30°~150° C -20°~300° F Actuation 0.03 sec. 0.03 sec. Repeatability.... ±0.0008 in. ±0.02 mm *with Option RE or RI

PARALLEL GRIPPERS PPC-12-C

THROUGH HOLE SERIES



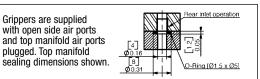
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

Loading Information How to Order: (Order Accessories separately from Basic Model) **GRIP FORCE PER FINGER BASIC MODEL EXTENDED STROKE** (springs compressed at mid-stroke) N Ibs. WARNING! 300 67 DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS 250 56 200 FINGER FORCE 150 34 SAFETY SPRINGS (See below) 100 **SAFETY SPRINGS RE** External Clamping 50 11 RI Internal Clamping Leave Blank. No Spring Option (standard) 1.97 50 .39 10 1.18 0 **SENSOR ACCESSORIES** Order # QTY/UNIT EFFECTIVE FINGER LENGTH - L Inductive Sensor Holder Kit (1 Holder,1 Flag, 2 Spacers) **OSMK-105** 1 to 2 Inductive NPN Sensor M8 with Quick Disconnect OISN-011 1 to 4 Inductive PNP Sensor M8 with Quick Disconnect 0ISP-011 1 to 4 CABL-010 Quick Disconnect 2 Meter Cable Length 1 to 6 Quick Disconnect 5 Meter Cable Length CABL-013 1 to 6 **PNEUMATIC ACCESSORIES** ✓ My Standard Seal Repair Kit **SLKT-207 Dynamic** Viton® Seal Repair Kit SLKT-207V Loading Capacity¹ Static Maximum Tensile T 214 lbs. [950 N] 49 lbs. [220 N] Detailed sensor information at the end of this section. Maximum Compressive C 281 in.-lbs. [1250 N] 49 lbs. [220 N] Maximum Moment Mx 177 in.-lbs. [20 Nm] 53 in.-lbs. [6 Nm] Maximum Moment My 177 in.-lbs. [20 Nm] 53 in.-lbs. [6 Nm] Maximum Moment Mz 531 in.-lbs. [60 Nm] 89 in.-lbs. [10 Nm] †Capacities are per set of jaws and are not simultaneous

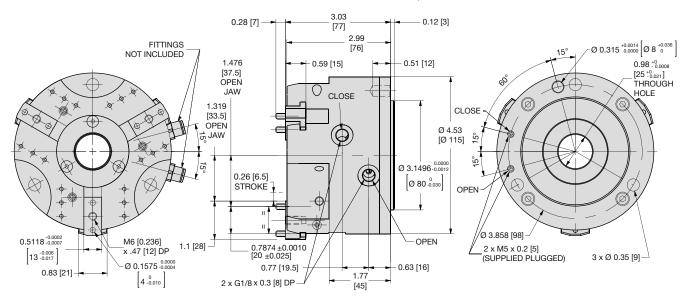
PARALLEL GRIPPERS PPC-25 THROUGH HOLE SERIES



Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold



Specifications	PPC-25			
Total Rated Grip Force @ 100 psi, 7 bar	589 lbs.*	2620 N*		
Total Stroke	0.512 in.	13 mm		
Weight	4.9 lbs.	2.2 Kg		
Pressure Range without Springs	30-100 psi	2-7 bar		
Pressure Range with Springs	45-100 psi	3-7 bar		
Cylinder Bore Ø	3.35 in.	85 mm		
Displacement	3.11 in ³ .	51 cm ³		
Temperature Range				
Standard Seals	-30°∼180° F	-35°~80° C		
Viton® Seals	-20°∼300° F	-30°~150° C		
Actuation	0.04 sec.	0.04 sec.		
Repeatability	±0.0008 in.	±0.02 mm		
*with Option RE or RI				

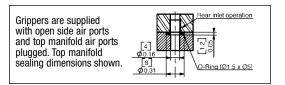


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Φ Imperial in. Metric [mm] $\Rightarrow \oplus$ $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Dimensions are symmetrical about Third Angle Metric Threads Projection Course Pitch centerline

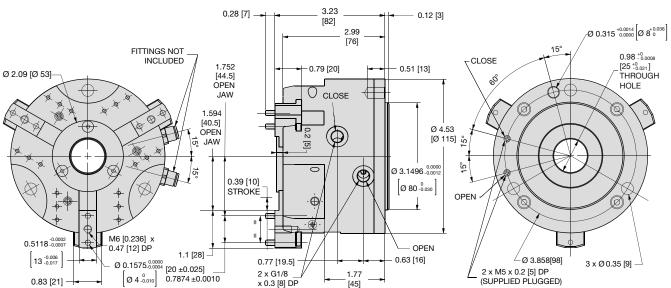
Loading Information How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER **BASIC MODEL** VITON® SEALS N Ibs. 900 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE **PPC-25** 750 169 FINGER FORCE 600 450 101 SAFETY SPRINGS (See below) 300 **SAFETY SPRINGS RE** External Clamping 150 34 RI Internal Clamping Leave Blank. No Spring Option (standard) .79 1.18 1.57 1.97 2.36 2.76 3.15 3.54 in. 20 30 40 50 60 70 80 90 mm EFFECTIVE FINGER LENGTH - **L SENSOR ACCESSORIES** Order # QTY/UNIT Inductive Sensor Holder Kit (1 Holder,1 Flag, 2 Spacers) OSMK-106 1 to 2 Inductive NPN Sensor M8 with Quick Disconnect OISN-011 1 to 4 Inductive PNP Sensor M8 with Quick Disconnect 0ISP-011 1 to 4 Quick Disconnect 2 Meter Cable Length CABL-010 1 to 6 Quick Disconnect 5 Meter Cable Length CABL-013 1 to 6 **PNEUMATIC ACCESSORIES** ∕Mγ Standard Seal Repair Kit **SLKT-208** SLKT-208V Loading Capacity¹ Static **Dynamic** Viton® Seal Repair Kit Maximum Tensile T 292 lbs. [1300 N] 88 lbs. [390 N] Detailed sensor information at the end of this section. Maximum Compressive C 337 lbs. [1500 N] 88 lbs. [390 N] Maximum Moment Mx 266 in.-lbs. [30 Nm] 115 in.-lbs. [13 Nm] Maximum Moment My 266 in.-lbs. [30 Nm] 115 in.-lbs. [13 Nm] Maximum Moment Mz 575 in.-lbs. [65 Nm] 221 in.-lbs. [25 Nm] †Capacities are per set of jaws and are not simultaneous



PARALLEL GRIPPERS PPC-25-C THROUGH HOLE SERIES



Specifications Total Rated Grip Force @ 100 psi, 7 bar...... 1642 N* Total Stroke 0.787 in. 20 mm 2.3 Kg Pressure Range without Springs...... 30-100 psi 2-7 bar Pressure Range with Springs..... 45-100 psi 3-7 bar 85 mm Displacement 3.11 in³. 51 cm³ Temperature Range Standard Seals...... -35°~80° C -30°~150° C Viton® Seals -20°~300° F Actuation 0.04 sec. 0.04 sec. Repeatability.... ±0.0008 in. ±0.02 mm *with Option RE or RI



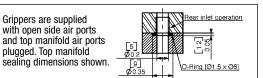
UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Third Angle Projection Locational Tolerance ±.0005" or [±.013mm] All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] Locational Tolerance Structure Threads Course Pitch Course Pitch D.000 = ±.005 0.000 = ±.005 0.000 = ±.005 0.000 = ±.013 [0.0] = [±.25]

Loading Information How to Order: (Order Accessories separately from Basic Model) **GRIP FORCE PER FINGER BASIC MODEL** (springs compressed at mid-stroke) **EXTENDED STROKE** N Ibs. 600 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS PPC-25 -500 112 FINGER FORCE . 400 300 SAFETY SPRINGS (See below) VITON® SEALS 200 **SAFETY SPRINGS RE** External Clamping 100 22 RI Internal Clamping Leave Blank. No Spring Option (standard) .79 1.18 1.57 1.97 2.36 2.76 3.15 20 30 40 50 60 70 80 EFFECTIVE FINGER LENGTH - L **SENSOR ACCESSORIES** Order # QTY/UNIT Inductive Sensor Holder Kit (1 Holder,1 Flag, 2 Spacers) OSMK-106 1 to 2 Inductive NPN Sensor M8 with Quick Disconnect OISN-011 1 to 4 Inductive PNP Sensor M8 with Quick Disconnect 0ISP-011 1 to 4 CABL-010 Quick Disconnect 2 Meter Cable Length 1 to 6 Quick Disconnect 5 Meter Cable Length CABL-013 1 to 6 **PNEUMATIC ACCESSORIES** ∕Mγ Standard Seal Repair Kit **SLKT-208** SLKT-208V Loading Capacity¹ Static **Dynamic** Viton® Seal Repair Kit Maximum Tensile T 292 lbs. [1300 N] 88 lbs. [390 N] Detailed sensor information at the end of this section. Maximum Compressive C 337 lbs. [1500 N] 88 lbs. [390 N] Maximum Moment Mx 266 in.-lbs. [30 Nm] 115 in.-lbs. [13 Nm] Maximum Moment My 266 in.-lbs. [30 Nm] 115 in.-lbs. [13 Nm] Maximum Moment Mz 620 in.-lbs. [70 Nm] 221 in.-lbs. [25 Nm] †Capacities are per set of jaws and are not simultaneous

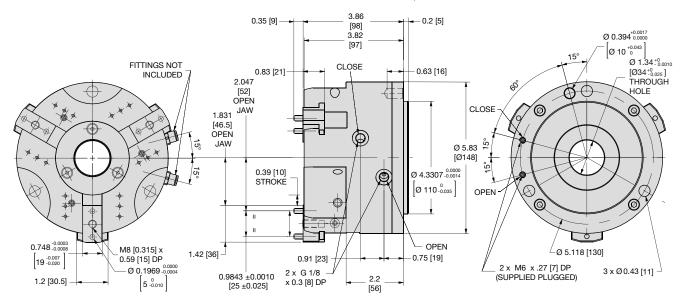


Grippers are supplied with open side air ports and top manifold air ports

plugged. Top manifold



PPC-:	34
974 lbs.*	4332 N*
0.787 in.	20 mm
11.2 lbs.	5.1 Kg
30-100 psi	2-7 bar
45-100 psi	3-7 bar
4.33 in.	110 mm
7.81 in³.	128 cm ³
-30°~180° F	-35°~80° C
-20°~300° F	-30°~150° C
0.06 sec.	0.06 sec.
±0.0008 in.	±0.02 mm
	974 lbs.* 0.787 in 11.2 lbs 30-100 psi 45-100 psi 4.33 in 7.81 in³. -30°~180° F -20°~300° F 0.06 sec.



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Ç Φ Imperial in. Metric [mm] $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Dimensions are symmetrical about Third Angle Metric Threads Projection Course Pitch centerline

Loading Information How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER **BASIC MODEL** (springs compressed at mid-stroke) **VITON® SEALS** N Ibs. WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 1500 337 **PPC-34 2** 1250 **281** FINGER LENGTHS 750 169 750 112 SAFETY SPRINGS (See below) **SAFETY SPRINGS RE** External Clamping 250 56 RI Internal Clamping Leave Blank. No Spring Option (standard) .**79** 20 3.94 100 **4.72 in.** 120 mm 2.36 60 **SENSOR ACCESSORIES** Order # QTY/UNIT EFFECTIVE FINGER LENGTH - L Inductive Sensor Holder Kit (1 Holder,1 Flag, 2 Spacers) **OSMK-107** 1 to 2 Мz Inductive NPN Sensor M8 with Quick Disconnect OISN-011 1 to 4 Inductive PNP Sensor M8 with Quick Disconnect 0ISP-011 1 to 4 Quick Disconnect 2 Meter Cable Length CABL-010 1 to 6 Quick Disconnect 5 Meter Cable Length CABL-013 1 to 6 **PNEUMATIC ACCESSORIES** ∕Mγ Standard Seal Repair Kit **SLKT-209** SLKT-209V Loading Capacity¹ Static **Dynamic** Viton® Seal Repair Kit Maximum Tensile T 438 lbs. [1950 N] 146 lbs. [650 N] Detailed sensor information at the end of this section. Maximum Compressive C 483 lbs. [2150 N] 146 lbs. [650 N] [32 Nm] Maximum Moment Mx 283 in.-lbs. 575 in.-lbs. [65 Nm] Maximum Moment My 575 in.-lbs. [65 Nm] 283 in.-lbs. [32 Nm] Maximum Moment Mz 885 in.-lbs. [100 Nm] 487 in.-lbs. [55 Nm] †Capacities are per set of jaws and are not simultaneous

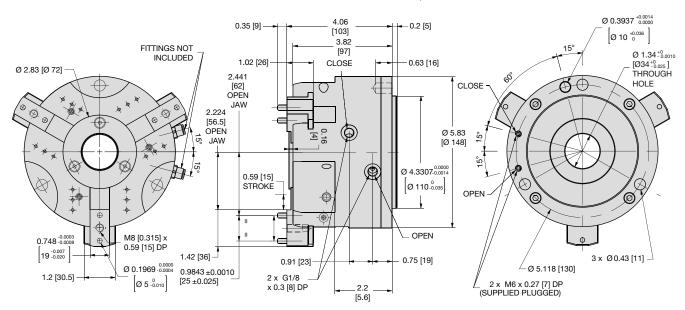


PARALLEL GRIPPERS PPC-34-C **THROUGH HOLE SERIES**

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

†Capacities are per set of jaws and are not simultaneous

Specifications Total Rated Grip Force @ 100 psi, 7 bar...... 638 lbs.* 2838 N* 30 mm Total Stroke 1.181 in. 5.3 Kg Pressure Range without Springs...... 30-100 psi 2-7 bar Pressure Range with Springs...... 45-100 psi 3-7 bar Cylinder Bore Ø 4.33 in. 110 mm 128 cm³ Temperature Range Standard Seals..... -35°~80° C -30°~150° C Viton® Seals -20°~300° F Actuation 0.06 sec. 0.06 sec. Repeatability..... ±0.0008 in. ±0.02 mm *with Option RE or RI



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW \bigoplus Imperial in. Metric [mm] $\triangleright \oplus$ $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Dimensions are symmetrical about Third Angle Metric Threads Projection Course Pitch centerline

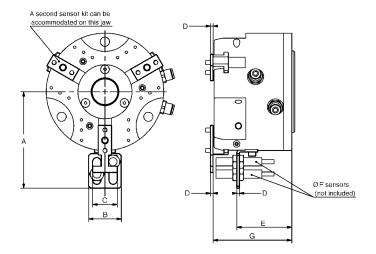
Loading Information How to Order: (Order Accessories separately from Basic Model) **GRIP FORCE PER FINGER BASIC MODEL** (springs compressed at mid-stroke) **EXTENDED STROKE** N Ibs. WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 1000 225 53 800 180 FINGER LENGTHS **FINGER FORCE** 600 135 SAFETY SPRINGS (See below) 400 200 **SAFETY SPRINGS RE** External Clamping 45 RI Internal Clamping Leave Blank. No Spring Option (standard) .**79** 20 **4.72 in.** 120 mm 2.36 100 60 **SENSOR ACCESSORIES** Order # QTY/UNIT EFFECTIVE FINGER LENGTH - L Inductive Sensor Holder Kit (1 Holder, 1 Flag, 2 Spacers) **OSMK-107** 1 to 2 Inductive NPN Sensor M8 with Quick Disconnect OISN-011 1 to 4 Inductive PNP Sensor M8 with Quick Disconnect 0ISP-011 1 to 4 Quick Disconnect 2 Meter Cable Length CABL-010 1 to 6 Quick Disconnect 5 Meter Cable Length CABL-013 1 to 6 **PNEUMATIC ACCESSORIES** ∕Mγ Standard Seal Repair Kit **SLKT-209** SLKT-209V Loading Capacity¹ Static **Dynamic** Viton® Seal Repair Kit Maximum Tensile T 438 lbs. [2150 N] 146 lbs. [650 N] Detailed sensor information at the end of this section. Maximum Compressive C 528 lbs. [2350 N] 146 lbs. [650 N] [32 Nm] Maximum Moment Mx 575 in.-lbs. [65 Nm] 283 in.-lbs. Maximum Moment My 575 in.-lbs. [65 Nm] 283 in.-lbs. [32 Nm] Maximum Moment Mz 1062 in.-lbs. [120 Nm] 487 in.-lbs. [55 Nm]

SENSOR ACCESSORIES

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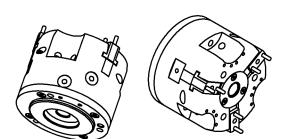
Accessory (OSMK): Inductive Sensor Holders

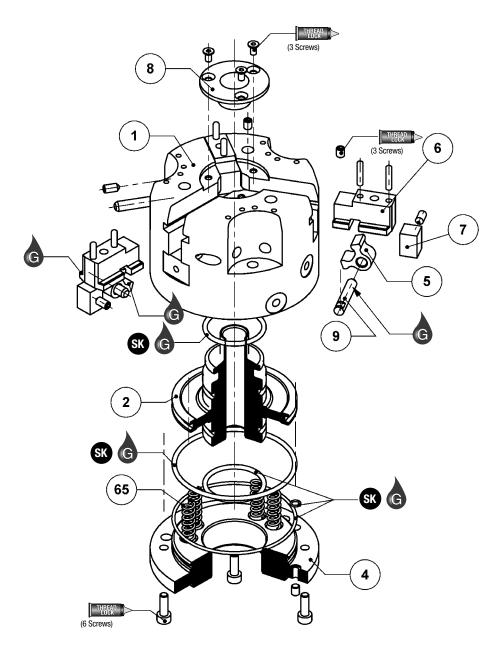
Each kit allows sensing up to 2 jaw positions: open jaws, closed jaws. or part present. Two kits can be used on each gripper allowing sensing up to 4 positions. The accessory (OSMK) comes with 1 sensor holder, 1 flag, 2 spacers and screws for mounting. The sensors are not included.



	Α	В	C	D	E	F	G
PPC-12	3.13 [79.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	1.72 [43.75]	M8	2.56 [65]
PPC-12-C	3.13 [79.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	1.72 [43.75]	M8	2.72 [69]
PPC-25	3.72 [94.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.12 [53.75]	M8	3.03 [77]
PPC-25-C	3.72 [94.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.12 [53.75]	M8	3.23 [82]
PPC-34	4.69 [119]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.84 [72.05]	M8	3.86 [98]
PPC-34-C	4.69 [119]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.84 [72.05]	M8	4.06 [103]







Item	Qty	Name
01	1	Body
02	1	Cam Driver Piston
04	1	Cap
05	3	Cam Lever
06	3	Jaw
07	3	Cover
80	1	Shielded Case
09	3	Pivot Pin

PPC Series Exploded View

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Springs

Assembly Procedure

6

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- 1) Lubricate and install the seals onto the cam driver piston
 2) Lubricate and install the seals into
- the cap
- 3) Plug rear ports in the cap if rear inlets are not used. If rear inlets are used, plug body ports.
- 4) Insert the piston into body. Place springs into counterbore holes between the body and the piston for -RE option or between the piston and the cap for -RI option
- 5) Assemble the cap
- 6) Insert together the jaw and the cam lever into the body
- 7) Insert the pivot pin aligning cam lever hole. Screw SS Screw into the body for preventing pivot pin from moving
- 8) Assemble the cover
- 9) Assemble the shielded case







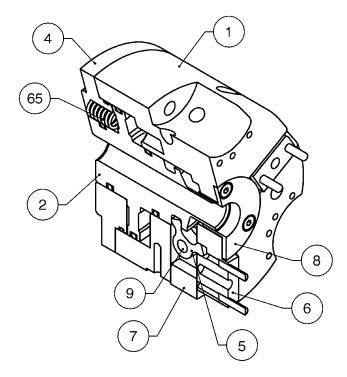








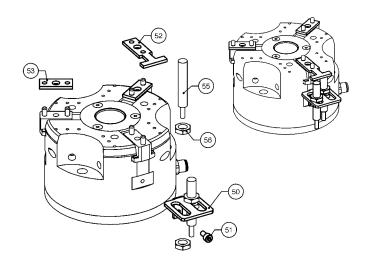




Item	Qty	Name
	_	
01	1	Body
02	1	Cam Driver Piston
04	1	Cap
05	3	Cam Lever
06	3	Jaw
07	3	Cover
80	1	Shielded Case
09	3	Pivot Pin
65	6	Springs

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation-Inductive Sensor

- 1) Assemble the sensor holder (#50) onto the gripper 2) Place the flag (#52) on one of the jaws above the sensor holder
- 3) Place the spacer (#53) on the other jaws
- 4) Position sensor for desired stroke position
- 5) Tighten sensor locking nuts (#56) to hold sensor depth 6) Repeat these operations in case of the use of two sensors holders